

EFFECT OF STREAMWISE AND TRANSVERSE DAMPING ON FLOW AROUND AN ELASTICALLY SUPPORTED CYLINDER

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ABSTRACT

In this paper flow around a circular cylinder free to move in two-degrees-of-freedom is investigated numerically in the Reynolds number range of Re=80-240. Reynolds number is varied with the reduced velocity U^* using Re=34.74 U^* and the mass ratio is fixed at $m^*=10$. The main purpose of the study is to investigate the effects of streamwise and transverse damping values (ζ_x and ζ_y). Computations are carried out for different Re and U^* pairs to investigate the separate effects of ζ_x and ζ_y . Although ζ_x has a negligible effect on flow parameters, at small transverse damping values a significant increase is identified in the mechanical energy transfer E and a substantial drop occurs in the root-mean-square and time-mean values of drag (C_{Drms} and C_{Dmean}). Energy transfer is influenced mainly by transverse cylinder motion. Changes in the vortex structure are also identified. In addition, computations are carried out for different ζ_{v} ($\zeta_{x}=0$) values with varying Re and U*. Two-branch cylinder response and small E are observed for $\zeta_{v}=0.001$ while high E is observed at larger but still low ζ_y values. At high ζ_y all quantities investigated become small. C_{Drms} and C_{Dmean} curves plotted against Re shift downwards with increasing ζy.

Keywords: circular cylinder, damping coefficient, mechanical energy transfer, natural frequency, numerical simulation

NOMENCLATURE

b	[kg/s]	damping
C_D	[-]	drag coefficient, $2F_D/(\rho U_{\infty}^2 d)$
C_L	[-]	lift coefficient, $2F_L/(\rho U_{\infty}^2 d)$
d	[m]	cylinder diameter, length scale
F_D	[N/m]	drag per unit length of cylinder
F_L	[N/m]	lift per unit length of cylinder
F_N	[-]	reduced natural frequency, $f_N d/U_\infty$
f_N	[1/s]	natural frequency of system
k	[N/m]	spring stiffness

Κ	[-]	non-dimensional natural
		frequency, $f_N d^2 / v$
т	[kg/m]	
m^*	[-]	mass ratio, $4m/(d^2\pi\rho)$
R	[-]	radius, non-dimensionalised by d
Re	[-]	Reynolds number, $U_{\infty}d/v$
St_0	[-]	dimensionless vortex shedding
		frequency for a stationary cylinder
t	[-]	time, non-dimensionalised by
		d/U_{∞}
U_∞	[m/s]	free stream velocity, velocity scale
U^*	[-]	reduced velocity, $U_{\infty}/(f_N d)$
<i>x</i> , <i>y</i>	[-]	Cartesian coordinates, non-
		dimensionalised by d
x_0, y_0	[-]	cylinder displacement in x and y
		directions, non-dimensionalised
		by d
ζ	[-]	structural damping coefficient,
		$b/(2\sqrt{mk})$
v	$[m^2/s]$	
ρ	$[kg/m^3]$	
,	L 0 · · J	5

Subscripts and Superscripts

- L, D lift, drag
- rms root-mean-square value
- mean time-mean values
- *x*, *y* streamwise and transverse directions
- 1,2 on cylinder surface, at outer boundary of domain
- 0 refers to cylinder response (x_0, y_0) or to a stationary cylinder (St_0)

1. INTRODUCTION

Flow around an elastically supported circular cylinder has been thoroughly investigated using both numerical and experimental approaches. Vortices shedding periodically from the body can cause high amplitude vibrations that can result in serious damage to the structure (e.g. collapse of the Tacoma Narrows Bridge, 1940). On the other hand, these

vibrations can be beneficial. Bernitsas et al. [1] studied the possibilities of energy harvesting from an oscillating body placed in a free stream.

The vibration can take place either streamwise with or transverse to the main stream, or both. Several articles deal with one-degree-of-freedom (1DoF) motion. In their experimental study Khalak and Williamson [2] investigated transverse-only motion at low mass-damping values $m^*\zeta$, where m^* is the mass ratio and ζ is the structural damping coefficient. They found initial, upper and lower branches, where the highest oscillation amplitude belongs to the upper branch. In contrast, Feng [3] found two-branch response (initial and lower branches) for high $m^*\zeta$ cases. Klamo et al. [4] analysing the damping effects for 1DoF transverseonly vibration found that $m^{*\zeta}$ alone is insufficient to predict the branching behaviour of the cylinder as it is also affected by the Reynolds number $\text{Re}=U_{\infty}d/v$, where U_{∞} is the free stream velocity, d is the cylinder diameter and v is the kinematic viscosity of the fluid. The effect of structural damping coefficient for transverse-only motion was also studied numerically at low Reynolds numbers. Bahmani and Akbari [5] investigated the individual effects of m^* and ζ and found that the oscillation amplitude and the width of the lock-in domain where the cylinder motion synchronises with the vortex shedding decreases by increasing either m^* or ζ . Leontini et al. [6] carried out computations for Re=200 and ζ =0.01 with varying reduced velocity $U^*=U_{\infty}/(f_N d)$, where f_N is the natural frequency of the cylinder, identifying a two-branch cylinder response.

In reality coupled two-degrees-of-freedom (2DoF) motion occurs when the cylinder is allowed to move in both streamwise x and transverse ydirections. Generally, the natural frequency (f_{Nx} and f_{Ny}), the mass ratio $(m_x^* \text{ and } m_y^*)$ and the structural damping coefficient values (ζ_x and ζ_y) are different in the two directions. Moe and Wu [7] carried out experiments where the streamwise to the transverse natural frequency ratio was kept at $f_{Nx}/f_{Ny}=2.18$ and m_y^*/m_x^* was set to 2. Lock-in was found in a wide reduced velocity $U_{\nu}^* = U_{\infty}/(f_{N\nu}d)$ range. Sarpkaya [8] and Dahl et al. [9] investigated experimentally the effect of f_{Nx}/f_{Ny} and found that when increasing the ratio of natural frequencies between $f_{Nx}/f_{Ny} \cong 1-2$ the transverse oscillation amplitude increases and the peak amplitude shifts to higher U^* values. In [8] and [9] the mass ratios in streamwise and transverse directions were different. Jauvtis and Williamson [10] investigated 2DoF cylinder motions with identical natural frequencies and identical mass ratios in the two directions. It was shown that by decreasing the mass ratio below $m^*=6$ a super-upper branch occurs.

As was mentioned, Re influences the flow significantly (see [4]). Most of the numerical simulations investigating the flow around an elastically supported circular cylinder are carried out

at low Reynolds numbers using two-dimensional approaches. Although Reynolds number and reduced velocity are not fully independent parameters, their separate effects are investigated numerically. Singh and Mittal [11] studied the effect of U^* at constant Reynolds number of Re=100 and also investigated the effect of Re at constant reduced velocity of $U^*=4.92$ for 2DoF motion. Assuming that the natural frequency of the cylinder is constant, a linear relationship can be written between Re and U^* , Re= KU^* where $K = f_N d^2 / v$ is the dimensionless natural frequency. Pransanth and Mittal [12] investigated the case of K=16.6 for 2DoF vibration and Bahmani and Akbari [5] and Willden and Graham [13] analysed 1DoF transverse-only motion at K=17.9 and 20, respectively.

The effect of structural damping coefficient has already been analysed for 1DoF transverse-only oscillation. However, although streamwise and transverse damping coefficients (ζ_x and ζ_y) are not identical in the 2DoF experiments of [7-9], their separate effects were not investigated, and neither experimental nor numerical studies seem to have focussed on this aspect. In this study the individual effects of ζ_x and ζ_y on the two-dimensional flow around an elastically supported cylinder in 2DoF motion are analysed at four different combinations of Re and U^* . After that further computations are carried out at four distinct ζ_y values using Re=34.74U*. Reynolds number and reduced velocity are varied for Re=80-240 and their corresponding reduced velocity values $U^*=2.3-6.91$ with the mass ratio fixed at m = 10.

2. COMPUTATIONAL METHOD

The non-dimensional governing equations for the two-dimensional, incompressible, Newtonian, constant property fluid flow around a freely vibrating circular cylinder in two-degrees-of-freedom (2DoF) motion are the two components of the Navier-Stokes equations written in a non-inertial system fixed to the moving body, the continuity equation and the Poisson equation for pressure. The displacement, velocity and acceleration components of the cylinder are obtained from the two non-dimensional structural equations (see [2])

$$\ddot{x}_0 + \frac{4\pi\zeta_x}{U_x^*}\dot{x}_0 + \left(\frac{2\pi}{U_x^*}\right)^2 x_0 = \frac{2C_D}{\pi m^*},$$
(1)

$$\ddot{y}_0 + \frac{4\pi\zeta_y}{U_y^*}\dot{y}_0 + \left(\frac{2\pi}{U_y^*}\right)^2 y_0 = \frac{2C_L}{\pi m^*},$$
(2)

where $U_x^*=U_{\infty}/(f_{Nx}d)$ and $\zeta_x = b_x/(2\sqrt{mk_x})$ are the reduced velocity and structural damping values in streamwise direction and $U_y^*=U_{\infty}/(f_{Ny}d)$ and $\zeta_y = b_y/(2\sqrt{mk_y})$ are the same quantities in transverse direction. In these non-dimensional equations x_0 and

 y_0 are the displacements, \dot{x}_0 and \dot{y}_0 are the velocity components and \ddot{x}_0 and \ddot{y}_0 are the acceleration components of the cylinder in streamwise and transverse directions, respectively. In Eqs. (1) and (2) C_D and C_L are the drag and lift coefficients and $m^*=4m/(d^2\pi\rho)$ is the mass ratio, where ρ is the fluid density.

The mechanical energy transferred between the oscillating cylinder and the surrounding fluid is computed as follows [14]

$$E = \int_0^T (C_D \dot{x}_0 + C_L \dot{y}_0) dt = E_1 + E_2, \qquad (3)$$

where t is the dimensionless time, T is the motion period and E_1 and E_2 are the energy transfer in streamwise and transverse directions, respectively.

The physical and computational domains are shown in Fig. 1. The cylinder surface is represented by the dimensionless radius R_1 and that of the far field, where potential flow is assumed, is denoted by R_2 . Dirichlet-type boundary conditions are used for the velocity components and Neumann-type boundary conditions is applied for pressure both on the cylinder surface and in the far field [14].

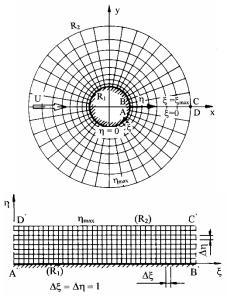


Figure 1. The physical and computational domains

In order to satisfy the boundary conditions accurately, the physical domain is mapped into a rectangular computational domain. Mapping functions are chosen so that the grid on the computational plane is equidistant and the mesh on physical domain is fine near the cylinder and coarse in the far field. An in-house code based on the finite difference method is used to solve the transformed governing equations with the boundary conditions [14]. The space derivatives are discretised using fourth-order accurate difference schemes except for the convective terms, where third-order modified upwind difference scheme is applied [14]. The two components of the Navier-Stokes equations and the two structural equations are integrated explicitly and the pressure Poisson equation is solved using the successive over-relaxation method.

The computational method was extensively validated against the available experimental and numerical data for stationary cylinder and forced cylinder oscillation cases (see [14]). Results obtained using the current code also compare well with those available the literature for elastically supported cylinder [15].

In this study the number of grid points is fixed at 360×292 , the computational domain is characterised by $R_2/R_1=160$ and the dimensionless time step is kept at 0.0005.

3. COMPUTATIONAL SETUP

In this study the effects of streamwise and transverse structural damping coefficients (ζ_x and ζ_y) on the flow around an elastically supported circular cylinder in 2DoF motions are investigated numerically at the mass ratio value of $m^*=10$. The natural frequencies in the two directions are chosen to be identical $f_{Nx} = f_{Ny} = f_N$ therefore the reduced velocities are also equal, $U_x^* = U_y^* = U^*$. Furthermore, keeping f_N at constant value, a linear relationship can be written between Re and U^* , i.e. Re= KU^* , where $K=f_Nd^2/v$ is the non-dimensional natural frequency. Assuming that the reduced natural frequency $F_N=1/U^*$ is equal to the dimensionless vortex shedding frequency for a stationary cylinder St_0 at $Re_0=180$, the non-dimensional natural frequency can be computed as $K=Re_0 \times St_0=34.74$ (here $St_0=0.192$ is obtained from [16]). Using Re= $34.74U^*$, Reynolds number and the reduced velocity values are varied within the ranges of Re=80-240 and U*=2.3-6.91, correspondingly.

The numerical simulations for undamped cylinder oscillations show that lock-in occurs between Re \cong 164–212 and $U^*\cong$ 4.72–6.1. The individual effects of ζ_x and ζ_y are investigated at Re=164, 175, 180 and 190, where relatively large oscillation amplitudes occur. The corresponding U^* values are calculated as $U^*=$ Re/34.74. The streamwise and transverse damping coefficients are varied between ζ_x =0–15 and ζ_y =0–0.3, respectively. It was found that ζ_y has a greater impact than ζ_x , therefore additional computations are carried out at fixed transverse structural damping values of ζ_y =0.001, 0.04, 0.06 and 0.2 while the streamwise structural damping coefficient is set to zero (ζ_x =0) and Re is varied with U^* using Re=34.74 U^* .

4. COMPUTATIONS FOR DIFFERENT REYNOLDS NUMBERS

Figure 2 shows the root-mean-square (rms) values of the transverse cylinder displacement y_{0rms} against Reynolds number for $\zeta_x = \zeta_y = 0$. Two-branch

cylinder response was identified, which is consistent with the results available in the literature for low Reynolds numbers (see [12]). The initial branch occurs at Re<140 and $U^*<4.03$ where low transverse cylinder displacement is observed $[y_{0rms}=O(10^{-2})]$. This branch is associated with 2S vortex shedding mode ([17]; two single vortices are shed from the cylinder periodically). In the range of Re=164-212 and $U^* \cong 4.72 - 6.1$ lock-in is observed, where y_{0rms} becomes large ($y_{0rms} \cong 0.41$ at Re=164). C(2S) vortex structure is observed at the lower edge of the lock-in domain (either positive and negative vortices coalesce in the cylinder wake, see [17]). With increasing Re and U^* in the synchronisation domain, *v*_{0rms} decreases and at Re=178.8 a small jump is observed. This jump is associated with a switch in the vortex structure from C(2S) to 2S mode. The vortex contours at the two sides of the jump are shown in Fig. 3a and 3b.

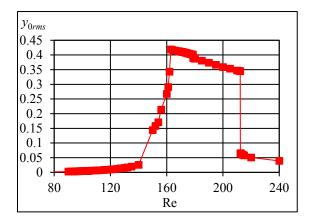


Figure 2. The rms values of transverse cylinder displacement for $\zeta_x = \zeta_y = 0$

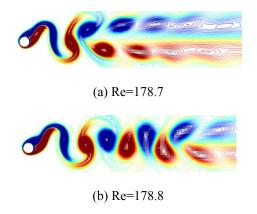


Figure 3. Vortex contours at the two sides of the jump in y_{0rms} at t=800

The effects of streamwise and transverse structural damping values are investigated at four different Reynolds numbers in the lock-in domain: at Re=164 and 175 where C(2S) vortex shedding mode is identified and at Re=180 and 190 where 2S mode is observed. Note that different reduced velocity

values belong to each Reynolds number ($U^*=\text{Re}/34.74$), but only Re is used to identify the different computational cases here.

4.1. Effects of streamwise damping

The effect of ζ_x is investigated first while the transverse damping is kept at zero ($\zeta_y=0$). Figure 4 shows the mechanical energy transfer E between the oscillating cylinder and the surrounding fluid against ζ_x . It can be seen that E is positive in the entire ζ_x domain, meaning that energy is transferred from the fluid to the cylinder. It can also be observed that by increasing ζ_x , the mechanical energy transfer first increases and reaches its maximum value at approximately $\zeta_x=1$. The peak value decreases with Reynolds number but its location does not depend on Re. For damping coefficients over $\zeta_x > 1 E$ decreases gradually. In Fig. 5 the rms values of drag C_{Drms} are shown against ζ_x . The C_{Drms} curves shift downwards with increasing Re. Overall, it is found that aside from the negligible increase in E, the streamwise structural damping coefficient does not have any significant effect.

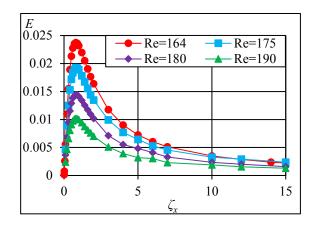


Figure 4. Mechanical energy transfer against ζ_x at different Re for $\zeta_y=0$

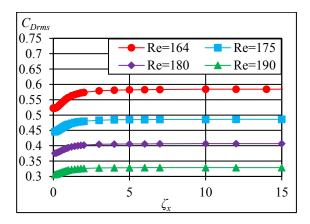


Figure 5. The rms values of drag against ζ_x at different Re for $\zeta_y=0$

4.2. Effects of transverse damping

The effect of transverse structural damping is investigated by varying the coefficient ζ_v ($\zeta_x=0$). Figure 6 shows mechanical energy transfer E against ζ_{ν} at four different Reynolds numbers. It can be seen in the figure that for the undamped vibration $(\zeta_x = \zeta_y = 0) E$ is approximately zero for all Re values investigated. At low transverse damping values E increases steeply with ζ_{y} and in three cases reaches its maximum value at $\zeta_{\nu} \cong 0.03$. The transverse damping effect is much stronger than the streamwise: for instance, at Re=175 the maximum value of the mechanical energy transfer obtained by varying ζ_{v} is $E_{max} \cong 0.6$, around 30 times larger than the result of $E_{max} \cong 0.02$ by varying ζ_x (see Fig. 4). As ζ_y is further increased, E decreases gradually. It can also be seen that the E curves belonging to increasing Reynolds numbers (except for Re=164) shift downwards and, as expected, using large damping $(\zeta_{\nu} > 0.2) E$ is almost the same for all the investigated Re values.

The results for Re=164 show somewhat different behaviour. The maximum energy transfer values appear to be smaller than those computed for Re=175, although some computational points are not plotted in the range of ζ_y =0.006–0.04 due to irregular cylinder motion. One possible explanation is that the combination of (Re, U^*) \cong (164, 4.721) for undamped vibration is near the boundary that separates initial and lower branches, where the flow is chaotic.

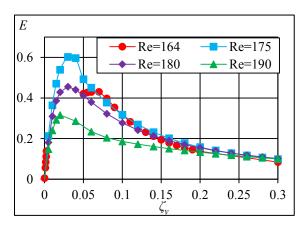


Figure 6. Mechanical energy transfer ζ_y at different Re for $\zeta_x=0$

The question arises which vibration component is responsible for high energy transfer. In Figs. 7 and 8 the time histories of $C_L \dot{y}_0$ and $C_D \dot{x}_0$ are shown. Integrating these signals over a motion period *T* the mechanical energy transfer values originating from streamwise and transverse motions (E_1 and E_2) are obtained [see Eq. (3)]. It can be seen in Fig. 7 that the area under $C_L \dot{y}_0$ over *T* where $C_L \dot{y}_0 > 0$ (indicated by '+' markers) is significantly larger than that where $C_L \dot{y}_0 < 0$ (shown by '-' markers), which leads to relatively large $E_2 > 0$. On the other hand E_1 is approximately zero because the areas under $C_D \dot{x}_0$ over *T* where $C_D \dot{x}_0 > 0$ and $C_D \dot{x}_0 < 0$ are almost identical (see in Fig. 8). For this reason the mechanical energy transfer $(E=E_1+E_2)$ is influenced mainly by transverse cylinder motion.

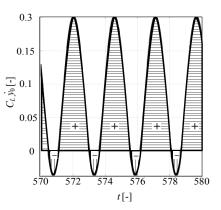


Figure 7. Time history of $C_L \dot{y}_0$ for $(\zeta_x, \zeta_y)=(0, 0.06)$ at Re=164

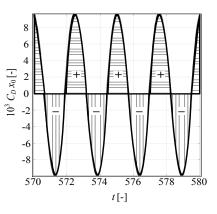


Figure 8. Time history of $C_D \dot{x}_0$ for $(\zeta_x, \zeta_y)=(0, 0.06)$ at Re=164

Figure 9 shows vortex structures at three different ζ_y values for Re=175. It is found that at Reynolds numbers where C(2S) mode is identified for undamped vibration (Re=164 and 175 in this study) C(2S) vortex shedding mode is observed below ζ_y =0.07 (see Fig. 9a and b). In the vicinity of ζ_y =0.07 the vortex structure changes from C(2S) to 2S mode which is shown in Fig. 9c. In contrast, vortex shedding mode does not change where 2S mode is observed originally at $\zeta_x = \zeta_y = 0$ (Re=180 and 190 in this study).

In Figs. 10 and 11 the rms and time-mean (TM) values of drag coefficient C_{Drms} and C_{Dmean} are plotted against ζ_y for different Re values. It can be seen that varying transverse damping from $\zeta_y=0$ to 0.1 C_{Dmean} and C_{Drms} diminish approximately by 25% and 75%, respectively. Beyond $\zeta_y=0.1 \ C_{Dmean}$ and C_{Drms} remain almost constant for all the Reynolds numbers investigated. No strong Re effect is found, as the curves fall close to each other.

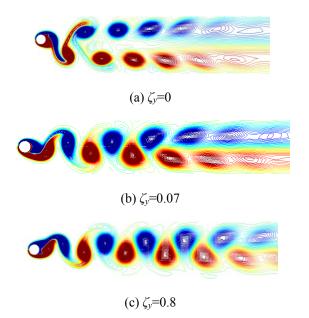


Figure 9. Vortex structures at different ζ_y values for Re=164 and $\zeta_x=0$ at t=800

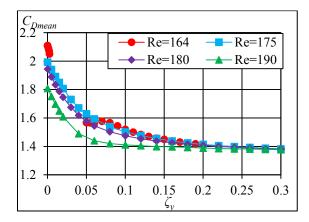


Figure 10. The time-mean values of drag against ζ_y at different Re for $\zeta_x=0$

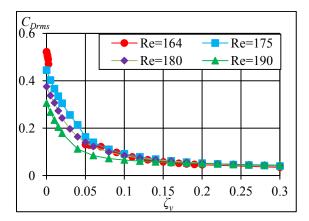


Figure 11. The rms values of drag against ζ_y at different Re for $\zeta_x=0$

5. COMPUTATIONS FOR DIFFERENT TRANSVERSE DAMPING VALUES

It was shown in Section 4 that ζ_y influences the flow much more strongly than ζ_x . For this reason systematic computations are carried out at different damping coefficients of $\zeta_y=0.001, 0.04, 0.06$ and 0.2, while keeping $\zeta_x=0$ and the natural frequency constant (Re=34.74*U**). In these investigations the Reynolds number and the reduced velocity are varied (Re=80–240 and *U**=2.3–6.91).

In Fig. 12 y_{0rms} is shown against Re for different ζ_y values. It can be seen that the results for $\zeta_y=0.001$ are very similar to those from undamped vibrations $(\zeta_x=\zeta_y=0)$; the cylinder response shows two-branch behaviour and at the boundaries of the lock-in domain irregular cylinder motion is observed. In contrast, for $\zeta_y=0.04$, 0.06 and 0.2 the chaotic flow regime at the lower and upper limit of the synchronisation domain completely disappears and y_{0rms} increases to around Re=175 and beyond that decreases continuously. As expected, y_{0rms} curves belonging to increasing ζ_y values shift to lower values in the lock-in domain.

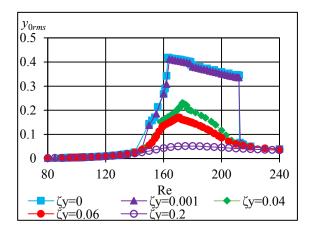


Figure 12. The rms values of transverse cylinder displacement against Re at different ζ_y values for $\zeta_x=0$

Figure 13 shows mechanical energy transfer against Re for different ζ_y values. It can be seen that for undamped vibration *E* is approximately zero. For $\zeta_y=0.001 E$ slightly increases but is still negligible. The results show that large positive mechanical energy transfer values can be obtained in the domain of Re=160–180 for relatively small transverse damping ($\zeta_y=0.04$ and 0.06). As was seen in Fig. 6, where ζ_y was varied independently, for large ζ_y values *E* decreases, which is consistent with results in Fig. 13: for $\zeta_y=0.2$ lower mechanical energy transfer occurs compared to the cases $\zeta_y=0.04$ and 0.06.

In Figs. 14 and 15 C_{Dmean} and C_{Drms} are shown for different transverse damping values. It is no surprise that for the smallest ζ_y value (here $\zeta_y=0.001$) the results do not differ from those obtained for the undamped case (similarly to y_{0rms} shown in Fig. 12). For larger but still small damping values ($\zeta_y=0.04$ or 0.06) C_{Dmean} and C_{Drms} curves belonging to different ζ_y shift downwards within the lock-in domain. For $\zeta_y=0.2$, where the maximum transverse oscillation amplitude is about $y_{0rms}=0.05$ (an almost stationary cylinder) neither C_{Dmean} nor C_{Drms} show significant increases.

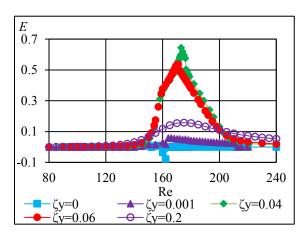


Figure 13. Mechanical energy transfer against Re at different ζ_y values for $\zeta_x=0$

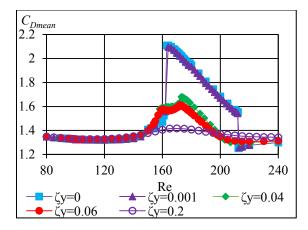


Figure 14. The time-mean values of drag against Re at different ζ_y for $\zeta_x=0$

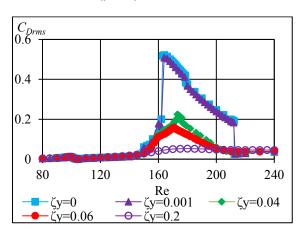


Figure 15. The rms values of drag against Re at different ζ_y values for $\zeta_x=0$

5. CONCLUSIONS

In this study two-dimensional flow around an elastically supported circular cylinder in 2DoF motion is investigated at the mass ratio value of $m^*=10$. The natural frequency of the cylinder is assumed to be constant, leading to a linear relationship between Reynolds number Re and reduced velocity U^* , i.e. Re= KU^* where K=34.74 is the non-dimensional natural frequency. The individual effects of streamwise and transverse structural damping coefficients (ζ_x and ζ_y) are investigated at Re=164 and 175, with C(2S) vortex shedding mode, and at Re=180 and 190, where 2S vortex structure is identified for undamped vibration. The main findings are as follows:

- Streamwise damping coefficient ζ_x slightly influences the mechanical energy transfer *E*;
- Transverse damping coefficient ζ_y has a much stronger influence than ζ_x . Changes in ζ_y may result in large effects on *E* and the amplitude of cylinder vibration. The peak energy transfer E_{max} =0.6 obtained at Re=175 is almost 30 times larger than E_{max} =0.02 obtained by varying ζ_x at the same Re. The transverse vibration component is mainly responsible for the energy transfer. By increasing ζ_y over 0.02 *E* decreases gradually.
- Transverse damping may affect vortex structure. Changes from C(2S) to 2S mode were found at ζ_y≅0.07 in Reynolds numbers where C(2S) mode was identified for undamped vibration, but 2S mode remained unchanged.
- Drastic decreases occur in C_{Drms} and C_{Dmean} when transverse damping is changed from $\zeta_y=0$ to 0.1, but values fall only gradually at larger ζ_y values.

Systematic computations are carried out for ζ_y =0.001, 0.04, 0.06 and 0.2 where Re and U^* are varied between Re=80–240 and U^* =2.3–6.91 using Re=34.74 U^* . The main findings:

- The results for $\zeta_y=0.001$ are similar to those for undamped vibration. Chaotic cylinder motion is observed at the boundaries of the lock-in regime and *E* approaches low values.
- Using transverse damping values of $\zeta_y=0.04$, 0.06 and 0.2 chaotic flow domain at the lower and upper edges of the synchronization domain completely disappear.
- High mechanical energy transfer can be obtained for $\zeta_y=0.04$ and 0.06.

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