

A Novel Design Conception of Switched Reluctance Motor for Electrical Vehicles

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Abstract—This paper deals with a novel design conception of Switched Reluctance Motor (SRM) for electrical vehicles as electrical mini truck. This design consists of segmented stator with toroid windings water cooled and the rotor has salient poles. The SRM dimensions are calculated on the base of input requirements. The static and dynamic parameters of SRM are obtained from simulation models based on Finite element method and torque, power versus speed characteristics are presented.

Keywords— switched reluctance motor, electrical car, equivalent circuit parameters, traction characteristic

I. INTRODUCTION

At present time, the discussion about electrical cars development and improvement is very extensive. One of the main tasks is still the price of such a car, which is at this time relatively high in comparison with other conventional automobiles. The electrical car consists of three basic parts: mechanical (it is very similar with conventional car and also the price can be comparative), fuel part (battery pack, which is the dominant part of the car price) and electrical equipment including electrical drive, which depends on used electrical drive and its converter and control system.

As it is known, DC, AC and special electrical drives are used in electrical cars. On the beginning, DC series machine were used because of their natural mechanical characteristic approached to the traction requirements. The development of power electronic caused the replacement of series DC machines by separately excited ones, whose field and armature windings are fed from two independent DC controlled sources and the mechanical characteristic can be adapted to traction ones [1]. This kind of electrical drive is used in the first electrical car in Slovakia more than 20 years ago [2].

The best solution seems to be SMPM because of very high ratio power density/volume. Here could be taken in the account the price of PM and their dependence on the temperature, which are disadvantages of this drive [3].

In many papers, Switched Reluctance Motor (SRM) is mentioned as a real drive for electrical car [4], [5], [6], [7]. The drive with SRM is becoming a very strong competitor to the drives with IM. SRM has simpler construction and, therefore, lower production costs, higher robustness and lower

maintenance requirements as the IM drives. The SRM can operate only from an inverter, which works in more wide speed range than IM converter. The same can be noticed about the control system and methods. It is also needed for the SRM operation, but it is simpler as the vector control for IM drives.

The profile of the SRM torque/speed characteristic, although it is supplied from converter, looks similar to traction characteristic. This is very important reason, why the SRM is becoming a strong competitor to IM drives. On the other hand, it could be mentioned, that the drawback of SRM is the torque ripple and rotor position sensor presence. It is given by basic principle of its construction and operation. The SRM construction is very simple. The both stator and rotor have salient poles and only stator carries winding coils, which are suitable connected to create phase. The magnetic flux is provided by phase current to develop a reluctance torque [8], [9], [10], [11]. The cross-section area of the three phases 12/8 novel conception SRM is shown in the Fig. 1.

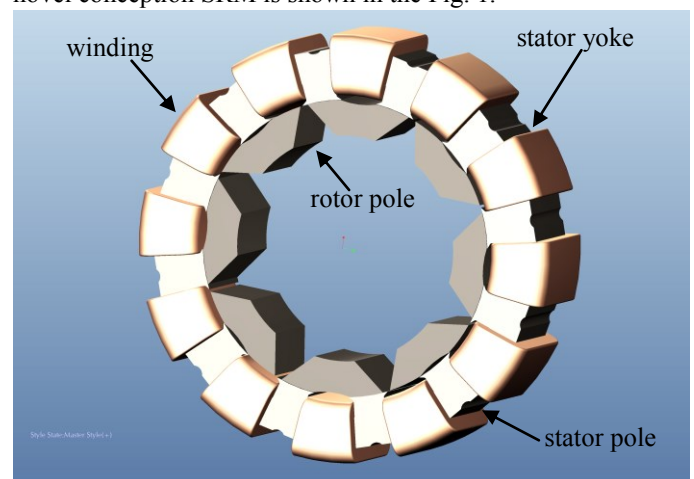


Fig. 1. Illustrative figure of the 12/8 three phases novel SRM design.

The aims of this paper are to point out the performances of the SRM novel design from the electrical car utilization and from point of view of the SRM parameters used in its model. The mathematical SRM model is described and solved to simulate different operation states to obtain output torque and output power/speed characteristics, which is compared and

discussed. The input parameters are: rated power 20 kW, rated speed 5000 rpm, DC voltage 300 V and maximal current is 250 A.

On the base of this analysis and the suitability of the SRM for electrical car, a new real SRM prototype will be manufactured for a real electrical car to replace existing DC drive.

II. DESIGN PROCEDURE

A. SRM sizing dimensions

Design procedure of SRM is made with the required outer geometric dimensions of the existed DC motor, mainly outer stator diameter d_s and stack length l_{Fe} , which are chosen: $d_s = 300$ mm and $l_{Fe} = 100$ mm, for voltage level of 300 V. The proposed number of phases is $m = 3$, because lower torque ripple is needed and motor can start up from every rotor position. The number of stator and rotor poles is given as $N_s / N_r = 12/8$. A novel concept of SRM consists of segmented stator with concentrated windings and shorted magnetic flux paths.

B. Sizing internal dimensions

The basic topology of geometry is shown in Fig. 2. The SRM dimensions are calculated on the base of known analytical equations used during common SRM design procedure. It is described in [3] and [11].

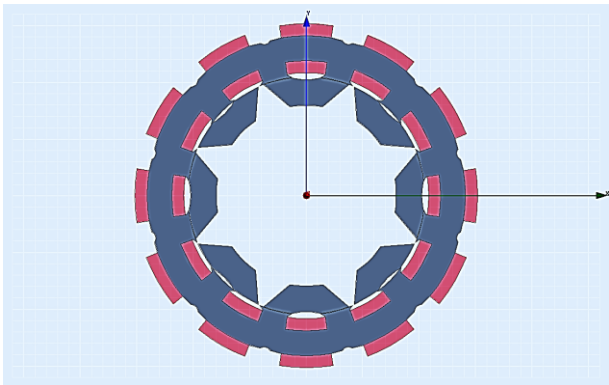


Fig. 2. Basic topology of 12/8 three phases SRM novel concept.

C. Winding coil design

The calculation of the number of turns N_p can be made by assuming that at the specified speed the conduction angle of power transistors is equal to the stroke angle ε , which is defined as:

$$\varepsilon = \frac{2\pi}{mN_r} \quad (1)$$

where m is number of phases and N_r is number of rotor poles. If there is no current – chopping the peak flux linkage per phase is given by:

$$\psi_{peak} = \frac{V\varepsilon}{\omega} \quad (2)$$

where ω is angular velocity and V is DC supply voltage. At rated speed ψ_{peak} occurs well before the aligned position, typically when the overlap between the stator and rotor poles is about 2/3 of the stator pole arc. At this moment, it can be assumed that the ampere-turns are sufficient to bring the stator pole to the flux density B_s , then:

$$\psi_{peak} = SB_s n_c N_p \quad (3)$$

Where S is cross-section of magnetic flux path, n_c is number of phase coils connected in serial and N_p is number of one coil turns. Substituting of eq. (2) to (3),

$$N_p = \frac{V\varepsilon}{SB_s n_c \omega} \quad (4)$$

where n_c is number of coils per phase. The flux density of stator pole can be supposed 1.6 T. The cross section of coil wires is depended on normalized wire conductor. The calculation is based on constant flux density (1.6 T). The basic geometrical parameters of the winding are in the Fig.3.

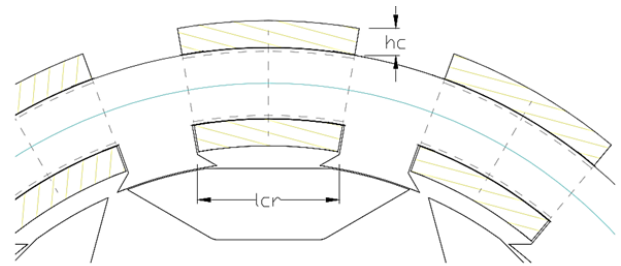


Fig. 3. The basic geometrical winding parameters of the SRM novel concept.

D. Static parameters calculation

On the base of this design the static characteristics as phase inductance, magnetic flux linkage and torque versus phase current and rotor position have been calculated by means of FEM. The analytical approach is used only for geometrical dimension calculations. The results are in the Fig. 4, Fig. 5 and Fig. 6, respectively.

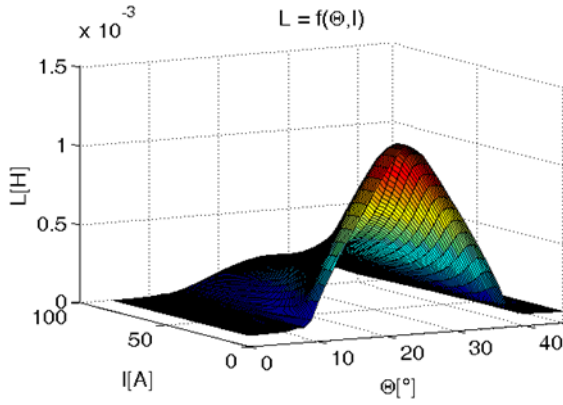


Fig. 4. FEM analysis of inductance for various rotor position and current.

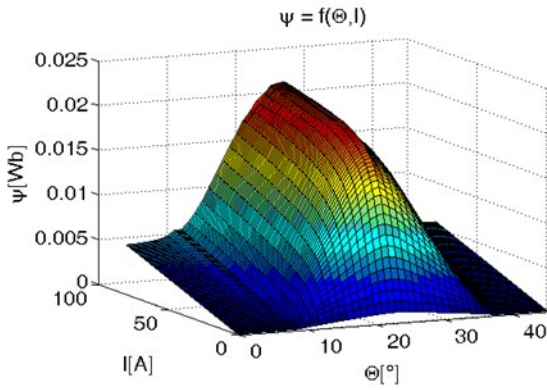


Fig. 5. FEM analysis of flux linkage for various rotor position and current.

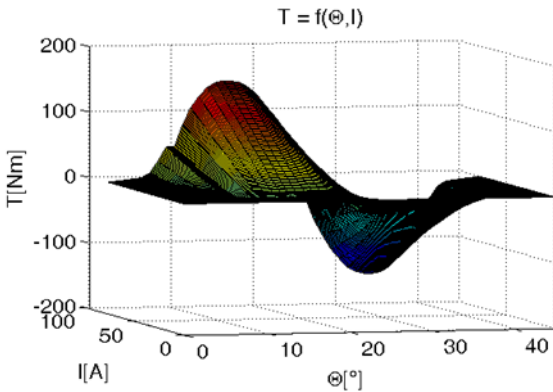


Fig. 6. FEM analysis of torque for various rotor position and current.

E. Dynamic analysis of SRM

By using mathematical model in the dynamic analysis we can calculate phase current, speed, voltage and dynamic torque of the SRM. The electromagnetic torque of SRM can be calculated from:

$$T_e = \frac{\partial}{\partial \Theta} \int_0^i \Psi di \quad (5)$$

The voltage equation of one SRM phase is given as:

$$v = Ri + \frac{d\psi}{dt} \quad (6)$$

where R is phase resistance, i is phase current and ψ is flux linkage. The flux linkage depends on both parameters: phase current and rotor position ($\psi = f(i, \Theta)$). Then

$$\frac{d\psi}{dt} = \frac{\partial \psi}{\partial i} \frac{di}{dt} + \frac{\partial \psi}{\partial \Theta} \frac{d\Theta}{dt} \quad (7)$$

The phase current is calculated from combination of (6) and (7) as:

$$\frac{di}{dt} = \frac{v - \left(R + \frac{dL(i, \Theta)}{d\Theta} \omega \right) i}{L(i, \Theta)} \quad (8)$$

The real angular speed is calculated from equation:

$$\frac{d\omega}{dt} = \frac{1}{J} \left(\sum_{j=1}^m T_j(\Theta, i) - T_{load} \right) \quad (9)$$

where J is the moment of inertia and T_{load} is load torque.

The SRM is controlled on the base of rotor position Θ , therefore it is as following:

$$\Theta = \int \omega dt \quad (10)$$

On the base of this mathematical model a simulation model has been created to solve transients for different speeds, loads, switch ON, switch OFF angles to find optimal dynamic operation of SRM. The simulation of currents, speed and torque waveform has been done for demanded speed 5000 rpm. In the Fig. 7 speed waveform is shown during startup to 5000 rpm and at $t = 0.6$ a 65 Nm load is connected.

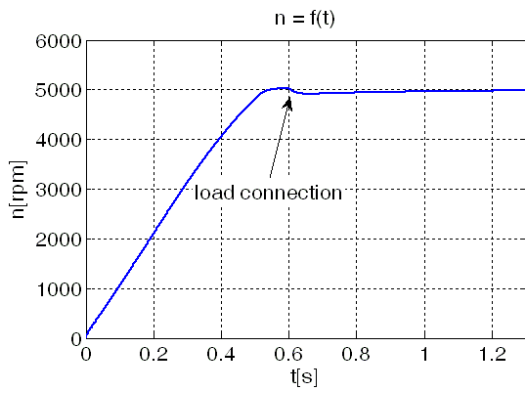


Fig. 7. Speed waveform with $n = 5000$ rpm.

The current waveforms for all three phases, start up, load connection for speed 5000 rpm are shown in the Fig. 8.

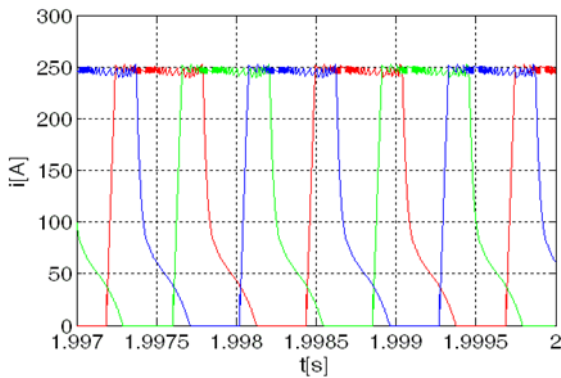


Fig. 8. Phase currents for $n = 5000$ rpm.

The total torque given by all three phase is shown in the Fig. 9 and the torque ripple detail is in the Fig. 10 respectively.

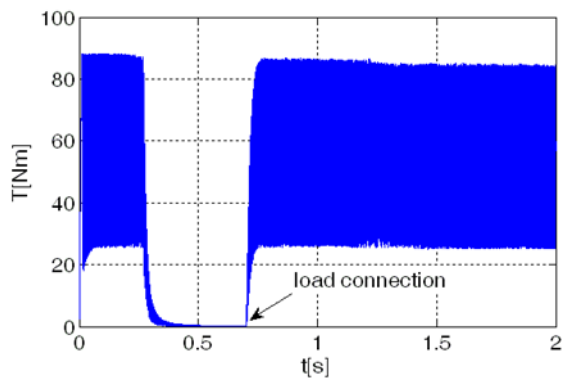


Fig. 9. Total torque for $n = 5000$ rpm.

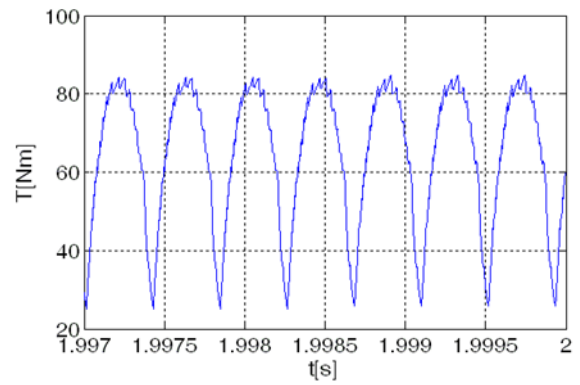


Fig. 10. Total torque ripple detail for $n = 5000$ rpm.

On this base of all required parameters, the output characteristics torque and power versus speed have been obtained from dynamic simulation. These characteristics are shown in the Fig. 11 and Fig. 12 for current up to 250 A.

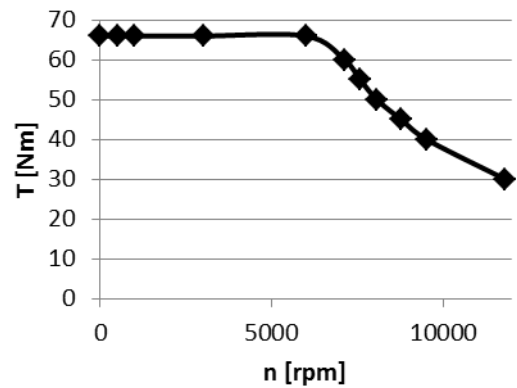


Fig. 11. Total torque versus speed for working range of proposed novel SRM design

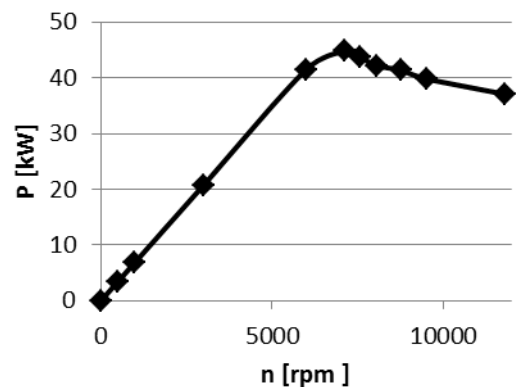


Fig. 12. Output power versus speed for working range of proposed novel SRM design

The losses calculation can be carried out in accordance with [11] and [12]. As it is known, two dominant parts of losses are in electrical machines: winding losses and core losses. In this case both of them have been analyzed and calculated.

To calculate the efficiency, the input power is needed. It could be given from known equation for instantaneous power. On this base, the efficiency of designed SRM for various speeds from 1000 to 5000 has been calculated. The results are from 89 % to 92 %, what are acceptable values for SRM. The working point of this motor is around 5000 rpm and 65 Nm what is 34 kW of output power. It can be noticed, that required input parameters were over obtained and an optimization process can be carried out to minimize some dimensions and losses. The basic masses of designed SRM are shown in the Table I.

TABLE I. BASIC SRM MASSES

12/8 designed SRM		
Defined part of SRM	kg	kg
Winding mass	1.9 (Al)	5.75 (Cu)
Stator mass	10.25	-
Rotor mass	4.845	-
Total mass	17 (Al)	20.8 (Cu)

This SRM design described above has been calculated on the base of analytical calculation and FEM without its optimization. The prototype model of this novel SRM design with segmented stator is shown in the Fig. 13.

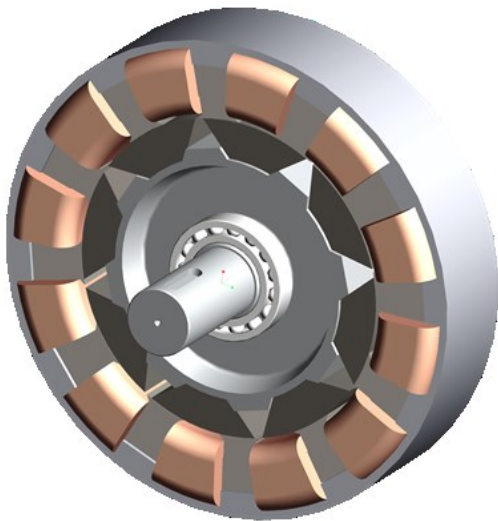


Fig. 13. The prototype model of this novel SRM design with segmented stator

In the next, the thermal analysis will be carried out with water cooling system and some recommendations will be given for manufacturing process.

III. CONCLUSION

The paper deals with the SRM novel design and static and dynamic parameters investigation from point of view of its application and using in electrical cars. In the future, the optimization of this concept will be carried out to minimize materials and losses and to improve efficiency of this motor. On this base a prototype of SRM will be manufactured and used in the real car.

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