

A SPECIAL NONLINEAR CONNECTION IN SECOND ORDER GEOMETRY

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ABSTRACT. We show that, for mechanical system with external forces, the equations of deviations of solution curves of the corresponding Lagrange equations, determine a nonlinear connection on the second order tangent bundle. In particular, Jacobi equations in Finsler and Riemann spaces determine such a nonlinear connection.

1. INTRODUCTION

As shown in [27], nonlinear connections on bundles can be a powerful tool in integrating systems of differential equations. A way of obtaining them is that of deriving them from the respective systems of DE's, in particular, from variational principles, [2], [16], [15]. For instance, an ODE system of order 2 on a manifold M induces a nonlinear connection on its tangent bundle TM . A remarkable example is here the Cartan nonlinear connection of a Finsler space, which has the property that its autoparallel curves correspond to geodesics of the base manifold:

$$\frac{\delta y^i}{dt} := \frac{dy^i}{dt} + N^i_j y^j = 0.$$

Further, an ODE system of order three determines a nonlinear connection on the second order tangent (jet) bundle $T^2M = J_0^2(\mathbb{R}, M)$. For instance, Craig-Synge equations (R. Miron, [16])

$$\frac{d^3 x^i}{dt^3} + 3!G^i(x, \dot{x}, \ddot{x}) = 0,$$

lead to:

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a) Miron's connection:

$$(1) \quad M_{(1)j}^i = \frac{\partial G^i}{\partial y^{(2)j}}, \quad M_{(2)j}^i = \frac{1}{2} \left(SM_{(1)j}^i + M_{(1)m}^i M_{(1)j}^m \right),$$

where $S = y^i \frac{\partial}{\partial x^i} + 2y^{(2)i} \frac{\partial}{\partial y^i} - 3G^i \frac{\partial}{\partial y^{(2)i}}$ is a semispray on T^2M .

b) Bucătaru's connection

$$M_{(1)j}^i = \frac{\partial G^i}{\partial y^{(2)j}}, \quad M_{(2)j}^i = \frac{\partial G^i}{\partial y^j}.$$

With respect to the last one, if G^i are the coefficients of a spray on T^2M (i.e., 3-homogeneous functions), then the Craig-Synge equations can be interpreted as:

$$(2) \quad \frac{\delta y^{(2)i}}{dt} = 0,$$

where $\frac{\delta y^{(2)i}}{dt} := \frac{dy^{(2)i}}{dt} + M_{(1)j}^i \frac{dy^j}{dt} + M_{(2)j}^i \frac{dx^j}{dt}$.

In Miron's and Bucătaru's approaches, nonlinear connections on T^2M are obtained from a Lagrangian of order 2, $L(x, \dot{x}, \ddot{x})$, by computing the first variation of its integral of action.

Here, we propose a different approach, which, we consider, could be at least as interesting as the above one from the point of view of Mechanics - namely, we start with a first order Lagrangian $L(x, \dot{x})$ and compute its second variation.

This way, for a mechanical system $(M, L(x, \dot{x}), F(x, \dot{x}))$ with external force field F , we obtain a nonlinear connection on T^2M , with respect to which the equations of deviations of evolution curves have a simple invariant form.

As a remark, our nonlinear connection is also suitable for modelling the solutions of a (globally defined) ODE system, not necessarily attached to a certain Lagrangian, together with the deviations of these solutions.

More precisely, in the following our aims are:

(1) to obtain the Jacobi equations for the trajectories

$$\frac{\delta y^i}{dt} = \frac{1}{2} F^i(x, y)$$

(for extremal curves of a 2-homogeneous Lagrangian $L(x, \dot{x})$ in presence of external forces).

(2) to build a nonlinear connection such that:

$$w \in \mathcal{X}(M) \text{ Jacobi field along } c \Leftrightarrow \frac{\delta w^{(2)i}}{dt} = 0,$$

where $\frac{d}{dt}$ denotes directional derivative with respect to \dot{c} and

$$\frac{\delta w^{(2)i}}{dt} = \frac{1}{2} \frac{d^2 w^i}{dt^2} + M_{(1)j}^i \frac{dw^j}{dt} + M_{(2)j}^i w^j.$$

For $F = 0$, this nonlinear connection has as additional properties:

I. In Finsler spaces M , c is a geodesic of M if and only if its extension T^2M is horizontal.

II. A vector field w along a geodesic c on M is parallel along c if and only if $\frac{\delta w^i}{dt} = 0$.

Throughout the paper, by ‘differentiable’ or ‘smooth’ we mean C^∞ -differentiable.

2. TANGENT BUNDLE OF FIRST AND SECOND ORDER

Let M be a real differentiable manifold of dimension n and class C^∞ ; the coordinates of a point $x \in M$ in a local chart (U, ϕ) will be denoted by $\phi(x) = (x^i)$, $i = 1, \dots, n$. Let (TM, π, M) be its tangent bundle and (x^i, y^i) the coordinates of a point in a local chart.

The *2-tangent bundle* (T^2M, π^2, M) is the space of jets of order two at 0 of all smooth functions $f: (-\varepsilon, \varepsilon) \rightarrow M$, $t \mapsto (f^i(t))$, on $(-\varepsilon, \varepsilon)$, $\varepsilon > 0$, ([19]-[24], [16], [10]).

In a local chart, a point p of T^2M will have the coordinates $(x^i, y^i, y^{(2)i})$. This is,

$$x^i = f^i(0), \quad y^i = \dot{f}^i(0), \quad y^{(2)i} = \frac{1}{2} \ddot{f}^i(0), \quad i = 1, \dots, n,$$

for some f as above. Then, (T^2M, π^2, M) is a differentiable manifold of class C^∞ and dimension $3n$, and TM can be identified with a submanifold of T^2M . The local coordinate changes induced by local coordinate changes on M are, [16], [19]-[24],

$$(3) \quad \begin{aligned} \tilde{x}^i &= \tilde{x}^i(x^1, \dots, x^n), \quad \det \left(\frac{\partial \tilde{x}^i}{\partial x^j} \right) \neq 0 \\ \tilde{y}^i &= \frac{\partial \tilde{x}^i}{\partial x^j} y^j \\ 2\tilde{y}^{(2)i} &= \frac{\partial \tilde{y}^i}{\partial x^j} y^j + 2 \frac{\partial \tilde{y}^i}{\partial y^j} y^{(2)j}. \end{aligned}$$

For a curve $c: [0, 1] \rightarrow M$, $t \mapsto (x^i(t))$ on the base manifold M , let us denote:

- by \hat{c} its *extension* to the tangent bundle TM :

$$\hat{c}: [0, 1] \rightarrow M, t \mapsto (x^i(t), \dot{x}^i(t));$$

along \widehat{c} , there holds:

$$y^i = \dot{x}^i(t), \quad i = 1, \dots, n;$$

- by \widetilde{c} its *extension to T^2M* :

$$\widetilde{c}: [0, 1] \rightarrow T^2M, \quad t \mapsto (x^i(t), \dot{x}^i(t), \frac{1}{2}\ddot{x}^i(t));$$

along such an extension curve, there holds

$$y^i(t) = \dot{x}^i(t), \quad y^{(2)i}(t) = \frac{1}{2}\ddot{x}^i(t), \quad i = 1, \dots, n.$$

A tensor field on TM (or T^2M) is called a *distinguished tensor field*, or simply, a *d-tensor field* if, under a change of local coordinates induced by a change of coordinates on the base manifold M , its components transform by the same rule as the components of a corresponding tensor field on M , [16].

3. NONLINEAR CONNECTIONS ON TM

Let (TM, π, M) be the tangent bundle of a differentiable manifold M as above and (x^i, y^i) the coordinates of a point $p \in TM$ in a local chart. For simplicity, we shall also denote $(x, y) = (x^i, y^i)_{i=1, \dots, n}$.

Let $d\pi: T(TM) \rightarrow TM$ denote the tangent linear mapping of the projection $\pi: TM \rightarrow M$ and $V(TM) = \ker d\pi$, the *vertical subbundle* of $T(TM)$. Its fibres generate the *vertical distribution* V on TM of local dimension n , $V: p \in TM \mapsto V(p) \subset T_p(TM)$, locally spanned by $\{\frac{\partial}{\partial y^i}\}$.

A *nonlinear (Ehresmann) connection on TM* , [16], [18], is a distribution $N: p \in TM \mapsto N(p) \subset T_p(TM)$, which is supplementary to the vertical distribution:

$$(4) \quad T_p(TM) = N(p) \oplus V(p), \quad \forall p \in TM.$$

Let

$$B = \left\{ \frac{\delta}{\delta x^i}, \frac{\partial}{\partial y^i} \right\},$$

where:

$$(5) \quad \frac{\delta}{\delta x^i} = \frac{\partial}{\partial x^i} - N^j_i \frac{\partial}{\partial y^j}, \quad i = 1, \dots, n,$$

denote a local adapted basis to the direct decomposition (4). The quantities $N^j_i = N^j_i(x, y)$, [16], [18], are called the *coefficients* of the nonlinear connection N .

With respect to local coordinate changes on TM induced by changes of local coordinates $(x^i) \mapsto (\widetilde{x}^i)$ on the base manifold M , $\frac{\delta}{\delta x^i}$ transform by the rule:

$$\frac{\delta}{\delta x^i} = \frac{\partial \widetilde{x}^j}{\partial x^i} \frac{\delta}{\delta \widetilde{x}^j}.$$

The dual basis of B is $B^* = \{dx^i, \delta y^i\}$, given by

$$(6) \quad \delta y^i = dy^i + N^i_j dx^j.$$

With respect to changes of local coordinates on TM induced by local coordinate changes on M , there holds: $\delta \tilde{y}^i = \frac{\partial \tilde{x}^i}{\partial x^j} \delta y^j$.

Any vector field $X \in \mathcal{X}(TM)$ is represented in the local adapted basis as

$$(7) \quad X = X^{(0)i} \frac{\delta}{\delta x^i} + X^{(1)i} \frac{\partial}{\partial y^i},$$

where the components $X^{(0)i} \frac{\delta}{\delta x^i}$ and $X^{(1)i} \frac{\partial}{\partial y^i}$ are d-vector fields.

Similarly, a 1-form $\omega \in \mathcal{X}^*(TM)$ will be decomposed as the sum of two d-1-forms:

$$(8) \quad \omega = \omega_i^{(0)} dx^i + \omega_i^{(1)} \delta y^i.$$

In particular, if $\hat{c}: t \rightarrow (x^i(t), y^i(t))$ is an extension curve to TM , then its tangent vector field is expressed in the adapted basis as

$$(9) \quad \dot{\hat{c}} = \frac{dx^i}{dt} \frac{\delta}{\delta x^i} + \frac{\delta y^i}{dt} \frac{\partial}{\partial y^i}.$$

In our further considerations, an important role will be played by the notions of *semispray* and *spray*, [25], [10]. A semispray $S \in \mathcal{X}(TM)$ is a vector field locally described in the natural basis by $S = y^i \frac{\partial}{\partial x^i} - 2G^i(x, y) \frac{\partial}{\partial y^i}$, where the functions G^i (called the *coefficients* of the semispray) obey, with respect to coordinate changes induced by a change of local coordinates $(x^i) \mapsto (\tilde{x}^i)$ on M , the rule: $2\tilde{G}^i = 2 \frac{\partial \tilde{x}^i}{\partial x^j} G^j - \frac{\partial \tilde{y}^i}{\partial x^j} y^j$, $i = 1, \dots, n$. If G^i are 2-homogeneous functions in y , then the semispray is called a *spray*.

As shown by Grifone, [12], a semispray (in particular, a spray) on M determines a nonlinear connection on TM .

Also, evolution curves of mechanical systems with external forces, can be described in terms of semisprays on TM , (R. Miron, [15]):

Proposition 1. *Let $L = L(x, \dot{x})$ be a nondegenerate Lagrangian:*

$$\det \left(\frac{\partial^2 L}{\partial y^i \partial y^j} \right) \neq 0,$$

and $g_{ij} = \frac{1}{2} \frac{\partial^2 L}{\partial y^i \partial y^j}$, the induced (Lagrange) metric tensor. Then, the equations of evolution of a mechanical system with the Lagrangian L and the external force field $F = F_i(x, \dot{x}) dx^i$ are

$$(10) \quad \frac{d^2 x^i}{dt^2} + 2G^i(x, \dot{x}) = \frac{1}{2} F^i(x, \dot{x}),$$

where

$$2G^i = \frac{1}{2}g^{is} \left(\frac{\partial^2 L}{\partial y^s \partial x^j} y^j - \frac{\partial L}{\partial x^s} \right),$$

yield a semispray (called the canonical semispray of the Lagrange space (M, L)) and $F^i = g^{ij} F_j$, $i = 1, \dots, n$.

In the following, we shall use the above results in the case when G is a spray; this is, we shall have

$$2G^i = \frac{\partial G^i}{\partial y^j} y^j.$$

Then, [12], [2], [5], [18], the quantities

$$N^i_j = \frac{\partial G^i}{\partial y^j}$$

are the coefficients of a nonlinear connection on TM . Moreover, $N^i_j = N^i_j(x, y)$ are 1-homogeneous in y .

With respect to the above nonlinear connection, equations (10) take the form:

$$(11) \quad \frac{\delta y^i}{dt} = \frac{1}{2} F^i, \quad i = 1, \dots, n.$$

In particular, if there are no external forces, this is, if $F^i = 0$, then the extremal curves $t \mapsto x^i(t)$ of the Lagrangian L have horizontal extensions and vice-versa: horizontal extension curves \hat{c} project onto solution curves of the Euler-Lagrange equations of L .

4. NONLINEAR CONNECTIONS ON T^2M

Let $d\pi^2: T(T^2M) \rightarrow TM$ denote the tangent linear mapping of the projection $\pi^2: T^2M \rightarrow M$ and $V(T^2M) = \ker d\pi^2$, the vertical subbundle of $T(T^2M)$. Its fibres generate the *vertical distribution* V on T^2M of local dimension $2n$, $V: p \in T^2M \mapsto V(p) \subset T_p(T^2M)$, locally spanned by $\left\{ \frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^{(2)i}} \right\}$.

In the same way, if the projection $\pi_1^2: T^2M \rightarrow TM$ is given by

$$(x^i, y^i, y^{(2)i}) \mapsto (x^i, y^i),$$

then $V_2 := \ker d\pi_1^2$ generates a distribution $V_2: p \in T^2M \mapsto V_2(p) \subset T_p(T^2M)$ of local dimension n , locally spanned by $\left\{ \frac{\partial}{\partial y^{(2)i}} \right\}$.

Then, at any $p \in T^2M$, there exists a chain of vector spaces

$$V_2(p) \subset V(p) \subset T_p(T^2M).$$

Let us consider the $\mathcal{F}(T^2M)$ -linear mapping $J: \mathcal{X}(T^2M) \rightarrow \mathcal{X}(T^2M)$,

$$(12) \quad J\left(\frac{\partial}{\partial x^i}\right) = \frac{\partial}{\partial y^i}, \quad J\left(\frac{\partial}{\partial y^i}\right) = \frac{\partial}{\partial y^{(2)i}}, \quad J\left(\frac{\partial}{\partial y^{(2)i}}\right) = 0,$$

called the *2-tangent structure* on T^2M . J is globally defined on T^2M and $\text{Im } J = V$, $\text{Ker } J = V_2$, $J(V) = V_2$.

A *nonlinear connection* on T^2M , [16], is a distribution on T^2M , $N: p \in T^2M \rightarrow N(p) \subset T_p(T^2M)$, such that

$$(13) \quad T_p(T^2M) = N_0(p) \oplus V(p), \quad \forall p \in T^2M.$$

By setting $N_1(p) := J(N_0(p))$, $\forall p \in T^2M$, we get:

- the *horizontal distribution* $N_0: p \mapsto N(p)$;
- the *v_1 -distribution* $N_1: p \mapsto N_1(p)$;
- the *v_2 -distribution* $V_2: p \mapsto V_2(p)$, and there holds

$$T_p(T^2M) = N_0(p) \oplus N_1(p) \oplus V_2(p), \quad \forall p \in T^2M.$$

We denote by $h = v_0$, v_1 and v_2 the projectors corresponding to the above distributions.

Let \mathcal{B} denote a local adapted basis to the decomposition (13):

$$\mathcal{B} = \left\{ \delta_{(0)i} := \frac{\delta}{\delta x^i}, \quad \delta_{(1)i} := \frac{\delta}{\delta y^i}, \quad \delta_{(2)i} := \frac{\delta}{\delta y^{(2)i}} \right\},$$

this is, $N_0 = \text{Span}(\delta_{(0)i})$, $N_1 = \text{Span}(\delta_{(1)i})$, $V_2 = \text{Span}(\delta_{(2)i})$. The elements of the adapted basis are locally expressed as

$$(14) \quad \begin{aligned} \delta_{(0)i} &= \frac{\delta}{\delta x^i} = \frac{\partial}{\partial x^i} - \frac{N^j}{(1)^i} \frac{\partial}{\partial y^j} - \frac{N^j}{(2)^i} \frac{\partial}{\partial y^{(2)j}} \\ \delta_{(1)i} &= \frac{\delta}{\delta y^i} = \frac{\partial}{\partial y^i} - \frac{N^j}{(1)^i} \frac{\partial}{\partial y^{(2)j}} \\ \delta_{(2)i} &= \frac{\delta}{\delta y^{(2)i}} = \frac{\partial}{\partial y^{(2)i}}. \end{aligned}$$

With respect to changes of local coordinates on T^2M , induced by changes $(x^i) \mapsto (\tilde{x}^i)$ of local coordinates on the base manifold M , for $\delta_{(\alpha)i}$, $\alpha = 0, 1, 2$, there

holds: $\delta_{(\alpha)i} = \frac{\partial \tilde{x}^j}{\partial x^i} \tilde{\delta}_{(\alpha)j}$.

The dual basis of \mathcal{B} is $\mathcal{B}^* = \{dx^i, \delta y^i, \delta y^{(2)i}\}$, given by

$$(15) \quad \begin{aligned} \delta y^{(0)i} &= dx^i, \\ \delta y^i &= dy^i + M_{(1)j}^i dx^j, \\ \delta y^{(2)i} &= dy^{(2)i} + M_{(1)j}^i dy^j + M_{(2)j}^i dx^j. \end{aligned}$$

The above $\delta y^{(\alpha)i}$, $\alpha = 0, 1, 2$, $i = 1, \dots, n$, are d-1-forms on T^2M .

The quantities $N_{(1)j}^i$, $N_{(2)j}^i$ are called the *coefficients* of the nonlinear connection N , while $M_{(1)j}^i$ and $M_{(2)j}^i$ are called its *dual coefficients*. The link between the two

sets of coefficients is, [16]:

$$(16) \quad M_{(1)j}^i = N_{(1)j}^i, \quad \widetilde{M}_{(2)j}^i = N_{(2)j}^i + N_{(1)f}^i N_{(1)j}^f.$$

In the following, the next result will be very useful to us:

Theorem 2 ([16],[19]-[24]). *1. A transformation of coordinates (3) on the differentiable manifold T^2M implies the following transformation of the dual coefficients of a nonlinear connection*

$$(17) \quad \begin{aligned} \frac{\partial \widetilde{x}^i}{\partial x^k} M_{(1)j}^k &= \widetilde{M}_{(1)k}^i \frac{\partial \widetilde{x}^k}{\partial x^j} + \frac{\partial \widetilde{y}^i}{\partial x^j} \\ \frac{\partial \widetilde{x}^i}{\partial x^k} M_{(2)j}^k &= \widetilde{M}_{(2)k}^i \frac{\partial \widetilde{x}^k}{\partial x^j} + \widetilde{M}_{(1)k}^i \frac{\partial \widetilde{y}^k}{\partial x^j} + \frac{\partial \widetilde{y}^{(2)i}}{\partial x^j}. \end{aligned}$$

2. If on each domain of local chart on T^2M it is given a set of functions $\left(M_{(1)j}^i, M_{(2)j}^i \right)$, such that, with respect to (3), there hold the equalities (17), then there exists on T^2M a unique nonlinear connection N which has as dual coefficients the given set of functions.

In presence of a nonlinear connection, a vector field $X \in \mathcal{X}(T^2M)$ is represented in the local adapted basis as

$$(18) \quad X = X^{(0)i} \delta_{(0)i} + X^{(1)i} \delta_{(1)i} + X^{(2)i} \delta_{(2)i},$$

with the three right terms (which are d-vector fields) belonging to the distributions N , N_1 and V_2 respectively.

A 1-form $\omega \in \mathcal{X}^*(T^2M)$ will be decomposed as

$$(19) \quad \omega = \omega_i^{(0)} dx^i + \omega_i^{(1)} \delta y^i + \omega_i^{(2)} \delta y^{(2)i}.$$

Similarly, a tensor field $T \in \mathcal{T}_s^r(T^2M)$ can be split with respect to (13) into components, which are d-tensor fields.

In particular, if $\tilde{c}: t \rightarrow (x^i(t), y^i(t), y^{(2)i}(t))$ is an extension curve, then its tangent vector field is expressed in the adapted basis as

$$(20) \quad \dot{\tilde{c}} = \frac{dx^i}{dt} \delta_{(0)i} + \frac{\delta y^i}{dt} \delta_{(1)i} + \frac{\delta y^{(2)i}}{dt} \delta_{(2)i}.$$

Our goal is to give a precise meaning to the equality $v_2(\dot{\tilde{c}}) = 0$.

5. BERWALD LINEAR CONNECTION ON T^2M

Let $G^i = G^i(x, y)$ be the coefficients of a spray on TM , and

$$N^i_j(x, y) = \frac{\partial G^i}{\partial y^j},$$

the coefficients of the induced nonlinear connection (on TM).

Let also

$$L^i_{jk}(x, y) = \frac{\partial N^i_j}{\partial y^k} = \frac{\partial^2 G^i}{\partial y^j \partial y^k},$$

the local coefficients of the induced Berwald linear connection on TM , [16].

Now, let on T^2M , a linear connection defined by $N^i_{(1)j} = N^i_j(x, y^{(1)})$ as above, and arbitrary $N^i_{(2)j} = N^i_j(x, y, y^{(2)})$. The *Berwald connection* on T^2M , [8], is the linear connection defined by

$$(21) \quad \begin{aligned} D_{\delta_{(0)k}} \delta_{(\alpha)j} &= L^i_{jk} \delta_{(\alpha)i}, \\ D_{\delta_{(\beta)k}} \delta_{(\alpha)j} &= 0, \quad \beta = 1, 2, \quad \alpha = 0, 1, 2. \end{aligned}$$

This is, with the notations in [16], the coefficients of the Berwald linear connection are $B\Gamma(N) = (L^i_{jk}, 0, 0)$.

For extensions \tilde{c} to T^2M of curves $c: [0,1] \rightarrow M$, we can express the v_1 component of the tangent vector field \tilde{c} , given by $\frac{\delta y^i}{dt}$ (the *geometric acceleration*, [13]) by means of the Berwald covariant derivative:

$$(22) \quad \frac{Dy^i}{dt} := D_{\tilde{c}} y^i = \frac{\delta y^i}{dt}, \quad i = 1, \dots, n.$$

Let \mathbb{T} denote its torsion tensor, and:

$$R^i_{jk} = v_1 \mathbb{T}(\delta_{(0)k}, \delta_{(0)j}) = \delta_{(0)k} N^i_j - \delta_{(0)j} N^i_k,$$

its $v_1(h, h)$ components.

Also, let \mathbb{R} be the curvature tensor; then

$$\begin{aligned} R^i_{jkl} &= \delta_{(0)l} L^i_{jk} - \delta_{(0)k} L^i_{jl} + L^m_{jk} L^i_{ml} - L^m_{jl} L^i_{mk}, \\ P_j^i{}_{kl} &= \delta_{(1)l} L^i_{jk} = \frac{\partial^3 G^i}{\partial y^j \partial y^k \partial y^l}, \end{aligned}$$

where $R^i_{jkl} \delta_{(0)i} = h\mathbb{R}(\delta_{(0)l}, \delta_{(0)k})$, $P_j^i{}_{kl} \delta_{(0)i} = h\mathbb{R}(\delta_{(1)l}, \delta_{(0)k})$, define its only nonvanishing local components, [16].

Taking into account that L^i_{jk} do not depend on $y^{(2)}$ and that $G^i = G^i(x, y)$ are 2-homogeneous in y , it follows:

$$(23) \quad y^j R^i_{jkl} = R^i_{kl}.$$

From the 2-homogeneity of G^i , we also have

$$(24) \quad P_j^i{}_{kl} y^l = \frac{\partial^3 G^i}{\partial y^j \partial y^k \partial y^l} y^l = 0; \quad P_j^i{}_{kl} y^j = P_j^i{}_{kl} y^k = 0.$$

6. JACOBI EQUATIONS FOR SYSTEMS WITH EXTERNAL FORCES

Let us suppose that we know *a priori* a nonlinear connection on the first order tangent bundle TM , with (1-homogeneous) coefficients $N^i_j(x, y) = \frac{\partial G^i}{\partial y^j}$, coming from a spray on TM .

Let $c: [0, 1] \rightarrow M$, $t \mapsto x^i(t)$ be a curve on M , such that x^i are solutions for the system of ODE's (10):

$$\frac{\delta \dot{x}^i}{dt} = \frac{1}{2} F^i(x, \dot{x}),$$

where F^i are the components of a d-vector field on M .

Let $\alpha: [0, 1] \times (-\varepsilon, \varepsilon) \rightarrow M$, $(t, u) \mapsto (\alpha^i(t, u))$ denote a variation of c (not necessarily with fixed endpoints): $\alpha^i(t, 0) = x^i(t)$, $\forall t \in [0, 1]$,

$$y^i = \left. \frac{\partial \alpha^i}{\partial t} \right|_{u=0} = \frac{dx^i}{dt}$$

the components of the tangent vector field of c and

$$w^i(t) = \left. \frac{\partial \alpha^i}{\partial u} \right|_{u=0}$$

the components of the deviation vector field attached to the variation α . Let $\tilde{\alpha}$ denote the following extension of α to the second order tangent bundle T^2M :

$$(25) \quad \tilde{\alpha}: [0, 1] \times (-\varepsilon, \varepsilon) \rightarrow T^2M, (t, u) \mapsto (\alpha^i(t, u), \frac{\partial \alpha^i}{\partial t}(t, u), \frac{1}{2} \frac{\partial^2 \alpha^i}{\partial t^2}(t, u))$$

and

$$\alpha^i_t = \frac{\partial \alpha^i}{\partial t}, \quad \alpha^i_u = \frac{\partial \alpha^i}{\partial u}.$$

We have:

- $h \left(\frac{\partial \tilde{\alpha}}{\partial t} \right) = \alpha^i_t \delta_{(0)i}$, $h \left(\frac{\partial \tilde{\alpha}}{\partial u} \right) = \alpha^i_u \delta_{(0)i}$;
- $\alpha^i_t(t, 0) = y^i(t)$, $\alpha^i_u(t, 0) = w^i$, $\forall t \in [0, 1]$.

Let us denote $\frac{D}{\partial t} = D_{\frac{\partial \tilde{\alpha}}{\partial t}}$ and $\frac{D}{\partial u} = D_{\frac{\partial \tilde{\alpha}}{\partial u}}$ the covariant derivations with respect to the Berwald connection on T^2M . Then:

$$(26) \quad \begin{aligned} \frac{D\alpha^i_t}{\partial t} &= \frac{\partial \alpha^i_t}{\partial t} + N^i_j(\alpha, \alpha_t) \alpha^j_t, \\ \frac{D\alpha^i_t}{\partial u} &= \frac{\partial \alpha^i_t}{\partial u} + N^i_j(\alpha, \alpha_t) \alpha^j_u, \\ \frac{D\alpha^i_u}{\partial t} &= \frac{\partial \alpha^i_u}{\partial t} + N^i_j(\alpha, \alpha_t) \alpha^j_u; \end{aligned}$$

(the covariant derivatives are taken 'with reference vector $\frac{\partial \tilde{\alpha}}{\partial t}$ ', [5]).

By commuting partial derivatives of α^i , we have $\frac{\partial \alpha_t^i}{\partial u} = \frac{\partial \alpha_u^i}{\partial t}$, hence that the last two covariant derivatives (26) coincide:

$$\frac{D\alpha_t^i}{\partial u} = \frac{D\alpha_u^i}{\partial t},$$

which is,

$$\frac{D}{\partial u} \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) = \frac{D}{\partial t} \left(h \frac{\partial \tilde{\alpha}}{\partial u} \right).$$

By applying $D \frac{\partial \tilde{\alpha}}{\partial t}$ again to the above equality, we get:

$$(27) \quad \frac{D}{\partial t} \frac{D}{\partial u} \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) = \frac{D}{\partial t} \frac{D}{\partial t} \left(h \frac{\partial \tilde{\alpha}}{\partial u} \right).$$

In the left hand side, we can commute covariant derivatives by means of the curvature tensor of D :

$$\begin{aligned} \frac{D}{\partial t} \frac{D}{\partial u} \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) &= R \left(\frac{\partial \tilde{\alpha}}{\partial t}, \frac{\partial \tilde{\alpha}}{\partial u} \right) \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) + \frac{D}{\partial u} \frac{D}{\partial t} \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) \\ &\quad + D \left[\frac{\partial \tilde{\alpha}}{\partial t}, \frac{\partial \tilde{\alpha}}{\partial u} \right] \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right). \end{aligned}$$

But, $\left[\frac{\partial \tilde{\alpha}}{\partial t}, \frac{\partial \tilde{\alpha}}{\partial u} \right]$ is 0, hence the last term in the above relation vanishes and (27) becomes

$$(28) \quad \frac{D}{\partial t} \frac{D}{\partial t} \left(h \frac{\partial \tilde{\alpha}}{\partial u} \right) = R \left(\frac{\partial \tilde{\alpha}}{\partial t}, \frac{\partial \tilde{\alpha}}{\partial u} \right) \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) + \frac{D}{\partial u} \frac{D}{\partial t} \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right).$$

Moreover, at $u = 0$, we have $h \frac{\partial \tilde{\alpha}}{\partial t} \Big|_{u=0} = \alpha_t^i(t, 0) \delta_{(0)i} = y^i \delta_{(0)i}$, and by means of (11), we get

$$\frac{D}{\partial t} \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) \Big|_{u=0} = \frac{Dy^i}{\partial t} \delta_{(0)i} = \frac{1}{2} F^i \delta_{(0)i} =: \frac{1}{2} F$$

(where F is a d-vector field on T^2M). Then, (28) becomes

$$(29) \quad \frac{D^2}{\partial t^2} \left(h \frac{\partial \tilde{\alpha}}{\partial u} \Big|_{u=0} \right) = R \left(\frac{\partial \tilde{\alpha}}{\partial t}, \frac{\partial \tilde{\alpha}}{\partial u} \right) \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) \Big|_{u=0} + \frac{1}{2} D_u F.$$

At $u = 0$, we also have $h \frac{\partial \tilde{\alpha}}{\partial u} = w^i \delta_{(0)i}$. In local writing, by evaluating

$$R \left(\frac{\partial \tilde{\alpha}}{\partial t}, \frac{\partial \tilde{\alpha}}{\partial u} \right) \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right)$$

and taking into account (24), we obtain

$$R \left(\frac{\partial \tilde{\alpha}}{\partial t}, \frac{\partial \tilde{\alpha}}{\partial u} \right) \left(h \frac{\partial \tilde{\alpha}}{\partial t} \right) \Big|_{u=0} = y^h y^k R_{h^i jk} w^j \delta_{(0)i}.$$

We have thus proved

Proposition 3. *The components of the deviation vector field $w^i = \frac{\partial \alpha^i}{\partial u}|_{u=0}$ of the trajectories*

$$(30) \quad \frac{\delta y^i}{dt} = \frac{1}{2} F^i(x, y),$$

satisfy, with respect to the Berwald linear connection on T^2M , the Jacobi-type equation

$$(31) \quad \frac{D^2 w^i}{dt^2} = \frac{1}{2} \frac{DF^i}{\partial u}|_{u=0} + y^h y^k R_{hjk}^i w^j.$$

The above generalizes the usual Jacobi equation, in the case of mechanical systems with external forces.

7. NONLINEAR CONNECTION

In natural coordinates, (31) becomes:

$$(32) \quad \begin{aligned} & \frac{d^2 w^i}{dt^2} + \left(2N^i_j - \frac{1}{2} \frac{\partial F^i}{\partial y^j} \right) \frac{dw^j}{dt} \\ & + \left(\frac{d}{dt}(N^i_j) + N^i_k N^k_j - y^h y^k R_{hjk}^i + L^i_{kj} \frac{1}{2} F^k - \frac{1}{2} \frac{\partial F^i}{\partial x^j} \right) w^j = 0. \end{aligned}$$

Taking into account (23), we have $R^i_{hjk} y^h = R^i_{jk}$. Also, $L^i_{kj} = \frac{\partial N^i_k}{\partial y^j}$, hence the above equality can be seen as:

$$\begin{aligned} & \frac{d^2 w^i}{dt^2} + \left(2N^i_j - \frac{1}{2} \frac{\partial F^i}{\partial y^j} \right) \frac{dw^j}{dt} \\ & + \left(\mathbb{C}(N^i_j) + N^i_k N^k_j - y^k R^i_{jk} + \frac{1}{2} \frac{\partial N^i_k}{\partial y^j} F^k - \frac{1}{2} \frac{\partial F^i}{\partial x^j} \right) w^j = 0, \end{aligned}$$

where

$$\mathbb{C} = y^k \frac{\partial}{\partial x^k} + 2y^{(2)k} \frac{\partial}{\partial y^k}.$$

There holds:

Theorem 4. (1) *The quantities*

$$(33) \quad \begin{aligned} M^i_{(1)j}(x, y) &= \frac{1}{2} \left(2N^i_j - \frac{1}{2} \frac{\partial F^i}{\partial y^j} \right), \\ M^i_{(2)j}(x, y, y^{(2)}) &= \frac{1}{2} \left(\mathbb{C}(N^i_j) + N^i_k N^k_j - y^k R^i_{jk} \right. \\ & \quad \left. + \frac{1}{2} \frac{\partial N^i_k}{\partial y^j} F^k - \frac{1}{2} \frac{\partial F^i}{\partial x^j} \right) \end{aligned}$$

are the dual coefficients of a nonlinear connection on T^2M .

- (2) With respect to this nonlinear connection, the extensions of deviation vector fields attached to (10) have vanishing v_2 -components:

$$\frac{1}{2} \frac{d^2 w^i}{dt^2} + M_{(1)j}^i \frac{dw^j}{dt} + M_{(2)j}^i w^j = 0.$$

Proof. 1): In the equation (31), both the left hand side and the right hand side are components of d-vector fields; by a direct computation, it follows that, with respect to local coordinate changes (3) on T^2M , the quantities $M_{(1)j}^i$ and

$M_{(2)j}^i$ obey the rules of transformation (17) of the dual coefficients of a nonlinear connection on T^2M .

2): The deviation vector field attached to the variation $\tilde{\alpha}$ in (25) is

$$\begin{aligned} W &= \left. \frac{\partial \tilde{\alpha}}{\partial u} \right|_{u=0} \equiv \left\{ \frac{\partial \alpha^i}{\partial u} \frac{\partial}{\partial x^i} + \frac{\partial}{\partial u} \left(\frac{\partial \alpha^i}{\partial t} \right) \frac{\partial}{\partial y^i} + \frac{1}{2} \frac{\partial}{\partial u} \left(\frac{\partial^2 \alpha^i}{\partial t^2} \right) \frac{\partial}{\partial y^{(2)i}} \right\} \Big|_{u=0} \\ &= w^i \frac{\partial}{\partial x^i} + \frac{dw^i}{dt} \frac{\partial}{\partial y^i} + \frac{1}{2} \frac{d^2 w^i}{dt^2} \frac{\partial}{\partial y^{(2)i}}. \end{aligned}$$

In the adapted basis $(\delta_{(0)i}, \delta_{(1)i}, \delta_{(2)i})$, this yields:

$$W = w^i \delta_{(0)i} + \frac{\delta w^i}{dt} \delta_{(1)i} + \frac{\delta w^{(2)i}}{dt} \delta_{(2)i},$$

where $\frac{\delta w^i}{dt} = \frac{dw^i}{dt} + M_{(1)j}^i(x, y)w^j$ and

$$\frac{\delta w^{(2)i}}{dt} = \frac{1}{2} \frac{d^2 w^i}{dt^2} + M_{(1)j}^i(x, y) \frac{dw^j}{dt} + M_{(2)j}^i(x, y, y^{(2)})w^j.$$

Taking into account (33), the Jacobi equation (32) is re-expressed as: \square

$$\frac{\delta w^{(2)i}}{dt} = 0.$$

In presence of the above nonlinear connection, the extension W to T^2M of any Jacobi field on M , corresponding to trajectories (10) in presence of external forces, belongs to the $N_0 \oplus N_1$ distribution.

8. DEVIATIONS OF GEODESICS

Let us examine the particular case when $F = 0$. Let TM be endowed with a spray with coefficients $G^i = G^i(x, y)$ and $N_j^i = \frac{\partial G^i}{\partial y^j}$, the coefficients of the associated nonlinear connection on TM .

If $F = 0$, then we deal with deviations of autoparallel curves (called *geodesics*)

$$\frac{\delta y^i}{dt} = 0.$$

We get

$$\begin{aligned} M_{(1)j}^i &= N_j^i, \\ M_{(2)j}^i &= \frac{1}{2}(\mathbb{C}(N_j^i) + N_k^i N_j^k - y^j R_{jk}^i); \end{aligned}$$

taking into account that, in our approach, $M_{(1)j}^i$ do not depend on $y^{(2)}$, we notice that, in the case $F = 0$, our nonlinear connection only differs by the term $-y^j R_{jk}^i$ from Miron's one (1), [16].

Remark 5. Along an extension curve $\tilde{c}: [0, 1] \rightarrow T^2M$, $t \mapsto (x^i(t), y^i(t) = \dot{x}^i(t), y^{(2)i}(t) = \frac{1}{2}\ddot{x}^i(t))$ there hold the equalities

$$\frac{\delta y^i}{dt} = \frac{Dy^i}{dt}, \quad \frac{\delta y^{(2)i}}{dt} = \frac{D^2 y^i}{dt^2},$$

where $\frac{D}{dt}$ denotes the covariant derivative associated to the Berwald connection on T^2M . For these curves, taking into account the equalities $y^j y^k R_{jk}^i = 0$ (which can be obtained by direct calculation), it follows that, with the assumptions made at the beginning of this section, $\frac{\delta y^i}{dt}$ and $\frac{\delta y^{(2)i}}{dt}$ have the same values as those obtained for the connection (1). Still, along general curves γ on T^2M , the value of $v_2(\dot{\gamma})$ does no longer coincide with that one obtained with respect to (1).

Remark 6. Also, for a vector field w along the projection c of \tilde{c} onto M , we have

$$\frac{\delta w^i}{dt} = \frac{Dw^i}{dt}.$$

Conclusions:

- (1) c is a geodesic if and only if its extension to T^2M is horizontal.
- (2) For a vector field w along a geodesic c on M , we have:
 - (a) $\frac{\delta w^i}{dt} = 0$, if and only if w is parallel along $\dot{c} = y$.
 - (b) $\frac{\delta w^{(2)i}}{dt} = 0$ if and only if w is a Jacobi field along c .

In the case $F = 0$, we should mention some related results and approaches:

In the geometry of TM : In the case when the base manifold M is endowed with a linear connection ∇ , a linear connection on the tangent bundle TM , with similar properties to those of (33) is given by the *complete lift* ∇^C of ∇ (cf. [28] and [10]). Namely, in the two cited monographs, it is shown that, if a curve $\bar{\sigma}: [0, 1] \rightarrow TM$, $t \mapsto (x^i(t), w^i(t))$ is a geodesic with respect to ∇^C ,

then its projection $\sigma: t \mapsto (x^i(t))$ onto M is a geodesic with respect to ∇ and $X(t) = w^i(t) \frac{\partial}{\partial x^i}$ is a Jacobi field along σ .

In the geometry of T^2M : In presence of a linear connection ∇ on M , C. Dodson and M. Radivoioci, [11] built a covariant derivation law $\bar{\nabla}: \mathcal{X}(M) \times \Gamma(T^2M) \rightarrow \Gamma(T^2M)$ for sections of the second order tangent bundle (regarded as a vector bundle over M) and used it in order to define a nonlinear connection in the frame bundle of order 2 $L^{(2)}M$. In the case when ∇ is torsion-free, the covariant derivative $\bar{\nabla}_v X$, where $v = \frac{\partial \alpha}{\partial u}|_{u=0}$, and $X \equiv \left(\frac{\partial \alpha}{\partial t}, \frac{D \partial \alpha}{dt \partial t} \right)$ (with our notations in Section 6) would yield our $\left(\frac{\delta w^i}{dt}, \frac{\delta w^{(2)i}}{dt} \right)$. Still, in the cited paper, it is not established any link between the defined connection and the Jacobi equation on M .

The novelty of our approach consists in relating the v_2 -distribution on T^2M to deviations of geodesics of the base manifold.

9. EXTERNAL FORCES IN FINSLER-LOCALLY MINKOWSKIAN SPACES

Another interesting particular case is that of Finsler-locally Minkowskian spaces (whose geodesics are straight lines). Let $(M, L(y))$ be a Finsler-locally Minkowskian space, [2], [5].

Then, $N^i_j = 0$, $L^i_{jk} = 0$ (for the Berwald connection), [2], [5]. In presence of an external force field, the evolution equations of a mechanical system will take the form

$$(34) \quad \frac{d^2 x^i}{dt^2} = \frac{1}{2} F^i(x, \dot{x}).$$

In this case, with the above notations, our nonlinear connection is given by

$$\begin{aligned} M^i_{(1)j} &= -\frac{1}{4} \frac{\partial F^i}{\partial y^j}, \\ M^i_{(2)j} &= -\frac{1}{4} \frac{\partial F^i}{\partial x^j}. \end{aligned}$$

This is, deviations of the evolution curves (34) can be written simply:

$$2 \frac{\delta w^{(2)i}}{dt} \equiv \frac{d^2 w^i}{dt^2} - \frac{1}{2} \frac{\partial F^i}{\partial y^j} \frac{dw^j}{dt} - \frac{1}{2} \frac{\partial F^i}{\partial x^j} w^j = 0.$$

The result holds valid for any globally defined system of ordinary differential equations of order 2 on M , of the form (34).

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