

# PATHS ON THE SPHERE WITHOUT SMALL ANGLES

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ABSTRACT. It is a recent result that given a finitely many points on  $\mathbb{R}^2$ , it is possible to arrange them on a polygonal path so that every angle on the polygonal path is at least  $\pi/9$ . Here we extend this result to finite sets contained in the 2-dimensional sphere.

## 1. INTRODUCTION AND RESULTS

Let  $X$  be a finite set in  $\mathbb{R}^2$ . An ordering,  $x_1, x_2, \dots, x_n$ , of the points of  $X$  gives rise to a polygonal path  $p = x_1x_2 \dots x_n$  on  $X$ : its edges are the segments connecting  $x_i$  to  $x_{i+1}$ . The angle of  $p$  at  $x_i$  is just  $\angle x_{i-1}x_ix_{i+1}$ . The path is called  $\alpha$ -good if all of its angles are at least  $\alpha$  where  $\alpha > 0$ . Answering a question of Sándor Fekete [3] from 1992, (cf [4] as well) we proved in [1] the following result.

**Theorem 1.** *If  $X$  is a finite set in the plane, then there is an  $\alpha_0$ -good path on  $X$  with  $\alpha_0 = 20^\circ = \pi/9$ .*

The aim of this paper is to extend this result to finite sets  $X \subset S^2$ , the 2-dimensional Euclidean sphere. The definitions are almost the same. Given  $a, b \in S^2$  there is a shortest path  $\widehat{ab} \subset S^2$  connecting  $a$  and  $b$  in  $S^2$ . This shortest path is an arc of the great circle containing  $a$  and  $b$ , and is unique unless  $a$  and  $b$  are antipodal. An ordering,  $x_1, x_2, \dots, x_n$ , of the points of  $X$  is identified with a path  $x_1x_2 \dots x_n$  on  $X$  consisting of the arcs  $\widehat{x_ix_{i+1}}$ . The angle of this path at  $x_i$  is just the spherical angle at  $x_i$  of the spherical triangle with vertices  $x_{i-1}, x_i, x_{i+1}$ . The path is called  $\alpha$ -good if all of its angles are at least  $\alpha$  where  $\alpha > 0$ .

**Theorem 2.** *There is  $\alpha > 0$  such that for every finite set  $X \subset S^2$  there exists an  $\alpha$ -good path on the points of  $X$  (using every point of  $X$  exactly once).*

The proof gives  $\alpha = 5^\circ$  via generous computations. Slightly larger value for  $\alpha$  can be reached by more careful calculations but we have not tried to find the best possible  $\alpha$ . The planar example consisting of the vertices of an equilateral triangle and its center shows that Theorem 1 cannot hold with  $\alpha_0 > 30^\circ$ . The same applies to the spherical case as shown by a small size

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1991 *Mathematics Subject Classification.* Primary 52C35, secondary 52C99.

*Key words and phrases.* finite point sets on the sphere, polygonal paths, no small angle.

spherical and equilateral triangle in  $S^2$ . Jan Kynčl [2] has proved recently that Theorem 1 holds with  $\alpha = 30^\circ$ , the best possible bound. Using his results the bound  $\alpha = 5^\circ$  can be improved to  $\alpha = 7^\circ$ .

The same question can be asked on higher dimensional spheres  $S^d$ . The methods of this paper work there as well, resulting in a smaller universal  $\alpha$ , see Section 6.

We will need a stronger version of Theorem 1 which is proved in [1]. To state it a few additional definitions are needed. The direction  $\overline{xy}$  of a pair  $x, y \in \mathbb{R}^2$  is the unit vector  $(y - x)/|y - x|$ , we suppose here that  $x \neq y$ . So  $\overline{xy} \in S^1$ , the unit circle.

Given a path  $z_1 z_2 \dots z_n$  in the plane the directions  $\overline{z_2 z_1}$  and  $\overline{z_{n-1} z_n}$  are called the *end directions* of the path. We call a subset  $R$  of  $S^1$  a *restriction* if it is the disjoint union of two closed arcs  $R_1, R_2 \subset S^1$  such that both have length  $4\alpha_0$  and their distance from each other (along the unit circle) is larger than  $2\alpha_0$ . (Recall that  $\alpha_0 = 20^\circ$ .) We call the path  $z_1 \dots z_n$  *R-avoiding* if the path is  $\alpha_0$ -good and the two end directions are not in the same  $R_i$  ( $i = 1, 2$ ).

**Theorem 3.** *Let  $X$  be a finite set of points in the plane. For every restriction  $R$  there is an  $R$ -avoiding path on all the points of  $X$ .*

## 2. PREPARATIONS

In the proofs to come we assume that our finite set  $X \subset S^2$  contains no antipodal pair. The general case follows from this by a simple limit argument.

Given  $a, b \in S^2$ , the length of the arc  $\widehat{ab}$  is simply the angle between the vectors  $a$  and  $b$ , measured in degrees (sometimes in radians). Of course the length of  $\widehat{ab}$  can be expressed by the Euclidean distance  $|a - b|$ . The pair  $a, b \in X$  is a diameter of  $X$  if it has the largest length among all pairs in  $X$ .

For the proof of Theorem 2 we need two auxiliary results. The first one is simpler: it is essentially the planar case, that is Theorem 1 applied on  $S^2$ . Precisely, let  $P$  be a plane touching  $S^2$  at a point  $z \in S^2$  and let  $C = C(t)$  be the cap of  $S^2$  defined by

$$C(t) = \{x \in S^2 : z \cdot x \geq t\}$$

where  $t \in (0, 1)$ .

**Theorem 4.** *If  $X \subset C(t)$  is finite, then there is an  $\alpha(t)$ -good path on  $X$  where  $\alpha(t) \in (0, 90^\circ)$  is given by  $\sin \alpha(t) = t \sin 20^\circ$ .*

The proof is given in Section 4. The following corollary to Theorem 4 will be used in the proof of Theorem 2. Note that  $\alpha(1/2) = 9.846\dots^\circ > 9^\circ$ . Set  $\alpha_1 = 9^\circ$ .

**Corollary 1.** *If the diameter of  $X$  is at most  $60^\circ$ , then there is an  $\alpha_1$ -good path on  $X$ .*

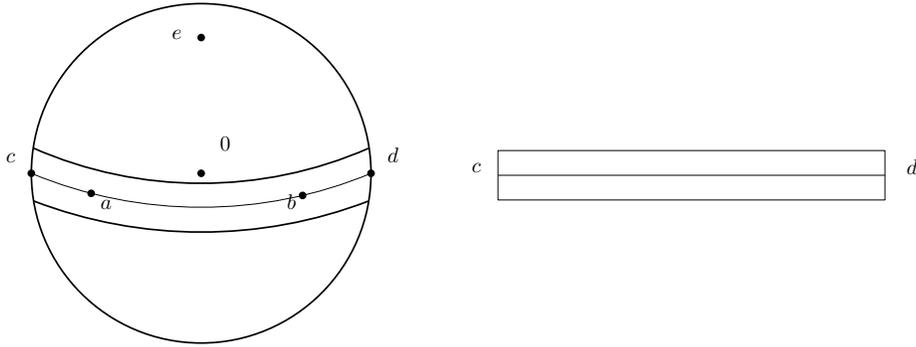


FIGURE 1. The spherical halfslab  $Q(a, b)$  and its planar representation

To state the second auxiliary result we need some definitions. Let  $a, b \in X$  form a diameter of  $X \subset S^2$ . Set  $c = (a - b)/|a - b|$  so  $c \in S^2$ . Choose  $e \in S^2$  that is orthogonal to both  $c$  and  $a + b$ . Let  $\beta = 10^\circ$ . We define the halfslab  $Q = Q(a, b)$  as

$$Q = \{x \in S^2 : (a + b) \cdot x \geq 0, |e \cdot x| \leq \sin \beta\},$$

see Figure 1. Here is the second auxiliary result.

**Theorem 5.** *If  $a, b$  form a diameter of  $X$  and  $X \subset Q(a, b)$ , then there is an  $\alpha$ -good path on  $X$  (where  $\alpha = 5^\circ$ ).*

We prove this theorem in Section 6 with some preparations in Section 5. The next section contains the proof of Theorem 2. It is essentially an induction argument reducing the problem to two cases: when  $X$  lies in a cap  $C(t)$  for some  $t$  and when  $X$  lies in the halfslab  $Q(a, b)$ . These two cases are covered by Theorems 4 and 5.

### 3. PROOF OF THEOREM 2

We introduce further terminology and notation before the proof. Given  $u, v \in S^2$  with  $u \neq \pm v$ , let  $L(u; v)$  be the half of the great circle connecting  $u$  to  $-u$  that contains  $v$ . The union of  $L(u; v)$  and  $L(u; w)$  (when  $w \notin L(u; v)$ ) is a closed curve without self-intersection on  $S^2$  so it splits  $S^2$  into two connected components to be called *sectors*. Let  $E(u; v, w)$  denote the smaller one of the two. No confusion will arise here since  $E(u; v, w)$  will always be much smaller than the other sector.

Note that for  $x, y \in E(u; v, w)$  the arc  $\widehat{xy} \subset E(u; v, w)$ .

Let  $L(u; z)$  be the half of the great circle exactly halving  $E(u; v, w)$ . Let  $\gamma$  be the angle between the planes  $L(u; v)$  and  $L(u; z)$ , we call  $\gamma$  the *angle of the sector*  $E(u; v, w)$ . Note that this angle is at most  $90^\circ$  always.

We will often write  $E(u; \gamma, z)$  or simply  $E(u; \gamma)$  instead of  $E(u; v, w)$  where  $\gamma$  is the angle of this sector, especially when  $v$  and  $w$  are not important.

**Proof of Theorem 2.** It goes by induction on  $|X|$ . Everything is easy when  $|X| = 1, 2$  or  $3$ . Suppose now that  $|X| > 3$ . Assume that there is a spherical triangle  $\Delta$  with vertices  $a, b, c$  with all of its angles at least  $2\alpha$  which is not contained in any sector  $E(z; \alpha)$  when  $z \in X$ . Then induction works as follows. Find first an  $\alpha$ -good path  $p = x_1 x_2 \dots x_n$  on  $X \setminus \{a, b, c\}$ . Define  $E(x_1; \alpha)$  as  $E(x_1; \alpha, x_2)$  if  $n > 1$  (that is,  $|X| > 4$ ), and as  $E(x_1; \alpha, c)$  if  $n = 1$ . As some vertex of  $\Delta$ , say  $a$ , is not contained in  $E(x_1; \alpha)$ ,  $ax_1 x_2 \dots x_n$  is an  $\alpha$ -good path. The angle of  $\Delta$  at  $a$  is at least  $2\alpha$  so either  $\angle bax_1$  or  $\angle cax_1 \geq \alpha$ . Suppose, say, that  $\angle bax_1 \geq \alpha$ . Then  $cbax_1 \dots x_n$  is an  $\alpha$ -good path on  $X$ , even  $\angle cba \geq 2\alpha$ .

So we can assume that no such triangle  $\Delta$  exists. If the diameter of  $X$  is at most  $60^\circ$ , then Corollary 1 applies and gives an  $\alpha_1$ -good path on  $X$  (where  $\alpha_1 = 9^\circ$ ). So suppose that the diameter, formed by the pair  $a, b \in X$  is at least  $60^\circ$ .

Observe now that  $\widehat{ab}$  is contained in no sector  $E(z; \alpha)$  with  $z \in X \setminus \{a, b\}$ . Indeed,  $\widehat{ab}$  is the longest side of the spherical triangle with vertices  $a, b, z$ . Then the largest angle of this triangle is at vertex  $z$ , and this largest angle is more than  $60^\circ > 2\alpha$ .

We claim now that no point of  $X$  is outside of the set

$$F := E(a; 2\alpha, b) \cup E(b; 2\alpha, a).$$

Assume the contrary and let  $c \in X \setminus F$ . All angles of the spherical triangle  $\Delta$  with vertices  $a, b, c$  are larger than  $2\alpha$ : the angle at  $c$  is at least  $60^\circ > 2\alpha$  as we just saw, while for the angles at  $a, b$  this follows from  $c \notin F$ . The triangle  $\Delta$  is not contained in any sector  $E(z; \alpha)$  for  $z \in X \setminus \{a, b\}$  as  $\widehat{ab}$  is not contained in such a sector. Further  $\Delta \subset E(a; \alpha)$  is impossible because  $c \notin E(a; 2\alpha, b)$ , and  $\Delta \subset E(b; \alpha)$  cannot hold for the same reason. Thus  $\Delta$  is not contained in any sector  $E(z, \alpha)$ ,  $z \in X$ , contradicting our previous assumption.

Consequently

$$X \subset F \cap \{x \in S^2 : |x - a|, |x - b| \leq |a - b|\}.$$

We observe that the set  $F \cap \{x \in S^2 : |x - a|, |x - b| \leq |a - b|\}$  is contained in the halfslab  $Q(a, b)$ . Then Theorem 5 applies and finishes the proof.  $\square$

#### 4. PROOF OF THEOREM 4

For  $x \in C(t)$  let  $x^*$  denote its radial projection (from the origin which is the center of  $S^2$ ) to  $P$ . Then  $X^*$ , the radial projection of  $X$ , is a finite set in the plane  $P$ . So by Theorem 1 there is a polygonal path  $p^* = x_1^* \dots x_n^*$  on  $X^*$  with all of its angles at least  $20^\circ$ . The next lemma implies that the path  $p = x_1 \dots x_n$  on  $X$  is  $\alpha(t)$ -good.

**Lemma 1.** *Assume  $a, b, c \in C(t)$ . Let the angle of the spherical triangle  $abc$  at  $c$  be  $\phi < 90^\circ$  and that of the (planar) triangle  $a^*b^*c^*$  at  $c^*$  be  $\phi^*$ . Then  $\sin \phi \geq t \sin \phi^*$  if  $\phi^* \leq 90^\circ$  and  $\sin \phi \geq t$  if  $\phi^* > 90^\circ$ .*



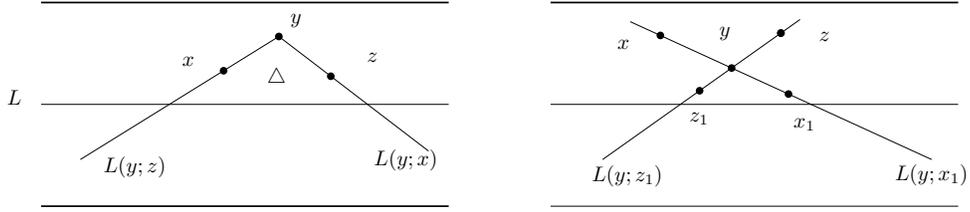


FIGURE 3. The two cases in Proposition 1

plane.  $H$  intersects the halfslab  $Q = Q(a, b)$  in the halfcircle  $L = L(c; a)$  whose endpoints are  $c$  and  $d = -c$ . Let  $e$  be the unit normal vector of  $H$ .

The *slope* of a pair  $x, y \in X$  is the angle between  $H$  and the 2-plane  $\text{lin}\{x, y\}$ . We denote this angle by  $\sigma(x, y)$ . Note that  $\sigma(x, y) \in [0, 90^\circ]$  always. We call a pair  $x, y \in X$  *steep* if  $\sigma(x, y) \geq 40^\circ$ .

If there is no steep pair in  $X$ , then one can construct an  $\alpha_2$ -good path on  $X$  with  $\alpha_2 = 100^\circ$  very easily. For  $x \in Q$  let  $h(x) = e \cdot x$  (the height of  $x$ ) and let  $\tau(x)$  be the angle between  $c$  and the midpoint of the half great circle  $L(e; x)$ . (Thus for instance,  $\tau(c) = 0$  and  $\tau(d) = 180^\circ$ ). Order the points of  $X$  by decreasing  $\tau(x)$  and call the resulting path the *decreasing path* of  $X$ . The following proposition shows that all angles of the decreasing path are at least  $180^\circ - 2 \cdot 40^\circ = 100^\circ$ .

**Proposition 1.** *Assume  $x, y, z \in Q$  and let  $\gamma$  be the angle of the spherical triangle with vertices  $x, y, z$  at vertex  $y$ . If  $\tau(x) \leq \tau(y) \leq \tau(z)$ , then  $\gamma \geq 180^\circ - \sigma(x, y) - \sigma(y, z)$ .*

**Proof.** We may assume by symmetry that  $h(y) \geq 0$ . To simplify the proof we also assume that  $\tau(x) < \tau(y) < \tau(z)$  and  $h(y) > 0$ . The general case follows from this by a simple limit argument.

Observe next that  $x$  can be replaced by any point (distinct from  $y$ ) on the arc  $\widehat{xy}$ . The same applies to  $z$ . So we assume that  $x$  and  $z$  are close to  $y$ , in particular,  $h(x), h(z) > 0$ .

The first and basic case is when  $z$  lies below the plane  $\text{lin}\{x, y\}$ . Then the half-circles  $L(y; x), L(y; z)$  and the great circle  $H \cap S^2$  delimit a spherical triangle  $\Delta$ , see Figure 3 left. The angle of  $\Delta$  at  $y$  coincides with  $\angle xyz$ , and its other two angles are  $\sigma(x, y)$  and  $\sigma(y, z)$ . Thus  $\angle xyz \geq 180^\circ - \sigma(x, y) - \sigma(y, z)$ , indeed.

The second case is when  $z$  is above the plane  $\text{lin}\{x, y\}$ . Choose points  $x_1$  and  $z_1$  in  $S^2$  close to, but distinct from,  $y$  so that  $y \in \widehat{xx_1}$  and  $y \in \widehat{zz_1}$ , see Figure 3 right. Then  $\tau(z_1) < \tau(y) < \tau(x_1)$ , and  $h(z_1), h(y), h(x_1)$  are all positive, and  $x_1$  lies below the plane  $\text{lin}\{z_1, y\}$ . The previous basic case applies now to  $z_1, y, x_1$  in place of  $x, y, z$ . Thus  $\angle z_1 y x_1 \geq 180^\circ - \sigma(z_1, y) - \sigma(y, x_1)$ . Here  $\angle z_1 y x_1 = \angle xyz$  and  $\sigma(z_1, y) = \sigma(y, z)$  and  $\sigma(y, x_1) = \sigma(x, y)$ . Consequently  $\angle xyz \geq 180^\circ - \sigma(x, y) - \sigma(y, z)$  again.  $\square$

We remark that the decreasing path method is applicable to any subset, say  $Y$ , of  $X$  that contains no steep pair. In that case the decreasing path on  $Y$  is  $\alpha_2$ -good.

## 6. PROOF OF THEOREM 5

For  $u, v \in L$  with  $\tau(u) < \tau(v)$  we define

$$T(u, v) = \{x \in Q : \tau(u) \leq \tau(x) \leq \tau(v)\}.$$

Now let  $u, v \in L$  be two points with  $\tau(v) - \tau(u) = 30^\circ$ . Thus  $c, u, v, d$  come on  $L$  in this order.

**Proposition 2.** *If  $x, y \in X$  with  $x \in T(c, u)$  and  $y \in T(v, d)$ , then  $\sigma(x, y) < 35^\circ$ .*

**Proof.** The spherical cotangent formula (see spherical trigonometry on wikipedia, for instance) says that  $\cos c \cos B = \cot a \sin c - \cot A \sin B$  where  $a, b, c$  are the sides, and  $A, B, C$  the opposite angles of the spherical triangle. With  $b = 10^\circ$ ,  $c = 15^\circ$ ,  $B = 90^\circ$  this shows that the angle in question is at most  $\operatorname{arccot}(\cot 10^\circ \sin 15^\circ) = 34.2656\dots$ , indeed smaller than  $35^\circ$ .  $\square$

Define now  $t = \sin 15^\circ \cos 10^\circ = 0.25488\dots$  and set  $\alpha_3 \in (0, 90^\circ)$  by

$$\sin \alpha_3 = t \sin 20^\circ = 0.087176\dots$$

and  $\alpha_3 > 5^\circ$  follows.

**Lemma 2.** *Assume again that  $u, v \in L$  with  $\tau(v) - \tau(u) = 30^\circ$ , and that  $\tau(u) \in [90^\circ, 120^\circ]$  and further that there is no steep pair from  $X$  in  $T(u, v)$ . Set  $Y = X \cap T(c, v)$ . Then there is an  $\alpha_3$ -good path  $y_1 \dots y_m$  on  $Y$  such that  $\angle xy_1y_2 > 5^\circ$  for every  $x \in T(v, d)$ .*

**Proof.** The conditions imply that  $\tau(v) \leq 150^\circ$ . Then a simple computation shows that  $Y$  is contained in a cap  $C(t)$  with center  $z \in L$  where  $t = \sin 15^\circ \cos 10^\circ$ . This value for  $t = \cos b$  comes from the spherical cosine theorem  $\cos b = \cos c \cos a + \sin c \sin b \cos B$  with  $B = 90^\circ$ ,  $c = 75^\circ$ ,  $a = 10^\circ$ . Project  $Y$  radially to the plane  $P$  that touches  $S^2$  at  $z$ . We get a finite set  $Y^*$  in  $P$ . The unit circle  $S \subset P$  is centered at  $z$ . Let  $R = R_1 \cup R_2 \subset S$  be the restriction in  $P$  where the line  $H \cap P$  halves both  $R_1$  and  $R_2$ . The radial projection  $c^*$  of  $c$  lies in  $P$  and we choose the names so that  $c^* \in R_1$ .

According to Theorem 3, there is a  $20^\circ$ -good path  $y_1^*y_2^* \dots y_m^*$  on  $Y^*$  which is  $R$ -avoiding, that is, not both end directions are in the same  $R_i$ . Here we choose the names so that  $\overline{y_2^*y_1^*} \notin R_1$ . Theorem 4 implies that  $y_1 \dots y_m$  is an  $\alpha_3$ -good path on  $Y \subset S^2$ .

We have to check that  $\angle xy_1y_2 > 5^\circ$  for every  $x \in T(v, d)$ . We distinguish two cases.

**Case 1.** When  $y_1, y_2$  is not a steep pair. Then, as is easy to check, the angle between the line spanned by  $y_1^*, y_2^*$  and the line  $H \cap P$  is smaller than

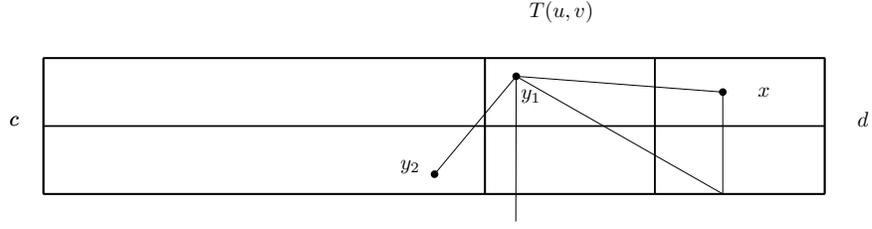


FIGURE 4. Case 2a

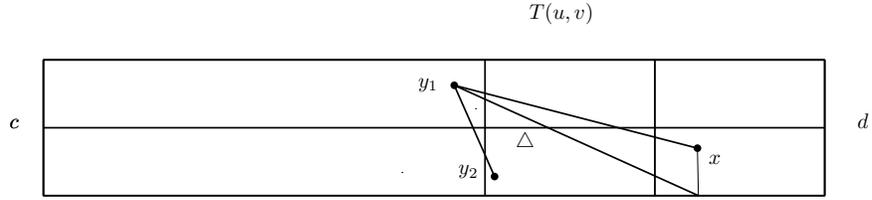


FIGURE 5. Case 2b

$40^\circ$ , so  $\overline{y_2^* y_1^*} \in R_2$ . Then  $\tau(y_2) < \tau(y_1) \leq \tau(x)$ . Proposition 1 shows that  $\angle xy_1 y_2 \geq 180^\circ - 90^\circ - 40^\circ > 5^\circ$ .

**Case 2.** When  $y_1, y_2$  is a steep pair. Then at least one of  $y_1$  and  $y_2$  is in  $T(c, u)$ . We assume by symmetry that  $h(y_1) \geq h(y_2)$ . Clearly  $\tau(x) > \tau(y_1), \tau(y_2)$ . There are two subcases.

**Case 2a.** When  $\tau(y_2) \leq \tau(y_1)$ . Then  $y_2 \in T(c, u)$  and the angle in question decreases if  $x$  is pushed down to  $h(x) = -\sin 10^\circ$  while keeping  $\tau(x)$  the same. The halfcircle  $L(e; y_1)$  cuts the angle  $\angle xy_1 y_2$  into two parts, see Figure 4. Assume that  $\angle xy_1 y_2 \leq 5^\circ$ , then both parts are at most  $5^\circ$ . The spherical cosine theorem implies then that  $\tau(y_1) - \tau(y_2) \leq 5^\circ$  and  $\tau(x) - \tau(y_1) \leq 5^\circ$ , contradicting  $\tau(x) - \tau(y_2) \geq 30^\circ$ .

**Case 2b.** When  $\tau(y_1) \leq \tau(y_2)$ . Then  $y_1 \in T(c, u)$ . The angle in question decreases again if  $x$  is pushed down to  $h(x) = -\sin 10^\circ$  while keeping  $\tau(x)$  the same. Note that while  $x$  is pushed down,  $y_1, y_2$  and  $x$  do not become coplanar as otherwise  $y_1, x$  would become a steep pair contradicting Proposition 2. Let  $\Delta$  be the spherical triangle delimited by  $L, L(x; y_1), L(y_2; y_1)$ , see Figure 5. The angle of  $\Delta$  at vertex  $y_1$  equals  $\angle y_2 y_1 x$ . The other two angles of  $\Delta$  are  $180^\circ - \sigma(y_1, y_2) \leq 140^\circ$  because  $y_1, y_2$  is a steep pair, and  $\sigma(y_1, x) < 35^\circ$  by Proposition 2. Thus  $\angle y_2 y_1 x > 180^\circ - (140^\circ + 35^\circ) = 5^\circ$ .  $\square$

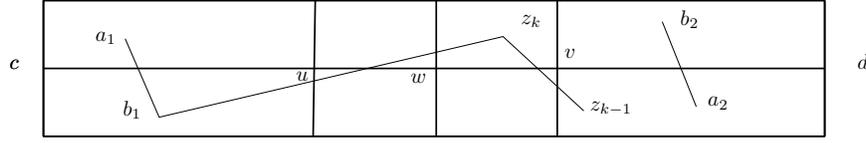


FIGURE 6. Part of the constructed path

**Proof of Theorem 5.** We have to consider two cases.

**Case 1.** There is no steep pair in  $T(u, d)$  where  $\tau(u) = 120^\circ$ . We can apply Lemma 2 to  $T(u, v)$ : setting  $Y = X \cap T(c, v)$  there is no steep pair from  $Y$  in  $T(u, v)$ . We get an  $\alpha_3$ -good path  $y_1 \dots y_m$  on  $Y$ . Let  $x_1 \dots x_k$  (where  $m + k = n$ ) be the decreasing path on the points of  $X \setminus Y$  which is an  $\alpha_2$ -good path on  $X \setminus Y$  ( $\alpha_2 = 100^\circ$ ). We claim that  $x_1 \dots x_k y_1 \dots y_m$  is an  $\alpha$ -good path on  $X$ . We only have to check its angles at  $x_k$  and  $y_1$ . The angle at  $y_1$  is at least  $\alpha$  by Lemma 2. The pair  $x_{k-1}x_k$  is not steep and  $\tau(y_1) \leq \tau(x_k) < \tau(x_{k-1})$ . Then Proposition 1 shows that the angle at  $x_k$  is at least  $180^\circ - 90^\circ - 40^\circ > 5^\circ$ .

The same method works when there is no steep pair in  $T(c, v)$  where  $\tau(v) = 60^\circ$ .

Define now  $u, v, w \in L$  by  $\tau(u) = 60^\circ$ ,  $\tau(w) = 90^\circ$ , and  $\tau(v) = 120^\circ$ . We are left with the following case.

**Case 2.** There is a steep pair  $a_1, b_1 \in X \cap T(c, u)$  and a steep pair  $a_2, b_2 \in X \cap T(v, d)$ . By swapping names if necessary we may assume that  $\tau(a_1) \leq \tau(b_1)$  and that  $\tau(b_2) \leq \tau(a_2)$ . Set  $Y = T(c, w) \cap X \setminus \{a_1, b_1\}$  and  $Z = T(w, d) \cap X \setminus \{a_2, b_2\}$ . Lemma 2 applies to  $T(w, v)$  and  $Y$  because there is no steep pair from  $Y$  in  $T(w, v)$  (actually, no point of  $Y$  there at all). We get an  $\alpha_3$ -good path  $y_1 \dots y_m$  on  $Y$  such that  $\angle b_2 y_1 y_2 > 5^\circ$ . The same lemma applies to  $Z$  and  $T(u, w)$  giving an  $\alpha_3$ -good path  $z_1 \dots z_k$  on  $Z$  with  $\angle b_1 z_k z_{k-1} > 5^\circ$ . Here  $m + 4 + k = n$ , and the case when either  $Y$  or  $Z$  is empty or singleton is easy.

We claim finally that  $z_1 \dots z_k b_1 a_1 a_2 b_2 y_1 \dots y_m$  is an  $\alpha$ -good path, see Figure 6. We have to check the angles at  $a_1, b_1$  and also at  $a_2, b_2$  but the latter would follow by symmetry. Observe that  $\tau(a_1) < \tau(b_1) \leq \tau(z_k)$  and  $\sigma(z_k, b_1) < 35^\circ$ . Then Proposition 1 shows that the angle at  $b_1$  is at least  $180^\circ - 90^\circ - 35^\circ > 5^\circ$ . Finally, the pair  $a_1, b_1$  is steep and  $\tau(a_1) \leq \tau(b_1)$ , and  $\tau(a_2) - \tau(a_1) \geq 60^\circ > 30^\circ$ . The spherical triangle with vertices  $b_1, a_1, a_2$  satisfies the same conditions as the triangle  $y_2, y_1, x$  in Case 2b in the proof of Lemma 2. The same argument shows then that the angle at  $a_1$  is larger than  $5^\circ$ .  $\square$

## 7. HIGHER DIMENSIONS

In the paper [1] we proved the higher dimension analogue of Theorem 1 in the following form.

**Theorem 6.** *For every  $d \geq 2$  there is a positive  $\alpha_d$  such that for every finite set of points  $X \subset \mathbb{R}^d$  there exists an  $\alpha_d$ -good path on  $X$ .*

Here the value of  $\alpha_d$  is  $\pi/80$  (for  $d > 2$ ), see [1]. The proof of Theorem 2 goes through in higher dimensions without any real difficulty, and gives the following result.

**Theorem 7.** *There exists a constant  $\alpha > 0$  such that for every  $d \geq 2$  and for every finite set of points  $X \subset S^d$  there exists an  $\alpha$ -good path on  $X$ .*

We omit the details.

## 8. OPEN PROBLEMS

The same question comes up in more general settings. For instance when  $X$  is a finite subset of the boundary of a convex body (compact convex set with nonempty interior)  $K \subset \mathbb{R}^3$  (and  $\mathbb{R}^d$ ,  $d \geq 2$ ). Again there is a shortest path  $\widehat{ab}$ , the geodesic connecting  $a, b$  in  $\partial K$ . So an ordering  $x_1, \dots, x_n$  of the elements of a finite set  $X \subset \partial K$  gives rise to a path on  $\partial K$ . The angle at  $x_i$  is defined in the usual way. Extending Theorem 2 would mean that there is  $\alpha > 0$  such that for every convex body  $K \subset \mathbb{R}^3$  and for every finite  $X \subset \partial K$  there is an ordering such that every angle of the corresponding path is at least  $\alpha$ . We suspect that such a universal  $\alpha$  exists.

The same problem can be considered on a smooth or piecewise linear manifold. We remark however that in the hyperbolic plane there are triangles with all three angles very small. The same thing occurs on other 2-dimensional manifolds for instance when they have three long "tentacles".

Here comes an abstract or combinatorial version of the same problem. Let  $X$  be a finite set. For every three elements  $a, b, c$  in  $X$  the *combinatorial angle* is a real number  $\angle abc \in [0, 1]$  satisfying the following conditions:

- $\angle abc = \angle cba$  for all  $a, b, c \in X$ , (symmetry),
- $\angle abc + \angle cbd \geq \angle abd$  for all  $a, b, c, d \in X$ , (triangle inequality),
- $\angle abc + \angle bca + \angle cab \geq 1$  for all  $a, b, c \in X$ , (no small triangle).

The question is now whether there exists an  $\varepsilon > 0$  such that for every finite set  $X$  with angles satisfying these three conditions there is an ordering  $x_1, \dots, x_n$  of the elements of  $X$  such that  $\angle x_{i-1}x_i x_{i+1} \geq \varepsilon$  for every  $2 \leq i \leq n-1$ .

It turns out that for every  $n$  there exists a largest number  $\varepsilon = \varepsilon(n)$  such that if  $|X| = n$  there exist an  $\varepsilon$ -good path on  $X$ . In Lemma 3 below we show that if  $\varepsilon(n)$  is not zero, then  $\varepsilon(n) = \frac{1}{k}$  for some integer  $k$ . One can check the case  $n = 4$  directly and show that  $\varepsilon(4) = \frac{1}{6}$ .

Let  $X$  be a finite set and let  $S$  be a subset of the combinatorial angles of  $X$ . We say that  $S$  is *blocking* if any path on  $X$  has an angle in  $S$ . Let  $\angle_S abc$  be the smallest number  $t$  such that there are  $b_0, \dots, b_t \in X$ , where  $b_0 = a, b_t = c$  and all the combinatorial angles  $\angle b_i b_{i+1}$  for  $i = 0, \dots, t-1$  are in  $S$ . It is possible that  $\angle_S abc = \infty$ . Let  $\alpha(S) = \min_{a,b,c \in X} (\angle_S abc + \angle_S bca + \angle_S cab)$ . It is possible that  $\alpha(S) = \infty$ . Define  $\alpha(n) = \max_{|X|=n, S \text{ is blocking}} \alpha(S)$ . Clearly  $\alpha(n)$  is an integer, or  $\infty$ .

**Lemma 3.** *If  $\alpha(n)$  is an integer, then  $\varepsilon(n) = \frac{1}{\alpha(n)}$ .*

**Proof.** Let  $S$  be the blocking set where  $\alpha(S) = \alpha(n)$ . Then the abstract combinatorial geometry with  $\angle abc = \frac{\angle_S abc}{\alpha(S)}$  shows that  $\varepsilon(n) \leq \frac{1}{\alpha(S)}$  since all the angles in  $S$  have that size, and  $S$  is blocking each path.

Assume that  $\varepsilon(n) < \frac{1}{\alpha(n)}$ . Then for some abstract geometry  $X$  every path contains an angle smaller than  $\frac{1}{\alpha(n)}$ . Let  $S$  be the set of all angles smaller than  $\frac{1}{\alpha(n)}$ . By definition  $S$  is blocking. By the triangle inequality  $\angle abc < \frac{\angle_S abc}{\alpha(n)}$  for any angle. Let  $abc$  be the triangle where  $\alpha(S) = \angle_S abc + \angle_S bca + \angle_S cab$ . Obviously  $\angle abc + \angle bca + \angle cab < \frac{\alpha(S)}{\alpha(n)} \leq 1$  which is a contradiction.  $\square$

**Acknowledgements.** Research of both authors were partially supported by ERC Advanced Research Grant 267165 (DISCONV). The first author was also supported by Hungarian National Research Grant K 111827.

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