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Revealing hidden features of a Japanese articulated iron lobster via non-destructive local element analysis and 3D imaging

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We present a workflow to non-destructively determine the elemental compositions of internal volumes of interest enclosed within complex-shaped objects, by combining 3D X-ray or neutron imaging, prompt-gamma activation analysis, and advanced Monte Carlo computer simulations. The correction of neutron- and gamma-attenuation effects during element analysis made it possible for the first time to obtain quantitative elemental compositions for such geometries. We applied the method successfully on an articulated iron lobster artifact from Edo period Japan. Using synchrotron X-ray and neutron imaging, we revealed that it has been constructed from numerous hammered plates. Rivets and two kinds of solder were identified based on the contrasts observed in the XCT images; these were selected for local composition analysis. It was found that one soldering material consisted of Cu63Zn37 brass, while the other was a eutectic tin and lead alloy Sn39Pb61. The Zn/Cu adhesive is widely used to bond small areas, whereas Sn/Pb adhesive is used for attaching larger surfaces.

Introduction

During peaceful periods from the mid-Edo period (17th century) Japan, makers of samurai armor used their exceptional anatomic knowledge and metalwork skills to manufacture articulated animal sculptures called in Japanese *jizai okimono*. These are sophisticated standing ornaments of animals and mythological beasts made of iron, and with movable parts, limbs, joints, genuinely imitating the living creatures and served as gifts to their lords (*daimyo*) to evidence of the craftsmanship excellence of the master. In the late 19th century, bronze and silver articulated animal sculptures started to be made for export purposes. However, many details of the manufacturing process and the materials used in these elaborated metal objects are nowadays still unknown, as the knowledge was secretly passed on within the families from generation to generation.

Advanced composition and structure analysis techniques available at large-scale facilities, such as synchrotrons and neutron centres, are capable of characterizing such valuable artifacts non-destructively^{1–4}. While optical photons and X-rays can penetrate a few (hundred) μm into metals⁵, neutrons and gamma rays have an information depth up to a few mm-cm⁶, so they offer either bulk representativity in case of homogeneous samples⁷ or local concentrations relevant to an internal gauge volume for non-homogeneous objects⁸, even if this volume element is inaccessible from outside^{9,10,11,12}.

A combination of synchrotron X-ray and neutron imaging as well as the prompt-gamma activation analysis⁷, a neutron-based non-destructive element analysis technique, was selected to characterize this articulated iron lobster attributed to the famous master Myochin Munenaga (Fig. 1). The diameter of the artifact is 35 mm, while its total length is 230 mm. Like in an industrial reverse engineering exercise, we aimed at clarifying the fine details of the inner structure, visualize the structural connections, and analyze the material compositions of the object, to bridge the knowledge gap and provide evidence to re-establish these accurate metalwork techniques.

Experimental

The lobster's structure was first studied using synchrotron X-ray microtomography at BL28B2 in SPring-8, Japan¹³. It was the first-ever attempt to investigate such articulated animal sculptures using X-ray CT. Here we took advantage of the high spatial resolution and the energetic X-rays offered by the synchrotron imaging. High-energy X-rays with the peak energy of around 200 keV were extracted from a white beam using heavy metal absorbers composed of tungsten with a thickness of 500 μm and lead with a thickness of 2 mm.



Fig. 1. The photo of the articulated iron lobster under study.

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The imaging setup was equipped with a conventional microtomographic stage and a visible-light conversion type X-ray imaging detector. It consisted of a Hamamatsu Photonics C11440-36U CMOS camera (native pixel size: $5.86\mu\text{m}\times 5.86\mu\text{m}$, $1920(\text{H})\times 1200(\text{V})$ pixels), a lens system, and a $20\mu\text{m}$ thick Gadolinium ($\text{Gd}_2\text{O}_3:\text{Tb}^+$) scintillator. The effective pixel size was $17.09\mu\text{m}\times 17.09\mu\text{m}$, resulting in an effective field of view: $32.8\text{ mm}(\text{H})\times 1.5\text{ mm}(\text{V})$ at a sample-to-detector distance of 2.7 m when a magnification factor in the lens system was set to 0.33. The vertical field of view has been limited by the beam size, so 86 scans were merged to cover the whole object. During each of these CT scans, 1800 projections of 200 ms exposure times were taken over 180 degrees of rotation. The whole CT dataset was acquired for 41 500 s. The tomogram was obtained from these raw data with homemade software employing the conventional filtered back-projection method¹⁴ and the parallel beam approximation.

It became clear that the articulated iron lobster has been constructed of numerous hammered plates and those were fixed with rivets and two kinds of soldering materials that produced different contrasts in the XCT images. Based on this knowledge, the local elemental compositions of the metal body and the solder materials were determined at the NIPS-NORMA facility¹⁵ of the Budapest Neutron Centre (BNC) with position-sensitive, radiography-driven prompt-gamma activation analysis (PGAA). Being a bulk-analytical technique, even the regions of interest confined by the steel plates are amenable to composition measurement, unlike with the more common surface-probing analytical techniques, such as XRF, PIXE, LIBS, or LA-ICP-MS. Moreover, the object is covered with a brownish patina (*niiro*) that can bias the results of such analyses, while it does not influence significantly the PGAA data.

After mounting the object onto the computer-controlled xyz sample stage, dynamic neutron radiography was used as real-time visual feedback for sample positioning⁹. Four positions were selected for compositional analysis based on the contrasts observed in the XCT: an area for Solder type 1, near the limbs of the lobster (Pos 1), an area where both Solder types are assumed to be present (Pos 2), an area representing the wall material only (Pos 3), and a spot around the eyes, representing Solder type 2 (Pos 4). These positions are depicted in Fig. 2. We took PGAA spectra for 10 000–13 000 s at Pos 1, Pos 3 and Pos 4, while an overnight measurement for 56 000 s was completed at Pos 2. The obtained raw PGAA spectra are presented in Figure 3. They were processed with Hypermet-PC gamma spectroscopy program¹⁶ and ProSpeRo¹⁷ concentration calculation software.

The cross-section of the impinging neutron beam could be set with a computer-controlled neutron aperture to laterally confine the source of the analytical information.

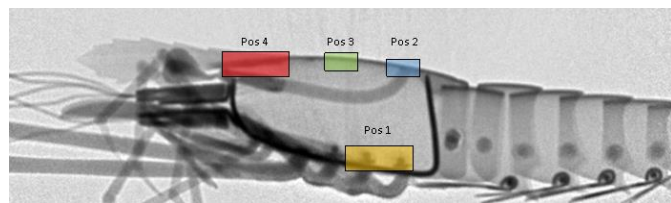


Fig. 2. Measurement positions for the position-sensitive PGAA experiment overlaid on the neutron radiogram.

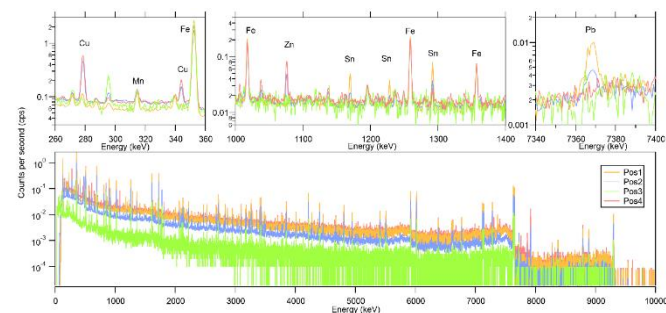


Fig. 3. The prompt-gamma spectra of the four measurement positions. Significant peaks of the elements are labeled in the insets.

As the analytical signal, i.e. the emission rate of the capture gamma-rays is proportional to the number of atoms of the element of interest present in the given infinitesimal volume and the local neutron flux.

In this chord geometry, the beam passes through the entire object towards the beam stop, and prompt-gamma photons are emitted along the beam path wherever material falls in the gauge volume. Our analytical goal is to decipher this integral information and determine the compositions of the individual materials using computer simulations and the geometry taken from the CT.

Monte Carlo simulations

The most accurate way to follow the propagation of the neutrons and gamma-rays in a given experimental geometry is the use of Monte Carlo calculations. We used the MCNP 6.2 code¹⁸ with the nuclear data library Lib80x¹⁹ (based on ENDF/B-VIII.0). We implemented the detailed geometry of the Budapest Neutron Centre's NIPS-NORMA station in the MCNP simulation environment, including the sample chamber, the shielding, and the detector. The energy distribution of the neutron beam was taken from our earlier publication²⁰.

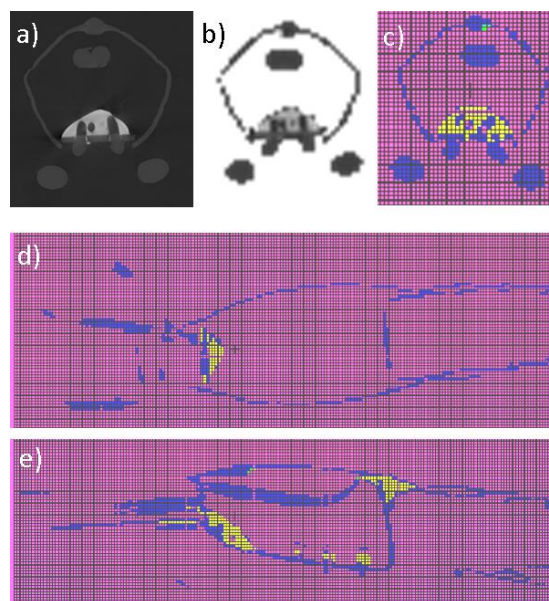


Fig. 4. The XCT slices (a) were segmented to discrete materials (b) and converted to the 3D MCNP simulation geometry, shown at cutting planes (c-e). Materials are color-coded: air (purple), metal body (blue), solder 1 (yellow) and solder 2 (green).

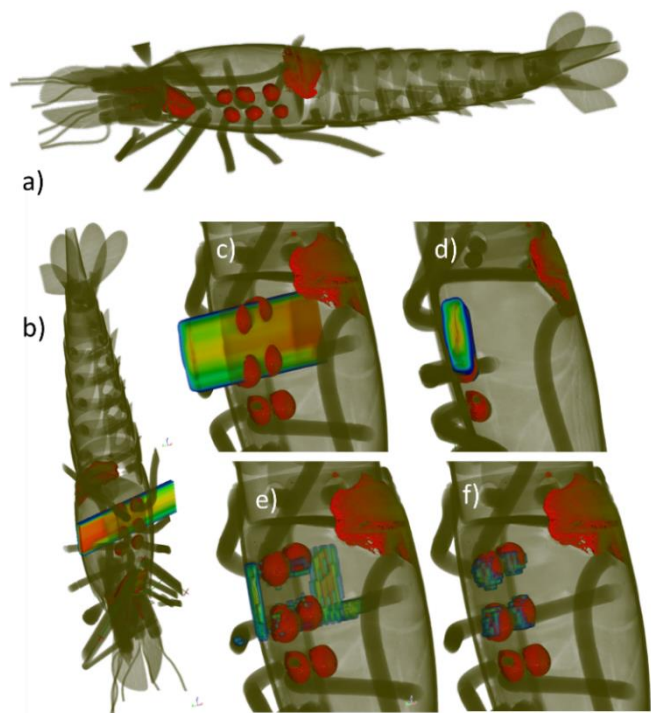


Fig. 5. The semi-transparent rendering of the lobster's structure, where the segmented soldering materials, identified by the XCT grayscale range, are shown in red (a). The Monte Carlo-calculated neutron beam intensity (b-d), as well as the emission maps of Fe (wall) (e) and Sn (solder) (f) for measurement position 1, are overlaid. Additional images are available in the Electronic Supplementary Information.

The MCNP calculation procedure has been recently validated for flat layered metal samples²¹. Here we further developed this approach to handle irregularly shaped and non-homogeneous objects via voxelization. The detailed geometry of the object was taken from segmented synchrotron CT data (Fig 4. a), where the distinct materials of the object were identified based on grayscale ranges (Fig 4. b). The material distribution was converted to a simulation geometry using a purpose-made utility²². The regular mesh of $66 \times 102 \times 278$ voxels had unit voxel sizes of $0.5 \times 0.5 \times 0.5 \text{ mm}^3$ and was filled with four kinds of materials: air (purple), metal body (blue), solder 1 (yellow), and solder 2 (green), as illustrated in Fig. 4 c-e). The material compositions were defined based on the raw PGAA concentration data.

The neutron intensity maps and the neutron capture rate maps for all relevant elements and all four measurement positions were simulated with a spatial resolution of 0.25 mm as a 3D superimposed mesh grid. The neutron capture rate map, normalized to the case of the undisturbed neutron beam, gave an integral quantity relevant to the neutron-related matrix-effect of the given element (self-shielding). In the second step of the simulation, these neutron capture rates of the elements were converted to emission maps of prompt-gamma rays, and the attenuation of the gamma-rays in the given measurement geometry towards the detector (self-absorption) was assessed²². The MCNP neutron simulations took 2 hours per irradiation position using 20 threads of an Intel i9-7940X 3.1 GHz workstation, while the corresponding gamma simulations lasted for 3 hours, for each relevant element in each of the four measurement positions.

Results and Discussion

Based on the XCT data, the metal body and two kinds of soldering materials could be visually differentiated. The full 3D rendering of the solder materials in red is shown in Figure 5. The voxelized results of the Monte Carlo simulations are presented here with intensity heat maps. Note that the neutron beam passes through the entire object, and more than one structural component may emit gamma rays from a single gauge volume. The emission maps of elements Fe (the main constituent of the metal body) and Sn (solder component) are plotted in Figures 5 e) and f), while further plots are available as Electronic Supplementary Information. Using these simulations, we achieved for the first time quantitative matrix-effect correction for such a non-homogeneous and complex-shaped object, which was a prerequisite to an unbiased local, but also in-depth element analysis by PGAA.

In PGAA spectra, most elements have several analytical lines at different energies, so there is an inherent way to verify the consistency of the calculations. In the ProSpeRo software¹⁷, we obtain the masses of the elements based on the weighted averages of up to 25 analytical lines per element. The element-dependent correction factors for neutron self-shielding and gamma self-absorption obtained from the Monte Carlo calculations were introduced to replace the default correction method applicable only to homogeneous slab geometry. As a result of the improved corrections, self-consistent element masses could be derived from multiple analytical lines, even in such complex experimental geometry. This is evidenced by Fig. 6, where the masses of iron are plotted as a function of the gamma-energy of the analytical peaks.

Consistency was not only achieved within one PGAA spectrum (i.e. the mass of an element calculated from its low- and high-energy peaks agreed, see the blue data points in Fig. 6) but also between the several measurement positions (the compositions of the metal body and two kinds of solder materials obtained from different spectra also agreed, see Table 1). If we assume that two or three distinct materials are present in the gauge volume in different combinations, one can deduce the compositions of the body and the two solder types as listed in Table 1.

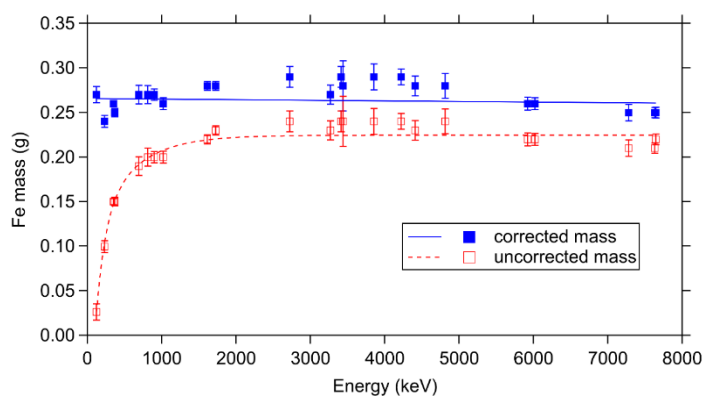


Fig. 6. The corrected and uncorrected masses of the element iron in Pos 4, as calculated from analytical lines at different prompt-gamma energies.

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Element	Pos 1		Pos 2		Pos 3		Pos 4	
	Lobster base metal + Solder 1		Lobster base metal + Solder 1 + Solder 2		Lobster base metal only		Lobster base metal + Solder 2	
	m/m%	rel. unc	m/m%	rel. unc	m/m%	rel. unc	m/m%	rel. unc
Mn	0.37	3.0	0.45	2.9	0.42	3.0	0.47	6.
Fe	99.63	0.03	99.55	0.03	99.58	0.03	99.53	0.03
Cu			61	1.3			63	1.2
Zn			39	2.0			37	2.1
Sn	27	4.	27	6.				
Pb	73	1.6	73	2.1				

Table 1. Element mass fractions and 1-sigma relative uncertainties of the metal body and the two soldering materials, as determined at the four measurement positions.

It was found that the lobster was made of 99.6% Fe with a 0.4% Mn impurity. Two soldering materials were identified: one is consisted of Cu63Zn37 brass, while the other is eutectic tin and lead alloy Sn39Pb61. Zn/Cu adhesive is widely used to bond small areas, whereas Sn/Pb adhesive is used for attaching larger surfaces.

Conclusions

We successfully characterized for the first time the internal structure and the material composition of a Japanese articulated metal lobster. This was made possible by using synchrotron X-ray tomography, neutron radiography experiments for geometry characterization, and position-sensitive prompt-gamma activation analysis, supported by advanced Monte Carlo calculations, for elemental composition measurements.

The joint consideration of position-sensitive PGAA element analysis and imaging data allows a more reliable explanation of the so far independently treated results. Moreover, the quantitative matrix-effect correction we developed in the course of this work made it possible to obtain consistent elemental concentrations within each spectrum, and also over the several measurement spots, even if the regions of interest are not accessible from outside, i.e. not amenable to the more conventional surface-confined analytical techniques.

Using these data, we concluded that the body of the lobster is pure iron with 0.4% Mn impurity, whereas two soldering materials, Cu63Zn37 brass, and eutectic Sn39Pb61 alloy were identified. The outcome of this reverse engineering study paves the way to re-establish the lost skills of the late Japanese masters, while, on the other hand, the developed analytical methodology will be applicable well beyond the scope of the current study.

Author Contributions

László Szentmiklósi – Conceptualization, Investigation, Methodology, Supervision, Funding acquisition, Visualization, Writing – original draft

Zoltán Kis – Investigation, Methodology, Software, Data curation, Writing – review & editing

Manako Tanaka – Conceptualization, Investigation, Supervision, Funding acquisition, Writing – review & editing

Boglárka Maróti – Investigation, Formal Analysis, Validation, Writing – review & editing

Masato Hoshino – Investigation, Methodology, Data curation, Formal analysis, Writing – review & editing

Katalin Bajnok – Project administration, Writing – review & editing

Conflicts of interest

There are no conflicts to declare.

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