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On $\gamma - R_0$ and $\gamma - R_1$ spaces

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ON γ - R_0 AND γ - R_1 SPACES

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Abstract. In this paper, we investigate further properties of γ - R_0 and γ - R_1 spaces due to Ekici.

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1. INTRODUCTION AND PRELIMINARIES

The separation axioms R_0 and R_1 were introduced and studied by N. A. Shan in [22] and C. T. Yang [23]. In 1963, they were rediscovered by A. S. Davis [4]. Then, their some properties are obtained by some authors [6, 7, 15, 17]. The notion of b -open (or sp -open) sets was introduced by Andrijević [1] and Dontchev and Przemski [5] independently of each other in 1996. Since then it has been investigated in the literature (see [9, 13, 14, 18, 19]). Ekici [9, 10] introduced γ - R_0 and γ - R_1 spaces and obtained some properties of them. In this paper, we investigate further properties of γ - R_0 and γ - R_1 spaces due to Ekici [9, 10].

In this paper, by (X, τ) and (Y, φ) (or X and Y) we always mean topological spaces on which no separation axioms are assumed, unless otherwise mentioned. For a subset A of (X, τ) , $\text{Cl}(A)$ and $\text{Int}(A)$ represent the closure of A and the interior of A with respect to τ , respectively.

Definition 1.1. Let (X, τ) be a topological space. A subset A is called

- (a) b -open [1] or sp -open [5] or γ -open [14] if $A \subset \text{Int}(\text{Cl}(A)) \cup \text{Cl}(\text{Int}(A))$,
- (b) α -open [20] if $A \subset \text{Int}(\text{Cl}(\text{Int}(A)))$.

The family of all b -open (resp., α -open) sets in a topological space (X, τ) is denoted by $BO(X)$ (resp., $\alpha(X)$).

Definition 1.2. The complement of a b -open set is called b -closed [1].

Similarly, the family of all b -closed sets in a topological space (X, τ) is denoted by $BC(X)$.

Definition 1.3. The intersection of all b -closed sets containing A is called the b -closure [1] of A and is denoted by $b\text{Cl}(A)$.

The union of all b-open sets contained in A is called the b-interior of A and is denoted by $\text{bInt}(A)$. The following lemma is useful in the sequel:

Lemma 1.1 ([1]). *Let A be a subset of a space (X, τ) . Then the following properties hold:*

- (a) $\text{bCl}(A) = \text{sCl}(A) \cap \text{pCl}(A)$,
- (b) $\text{bInt}(A) = \text{sInt}(A) \cup \text{pInt}(A)$,
- (c) $x \in \text{bCl}(A)$ if and only if $A \cap U \neq \emptyset$ for every $BO(X, x)$,
- (d) $\text{bCl}(A) = A \cup [\text{Int}(\text{Cl}(A)) \cap \text{Cl}(\text{Int}(A))]$,
- (e) $\text{bInt}(A) = A \cap [\text{Cl}(\text{Int}(A)) \cup \text{Int}(\text{Cl}(A))]$.

The family of all b-open sets containing x of X will be denoted by $BO(X, x)$. The following basic properties of the b-closure are useful in the sequel:

Lemma 1.2 ([11]). *Let A and B be subsets of a space (X, τ) . The following properties hold:*

- (a) If $A \subset B$, then $\text{bCl}(A) \subset \text{bCl}(B)$,
- (b) $\text{bCl}(X \setminus A) = X \setminus \text{bInt}(A)$,
- (c) $A \in BC(X, \tau)$ if and only if $A = \text{bCl}(A)$.

Lemma 1.3 ([1]). *The following assertions hold:*

- (a) The union of any family of b-open sets is a b-open set.
- (b) The intersection of an open set and a b-open set is a b-open set.

Definition 1.4. [10] Let X be a topological space and $S \subset X$. The γ -kernel of S , denoted by $\gamma\text{-ker}(S)$, is defined to be the set $\gamma\text{-ker}(S) = \cap \{U \in BO(X, \tau) \mid S \subset U\}$.

Remark 1.1. In [3], the set $\gamma\text{-ker}(S)$ has been denoted by S^{A_b} .

Lemma 1.4 ([10]). *Let (X, τ) be a topological space and A be a subset of X . Then $A^{A_b} = \{x \in X \mid \text{bCl}(\{x\}) \cap A \neq \emptyset\}$.*

2. PRESERVATION THEOREMS

Definition 2.1. A topological space (X, τ) is called $\gamma\text{-}R_0$ [10] if its every b-open set contains the b-closure of each of its singletons.

Theorem 2.1 ([10]). *A topological space (X, τ) is a $\gamma\text{-}R_0$ space if and only if for any x and y in X , $\text{bCl}(\{x\}) \neq \text{bCl}(\{y\})$ implies $\text{bCl}(\{x\}) \cap \text{bCl}(\{y\}) = \emptyset$.*

Definition 2.2. A function $f: (X, \tau) \rightarrow (Y, \varphi)$ is called

- (a) b-continuous [14] (resp., α -continuous [16]) if $f^{-1}(V)$ is b-open (resp., α -open) in (X, τ) for every open set V of (Y, φ) ;
- (b) α -open [16] if $f(U)$ is α -open in (Y, φ) for every open set U of (X, τ) .

Lemma 2.1 ([14]). *Let $f: (X, \tau) \rightarrow (Y, \varphi)$ be an α -continuous and α -open function. Then the inverse image of each b-open set in Y is b-open in X .*

Definition 2.3. A function $f: (X, \tau) \rightarrow (Y, \varphi)$ is called strongly γ -closed [12] if $f(F)$ is γ -closed in (Y, φ) for every γ -closed set F of (X, τ) .

Theorem 2.2. *If (X, τ) is a γ - R_0 space and $f: (X, \tau) \rightarrow (Y, \varphi)$ is an α -continuous, α -open and b -closed surjection, then (Y, φ) is a γ - R_0 space.*

Proof. Let V be a b -open set of Y and y any point of V . Since f is α -continuous and α -open, $f^{-1}(V)$ is a b -open set in (X, τ) , by Lemma 2.1. Since (X, τ) is γ - R_0 , for a point $x \in f^{-1}(\{y\})$ by Definition 2.1, $bCl(\{x\}) \subset f^{-1}(V)$. The b -closeness of f implies that $bCl(\{y\}) = bCl(\{f(x)\}) \subset f(bCl(\{x\})) \subset V$. Therefore, (Y, φ) is γ - R_0 . \square

Definition 2.4. A function $f: (X, \tau) \rightarrow (Y, \varphi)$ is called quasi γ -closed [12] if $f(F)$ is closed in (Y, φ) for every γ -closed set F of (X, τ) .

Theorem 2.3. *If (X, τ) is a γ - R_0 space and $f: (X, \tau) \rightarrow (Y, \varphi)$ is a strongly b -closed and b -continuous surjection, then (Y, φ) is an R_0 space.*

Proof. The proof is similar to that of Theorem 2.2 and is thus omitted. \square

3. γ - R_1 SPACES

Definition 3.1. A topological space (X, τ) is called γ - R_1 [9] if for x and y in X with $bCl(\{x\}) \neq bCl(\{y\})$, there exist disjoint b -open sets U and V such that $bCl(\{x\})$ is a subset of U and $bCl(\{y\})$ is a subset of V .

Proposition 3.1. *Every γ - R_1 space is γ - R_0 .*

Proof. Let U be a b -open set such that $x \in U$. If $y \notin U$, since $x \notin bCl(\{y\})$, we have $bCl(\{x\}) \neq bCl(\{y\})$. So, there exists a b -open set V such that $bCl(\{y\}) \subset V$ and $x \notin V$, which implies $y \notin bCl(\{x\})$. Hence $bCl(\{x\}) \subset U$. Therefore, (X, τ) is γ - R_0 . \square

Remark 3.1. The converse of Proposition 3.1 need not be true as shown in the following example.

Example 3.1. Let (X, τ) be a topological space as in [2, Example 4.16], that is, p be a fixed point of (X, τ) with τ as the cofinite topology on X . If it meant clearly, $\tau = \{\emptyset, X, U\}$ with $U \subset (X \setminus \{p\})$ and $X \setminus U$ finite. One can obtain $BO(X) = \{\emptyset, X, U, A\}$ such that for each $A \subset U$. Since $bCl(\{x\}) = \{x\}$ for every $x \in X$, we obtain that (X, τ) is γ - R_0 by using Theorem 2.1. On the other hand, one can easily show that (X, τ) is not γ - R_1 by using Definition 3.1.

Theorem 3.1 ([9]). *A topological space (X, τ) is γ - R_1 if and only if for $x, y \in X$, $\{x\}^{Ab} \neq \{y\}^{Ab}$, there exist disjoint b -open sets U and V such that $bCl(\{x\}) \subset U$ and $bCl(\{y\}) \subset V$.*

Definition 3.2. A set U in a topological space (X, τ) is called b -neighborhood [11] of x if U contains a b -open set V such that $x \in V$.

Theorem 3.2. *A topological space (X, τ) is γ - R_1 if and only if the inclusion $x \in X \setminus \text{bCl}(\{y\})$ implies that x and y have disjoint b-open neighborhoods.*

Proof. Necessity: Let $x \in X \setminus \text{bCl}(\{y\})$. Then $\text{bCl}(\{x\}) \neq \text{bCl}(\{y\})$ and x, y have disjoint b-open neighborhoods.

Sufficiency: First, we show that (X, τ) is γ - R_0 . Let U be a b-open set and $x \in U$. Suppose that $y \notin U$. Then, $\text{bCl}(\{y\}) \cap U = \emptyset$ and $x \notin \text{bCl}(\{y\})$. There exist b-open sets U_x and U_y such that $x \in U_x$, $y \in U_y$ and $U_x \cap U_y = \emptyset$. Hence, $\text{bCl}(\{x\}) \subset \text{bCl}(U_x)$ and $\text{bCl}(\{x\}) \cap U_y \subset \text{bCl}(U_x) \cap U_y = \emptyset$. Therefore, $y \notin \text{bCl}(\{x\})$. Consequently, $\text{bCl}(\{x\}) \subset U$ and (X, τ) is γ - R_0 . Next, we show that (X, τ) is γ - R_1 . Suppose that $\text{bCl}(\{x\}) \neq \text{bCl}(\{y\})$. Then, we can assume that there exists $z \in \text{bCl}(\{x\})$ such that $z \notin \text{bCl}(\{y\})$. There exist b-open sets V_z and V_y such that $z \in V_z$, $y \in V_y$ and $V_z \cap V_y = \emptyset$. Since $z \in \text{bCl}(\{x\})$, $x \in V_z$. Since (X, τ) is γ - R_0 , we obtain $\text{bCl}(\{x\}) \subset V_z$, $\text{bCl}(\{y\}) \subset V_y$ and $V_z \cap V_y = \emptyset$. This shows that (X, τ) is γ - R_1 . \square

Corollary 3.1. *For a topological space (X, τ) , the following properties are equivalent:*

- (1) (X, τ) is a γ - R_1 space,
- (2) $\text{bCl}(\{x\}) \neq \text{bCl}(\{y\})$ implies that x and y have disjoint b-open neighborhoods.

Proof. The implication (1) \Rightarrow (2) is obvious.

(2) \Rightarrow (1): Suppose that $x \in X \setminus \text{bCl}(\{y\})$. Then, $\text{bCl}(\{x\}) \neq \text{bCl}(\{y\})$ and by (2) x and y have disjoint b-open neighborhoods. By Theorem 3.2, (X, τ) is γ - R_1 . \square

The following notions are due to Park [21]. A point x of X is called a b- θ -cluster point of A if $\text{bCl}(U) \cap A \neq \emptyset$ for every $U \in \text{BO}(X, x)$. The set of all b- θ -cluster points of A is called the b- θ -closure of A and is denoted by $\text{bCl}_\theta(A)$. A subset A is said to be b- θ -closed if $A = \text{bCl}_\theta(A)$. The complement of a b- θ -closed set is said to be b- θ -open.

Lemma 3.1. *For any subset A of a topological space (X, τ) , $\text{bCl}(A) \subseteq \text{bCl}_\theta(A)$.*

Theorem 3.3. *A topological space (X, τ) is a γ - R_1 space if and only if for each $x \in X$, $\text{bCl}_\theta(\{x\}) = \text{bCl}(\{x\})$.*

Proof. Necessity: Let (X, τ) be γ - R_1 and x any point of X . Assume that $y \in X \setminus \text{bCl}(\{x\})$. By Theorem 3.2, there exist disjoint b-open sets U and V such that $x \in U$ and $y \in V$. Thus, we have $\{x\} \cap \text{bCl}(V) \subset U \cap \text{bCl}(V) = \emptyset$ and hence $y \notin \text{bCl}_\theta(\{x\})$. Therefore, we obtain $\text{bCl}_\theta(\{x\}) \subseteq \text{bCl}(\{x\})$. So, by using Lemma 3.1, we have $\text{bCl}_\theta(\{x\}) = \text{bCl}(\{x\})$.

Sufficiency: Let x, y be distinct points of X and $y \in X \setminus \text{bCl}(\{x\})$. Then $y \in X \setminus \text{bCl}_\theta(\{x\})$ and hence there exists a b-open neighborhood V of y such that $\text{bCl}(V) \cap \{x\} = \emptyset$. Then V and $X \setminus \text{bCl}(V)$ are disjoint b-open neighborhoods of y and x , respectively. By Theorem 3.2, (X, τ) is γ - R_1 . \square

The following notion is due to Ekici and Caldas [13].

Definition 3.3. A topological space (X, τ) is said to be b -regular [13] if for each b -closed set F and each point $x \in X \setminus F$, there exist disjoint b -open sets U and V such that $x \in U$ and $F \subset V$.

Now, we can give a characterization of b -regular spaces.

Theorem 3.4. For a topological space (X, τ) , the following properties are equivalent:

- (1) (X, τ) is b -regular,
- (2) $bCl_\theta(A) = bCl(A)$ for every subset A of X ,
- (3) $bCl_\theta(A) = A$ for every b -closed subset A of X .

Proof. (1) \Rightarrow (2): Since $bCl(A) \subseteq bCl_\theta(A)$ by Lemma 3.1, we will show that $bCl_\theta(A) \subseteq bCl(A)$. Assume that $x \notin bCl(A)$. Since (X, τ) is b -regular, there exist disjoint b -open sets U and V such that $x \in U$ and $bCl(A) \subset V$. Hence $A \cap bCl(U) \subset bCl(A) \cap bCl(U) = \emptyset$. This implies $x \notin bCl_\theta(A)$.

(2) \Rightarrow (3): Let A be a b -closed subset of X , then we have $A = bCl(A)$ and $bCl_\theta(A) = A$.

(3) \Rightarrow (1): Let V be a b -open set containing x in X . Hence $X \setminus V$ is b -closed. By (3), $X \setminus V = bCl_\theta(X \setminus V)$. Then there exists an $U \in BO(X, x)$ such that $bCl(U) \cap (X \setminus V) = \emptyset$. This implies $bCl(U) \subset V$. Consequently, the proof is completed. \square

Corollary 3.2. Every b -regular space is a γ - R_1 space.

Proof. This immediately follows from Theorems 3.3 and 3.4. \square

Definition 3.4. Let ∇ be a filter base of a topological space (X, τ) .

- (1) The b -adherence (resp., b - θ -adherence) of a filter base ∇ , denoted by $ad_b \nabla$ (resp., θ - $ad_b \nabla$), is defined by $\bigcap \{bCl(V) \mid V \in \nabla\}$ (resp., $\bigcap \{bCl_\theta(V) \mid V \in \nabla\}$),
- (2) ∇ b -converges [8] (resp., ∇ b - θ -converges) to x if for each b -open set U containing x , there is $V \in \nabla$ such that $V \subset U$ (resp., $V \subset bCl(U)$).

Theorem 3.5. If a topological space (X, τ) is γ - R_1 , then $ad_b \nabla \subset bCl(\{x\})$ for each filter base ∇ b - θ -converging to $x \in X$.

Proof. Let (X, τ) be a γ - R_1 space, $x \in X$, and ∇ be a filter base in X b - θ -converging to x . If $ad_b \nabla = \emptyset$, then the assertion of the theorem holds trivially. Assume that $y \in ad_b \nabla$ and $y \in X \setminus bCl_\theta(\{x\})$. Then there exists a b -open set U containing y such that $x \in X \setminus bCl(U)$. Since ∇ b - θ -converging to x , there exists $V \in \nabla$ such that $V \subset bCl(X \setminus bCl(U))$. This implies that $V \cap U = \emptyset$ which contradicts the assumption that $y \in ad_b \nabla$. Thus $y \in bCl_\theta(\{x\})$ and $ad_b \nabla \subset bCl_\theta(\{x\})$. Since (X, τ) is γ - R_1 , by Theorem 3.3 we obtain $ad_b \nabla \subset bCl(\{x\})$. \square

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