

**Tree thinking, time and topology:
Comments on the interpretation of tree diagrams in
evolutionary/phylogenetic systematics**

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Running title: Tree thinking, time and topology in systematic biology

Abstract: This paper presents a graph theoretical overview of tree diagrams applied extensively in systematic biology. Simple evolutionary models involving three speciation processes (*splitting*, *budding* and *anagenesis*) are used for evaluating the ability of different rooted trees to demonstrate *temporal* and *ancestor-descendant* relationships within- or among species. On this basis, they are classified into four types: 1) *diachronous* trees depict evolutionary history faithfully because the order of nodes along any path agrees with the temporal sequence of respective populations or species, 2) *achronous* trees show ancestor-descendant relationships for species or higher taxa such that the time aspect is disregarded, 3) *synchronous* trees attempt to reveal evolutionary pathways and/or distributional pattern of apomorphic characters for organisms living at the same point of time, and 4) *asynchronous* trees may do the same regardless the time of origin (e.g., when extant and extinct species are evaluated together). Trees of the last two types are cladograms; the synchronous ones emphasizing predominantly – but not exclusively – the evolutionary process within a group, while asynchronous cladograms are usually focused on pattern and infrequently on process. Historical comments and the examples demonstrate that each of these tree types is useful on its own right in evolutionary biology and systematics. In practice, separation among them is not sharp, and their features are often combined into eclectic tree forms whose interpretation is not entirely free from problems.

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Introduction

Tree-like drawings have long been used to summarize morphological affinities or evolutionary relationships in the organic world (O'Hara 1992; Panchen 1992; Ragan 2009; Kutschera 2011; Tassy 2011) demonstrating that, for many biologists, practically any branched pattern may be conceived as a tree. In particular, figures composed of a “trunk” and several “branches” are commonly used to illustrate evolutionary history and are therefore called phylogenetic trees (Fig. 1.a-b). In mathematics, however, trees are precisely defined in graph theoretical terms as being a collection of nodes (or vertices) and a set of edges connecting pairs of nodes such that there is only one path between any two nodes (in other words, there is no circle in the graph, Yellen and Gross 2005). In general, the nodes represent *objects* (or sets of objects) whereas the edges correspond to *relations* between objects (Fig. 1.c). Thus, the diagrams of Fig. 1.a-b in fact *do not qualify* as mathematical trees, just like hundreds of other published drawings in which 1) the exact meaning of nodes and edges is often forgotten, or 2) these two constituents of the graph are not even distinguished from each other. These problems are especially striking 1) when a tree is contrasted with a classification to explain, for instance, the notions of monophyly, stem or crown groups, and node-based or branch-based clades (Fig. 1.d) and also 2) when vague statements such as “branches represent OTU's” (Camin and Sokal 1965, p. 321) and “edges correspond to ancestors” (Hörandl and Stuessy 2010, p. 1649) are made¹. Often, distinction is drawn between “cladograms *and* trees” (emphasis mine, examples in Panchen 1992) as if cladograms were something other than mathematical trees. Loose usage of terminology in biology is unfortunate if we consider how much mathematical sophistication is involved in contemporary phylogenetic methodology to “reconstruct” evolutionary history. Apparently, non-mathematical tree thinking is a source of confusions in a research area which is heavily burdened by fallacies and misinterpretations

¹ As Wiley and Lieberman (2011) and Martin et al. (2010) emphasized, one source of confusion is that phylogenetic trees can be drawn in two different ways. In „node-based” trees, vertices are taxa and edges correspond to relations between them. In „stem-based trees”, however, „edges are taxa and the nodes are speciation events” (p. 86 in Wiley and Lieberman 2011, see also Martin et al. 2010). In my view, the latter type is ambiguous and ill-defined because terminal vertices in stem-based trees cannot be associated with speciation events, a point that probably escaped the attention of the authors who otherwise warned that „one cannot have an edge without both its endpoints” (Martin et al. 2010). Some confusion appears in Wiley and Lieberman's book itself, since in their Fig. 4.1.a one edge is labeled “edge” while another as “leaf”, although the latter has been reserved for terminal vertices or tips in graph theory. Nonetheless, phylogenetic (taxon-) trees are more readily comparable with population-level evolutionary trees, cladograms and tokogenetic graphs (see footnote 5) if vertices correspond to taxa (or other entities) and edges are relations, so this convention will be followed throughout this paper.

anyway (Krell and Cranston 2004; Crisp and Cook 2005; Omland et al. 2008; Sandvik 2008; Podani 2010a; Schmidt-Lebuhn 2012).

This paper starts from a published example to demonstrate that ambiguous references to nodes and edges, and to what these may represent in a tree, can lead to misleading conclusions in systematics. I will be concerned with rooted, and therefore directed trees only, because unrooted trees have much less relevance and appear usually as intermediate results in systematic studies². The most crucial aspect is how different types of trees reflect background speciation processes, a problem evaluated by the application of model trees and by the comparison of tree diagrams derived from these models. Emphasis is focused on the time factor, leading to a classification and a unified terminology of rooted trees as used in evolutionary and phylogenetic systematics. I suggest a simple system of four basic tree types which is intended to resolve persisting confusions in the literature and to enhance correct interpretation of phylogenetic trees and cladograms at every educational level.

A false critique

As a critique of the cladistic approach, Hörandl and Stuessy (2010) present several example trees (their Fig. 4, partly reproduced here as Fig. 2, right column) to show that cladograms cannot reflect evolutionary processes and patterns faithfully because the same cladogram (Fig. 2, left column) obtains for very different evolutionary relationships³. Speciation events examined by those authors include *budding* (or branching off: the ancestor gives rise to a daughter species and remains extant), *splitting* (or bifurcation: the ancestor ceases to exist while splitting into two descendants), and *merging* (hybridization). It is claimed that a cladogram may reflect evolutionary relationships correctly only for symmetric splitting events (as originally expressed by Hennig's (1966) deviation rule or cleavage model), whereas in other cases "evolutionary trees may differ in their topology from the respective cladograms". The implicit conclusion is that cladograms are of limited use in evolutionary systematics. However, I will show that it is not the cladogram that reflects evolutionary history incorrectly,

² Nevertheless, the entire „Tree of Life" is often portrayed as an unrooted tree. Without directionality of edges, however, we cannot examine the temporal aspects and ancestor-descendant relations which are of primary concern in this paper.

³ I just note that the issue is not new, in fact several authors tried to evaluate cladogram performance by considering the same type of trees Hörandl and Stuessy were using (for example, Platnick 1977; Wiley 1979).

but the tree type selected by Hörandl and Stuessy is unsuitable for the purpose: it is perhaps the worst choice for demonstrating the above-mentioned evolutionary scenarios.

Since hybridization is a reticulate event that cannot be portrayed by trees appropriately, I will focus on other speciation processes. In the trees used by Hörandl and Stuessy, all dead and living populations of a given species are aggregated into a single vertex. Therefore, even if extant and extinct species are distinguished from one another, temporal relationships remain confounded, as illustrated in Fig. 3. Whereas the small tree in Fig. 3.a is apparently considered by Hörandl and Stuessy as being the reflection of splitting (species A becomes extinct when giving rise to daughter species B and C), there are other possibilities. We can imagine at least six different evolutionary scenarios that lead to the same species tree⁴, which becomes obvious if we examine speciation processes at the population level. For illustration, we can use *evolutionary* (or *genealogical*) *model trees* in which a vertex represents a subset (“population”) of individuals of the same species, all being born earlier than the individuals in the collection corresponding to the subsequent vertex. That is, the vertex set of the tokogenetic graph⁵ is partitioned exhaustively into such subsets and then the vertices of each subset are aggregated into a single node. Edges in the evolutionary tree thus derived imply directionality in time (from bottom upwards in all figures in this paper, so arrows showing that the relation is not symmetric need not be shown). One scenario involves splitting as suggested (Fig. 3.b), while in three others the daughter species originate through two independent budding events such that the progenitor species A disappears only afterwards (B arises first as in Fig. 3.c, or C arises first, or they arise simultaneously from the same mother population; not shown). In the last two cases, one derivative species develops by budding and the other by anagenesis (phyletic transformation) from A (one of the possibilities, with B budding, is shown in Fig. 3.d). Therefore, species trees cannot always express the processes faithfully either, and their interpretation may be equivocal in terms of background speciation history. Thus, it is not necessarily the cladogram that may reflect “only one of many hypotheses of phylogenetic relationships” because species trees may suffer even more from this drawback.

⁴ The literature is inconsistent regarding the terminology of trees in which species are connected directly, e.g. “phylogenetic trees”, Wiley (1979), or “evolutionary trees”, Page and Holmes (1998, their Box 2.3) and Hörandl and Stuessy (2010). Here, these trees are called the species trees.

⁵ A tokogenetic network (cf. Hennig 1966) shows parent-offspring relations among individuals in sexual populations. Tokogeny for asexually reproducing species produces a tree, rather than a network.

Now, we can examine how the cladograms (assuming parsimony for *extant* species, without homoplasies) compare with the species trees of Hörandl and Stuessy (2010) and the corresponding evolutionary model trees (middle column of Fig. 2). These were made by hand to show instances of population-level changes that lead to the given species trees. The symmetric splitting speciation model provides a species tree identical in topology to the cladogram, as already mentioned. In more precise graph theoretical terms, they are *isomorphic*. The population level evolutionary tree looks differently because it has many more nodes, yet it is *homeomorphic*⁶ with the other two (Fig. 2.a). The cladogram and the species tree are the *backbone trees*⁷ of the evolutionary tree, which means that the three alternative trees are congruent in evolutionary sense. All is going well so far, but not any longer. When the ancestor species (C) survives its immediate descendant (D) which splits into two daughter species (A and B, Fig. 2.b), the topology of the species tree is radically different from the cladogram, while the latter is the backbone of the underlying evolutionary tree. That is, the shape of the cladogram corresponds to the true evolutionary history! When splitting appears first, and budding follows later (Fig. 2.c), the cladogram is again homeomorphic with the model tree, so cladogram topology reflects well the branching events in the evolutionary history of the extant species. The next example (Fig. 2.d) shows how confusing the inconsistent use of nodes can be: there is a third, unlabeled and undefined node in the species tree (marked by “?” in my figure). It becomes obvious only from the original caption that “B has budded from A” which means that this is in fact the same as Fig. 2.c with A and B transposed. Consequently, the cladogram and the evolutionary tree are as comparable as in the previous case. The last example is a sequence of budding events represented by a linear species tree (Fig. 2.e). Even in this example the cladogram and the evolutionary tree are homeomorphic, showing that the cladogram is no worse than the species tree in revealing true evolutionary patterns and processes⁸.

⁶ Two graphs are *isomorphic* if there is one-to-one correspondence between their nodes and their vertices. Graphs G and H are *homeomorphic* if isomorphism is achieved by two operations: 1) *smoothing* a vertex v with respect to the pair of edges (e,f) incident to v removes both edges at v and replaces them with a new edge that connects the other endpoints of the pair; or 2) *subdivision* which is the reverse operation, i.e., cutting an edge into two and inserting a new vertex. It is important that only vertices with a degree of 2 can be smoothed, the degree being the number of edges incident to the given vertex. For mathematical details, see Yellen and Gross (2005).

⁷ The *backbone* of any rooted tree T is defined here as the unique tree U obtained by smoothing all candidate vertices of T except for the root.

⁸ I suspect an error in the original figure of Hörandl and Stuessy (2010, their Fig. 4.f), because the species tree given there by $A \rightarrow B \rightarrow C$ produces a cladogram $(\{A\{BC\}\})$ that is not identical to the other cladograms used (i.e., $\{C\{AB\}\}$).

While the topology of cladograms and the population-level evolutionary trees is comparable in all cases discussed above, there are remarkable differences in character distributions on the cladograms. In other words, in examining the cladogram not only the topology deserves attention. If changes from the plesiomorphic state to the apomorphic are shown by small tick marks on edges in the usual manner (the number of marks on each edge is its weight or length), we see that all cladograms represent different synapomorphy schemes. The distribution of tick marks on the tree gives some insight into potential background processes – at least for the extant species. In particular, it is recognized easily that budding manifests itself as a lacking autapomorphy on the edge incident to the mother species (zero-length edge), which has long been known in cladistics (as visualized, for example, by the groundplan-divergence analysis of Wagner 1961).

Further examples

The trees shown by Hörandl and Stuessy (2010) include no more than three extant and two extinct species, and are based only on two kinds of speciation events. For a more reliable and convincing comparison, I will use examples with larger numbers of species and consider another speciation process, *anagenesis* (the ancestor is replaced by the descendant) as well, which was not examined by those authors⁹. Furthermore, a fourth type of tree will also be used: cladograms derived for all species, regardless whether they are extant or extinct. The basis of comparisons will be four model trees prepared by hand. The first three trees show either budding, splitting or anagenesis, whereas the fourth tree combines all the three speciation processes with extinction due to splitting, anagenesis (in this case, it is called “pseudoextinction”, Foote 1996) and lineage termination. In these model trees, as in those in Figs 2 and 3.b-d, each vertex corresponds to a morphologically homogeneous subset of individuals of a given species (called here a “population”) that were born earlier than individuals belonging to the subsequent vertex, while edges represent this temporal directionality¹⁰. Characters by species matrices underlying the different models are created

⁹ Anagenesis is not always acknowledged as a process leading to the origin of new species (see e.g., Kornet and McAllister 2005, Wiley and Lieberman 2011) contrary to other authors (see references in Benton and Pearson 2001, Stuessy et al. 2006). As shown later in this section, anagenesis and speciation via a series of budding events are closely related, the first being the ultimate reduction of the second.

¹⁰ This subdivision of the set of all species is similar to partitioning the vertex set of a tokogenetic network into internodons, as suggested by Kornet and McAllister (2005). However, internodons are bounded by successive branching events resulting in either a new species or a new tokogenetic branch of the same species which then becomes extinct. My model populations are bounded more arbitrarily according to time periods, or are defined less arbitrarily as generations (as in Darwin 1859).

based on the following simple assumptions: 1) each character has two states, “0” is the plesiomorphic state, “1” is the apomorphic; 2) there are no homoplasies (reversals or convergence), and 3) a single shift from the plesiomorphic to the derived character state results in a taxonomic change from one species to the other. That is, the evolutionary continuum is discretized to allow for making sharp distinction between character states and therefore between species¹¹. Cladograms are constructed under standard parsimony to minimize tree length (sum of character changes to explain the tree). Species trees are obtained by aggregating nodes in the evolutionary tree which represent the same species (as in Fig. 2), using the graph theoretical operation of edge contraction¹². The data, and the four different trees for each model are displayed in Figure 4, with species A as the (direct or indirect) ancestor of the other species in all cases.

The budding speciation model comprises eight species: A, C, D, F, and H are extant, while B, E and G are extinct via lineage termination (Fig. 4.a). From A, two species bud, just like from species C. Thanks to the two consecutive budding events from C, the cladogram for extant species has a trichotomy, showing that the *sequence* of budding events cannot be disclosed by cladograms. There are no tick marks on edges pointing to surviving ancestor species (A, C and F), as mentioned above. The graph theoretical relationship between this cladogram and the evolutionary tree is less obvious than in the previous examples. To find their correspondence, all extinct side branches (all vertices of species B and E, and the terminal vertex of G) are removed first by truncation. Then, smoothing all vertices of degree 2 produces the backbone of the truncated evolutionary tree¹³. Finally, edge contraction between vertices representing dead or extinct populations of the same species yields the cladogram: fusion of the two remaining vertices of C leads to the polytomy and the merger of two vertices of A gives the new root. Although these operations may appear substantial, the cladogram of extant species reflects fairly precisely the branching evolutionary pattern of extant species, the

¹¹ Definition of species is crucial for every taxonomic school, and there is no universal concept with general validity and acceptance. In this paper, the model assumes no more than that the spatio-temporal continuum of individuals can be exhaustively subdivided into mutually exclusive (disjoint) subsets, the species. This corresponds well the unified species concept of de Queiroz (2007) according to which a species is a segment of a metapopulation lineage in that continuum. To simplify modeling for the purposes of the present paper, the “Gray Zone” between segments, in which species definitions differ with schools (see Fig. 1 in de Queiroz 2007) is reduced to zero. Thus, the question whether what kind and how many characters are required for separating species is irrelevant here.

¹² Edge contraction is an operation which removes edge e from a graph while simultaneously merging together the two vertices previously connected by e .

¹³ See Fig. 3.e-f, for further illustration of the terms truncation and backbone tree based on Darwin’s diagram on speciation and a corresponding cladogram.

exception being speciation involving two or more budding events from the same ancestor. The cladogram of all species, extinct and extant, is homeomorphic with the evolutionary tree with the exception of two trifurcations. The species tree is entirely atemporal because, for example, ancestor species A survives three of its descendant species. This tree obtains directly from the cladogram of all species by edge contraction: the fusion of nodes connected by edges of zero length (those lacking tick marks for autapomorphic characters).

In the splitting model (Fig. 4.b), four species are ancestors (A, B, C, G) and species F disappears due to lineage termination. The cladogram of extant species (D, E, H, I) correctly recovers their backbone topology in the evolutionary tree. Contrary to the budding model, the cladogram of all species is not homeomorphic with the evolutionary tree at all. Similarly to the previous example, the species tree derives from the latter cladogram by edge contraction. The species and evolutionary model trees are homeomorphic, as already observed in this paper for other examples of splitting (Fig. 2.a, Fig. 3.a,b).

During anagenesis (Fig. 4.c), ancestor A runs through a transformation series ending with species E. The corresponding cladogram is trivial since it has a single terminal species. Still, it is homeomorphic with the evolutionary tree. The other cladogram, obtained for all species, has zero-length edges incident to the extinct species and their contraction reproduces the species tree. The latter, as for the splitting model, is homeomorphic with the evolutionary tree. The combined model is constructed for six species such that each type of speciation events appears twice (Fig. 4.d). In this case, the cladogram of recent species is a correct representation of the backbone topology of the truncated evolutionary tree. The cladogram of all species has three trifurcations, two pertaining to the splitting event and the other to budding. As earlier, edge contractions reproduce the species tree, which differs topologically from the evolutionary tree and the cladogram of extant species as well.

In the above examples, evolutionary model trees were drawn first, from which the data matrices were compiled and the alternative trees were constructed. To obtain a more general picture on the subject matter, we shall examine other possibilities to show that there is in fact no one-to-one correspondence between data and evolutionary trees. Two cases in point deserve particular attention. First, it is easy to see that the data matrix in Fig. 4.b may also serve as a descriptor of the model tree of Fig. 5.a. In this, contrary to the evolutionary tree depicted in Fig. 4.b, every speciation event is budding, every ancestor gives rise successively

to two descendants and then remains extant for a while. Note also that whereas the underlying model has been altered, the two associated cladograms and the species tree remain unchanged. We may conclude that species trees (as demonstrated already in Fig. 3) as well as both types of cladograms cannot make distinction between splitting and a combined process involving two consecutive budding events from the same ancestor and a delayed extinction of that ancestor. This suggests clearly that *splitting is an extreme case of this combined process*, with the topological distance between two consecutive budding events and the survival time of the ancestor species reduced to zero. The backbone of the truncated evolutionary tree and the regular cladogram are not homeomorphic, unless edge contraction reduces the number of vertices for species A, B and G to 1. The same is true for the (non-truncated) evolutionary tree and the cladogram of all species. The second example will illustrate another interesting situation. The data in Fig. 4.c can also be conceived as describing a tree in which a series of budding events is portrayed such that extinction of each ancestor is not immediate (Fig. 5.b). In this tree, contrary to the evolutionary tree of Fig. 4.c, anagenesis is completely lacking. Nevertheless, the two derived cladograms and the species tree remain the same as in Fig. 4.c. This illustrates lucidly that these trees cannot distinguish between anagenesis and a series of budding events with subsequent lineage termination of ancestors. A consequence is that *anagenesis can be conceived as a special case of a series of budding events* such that survival times of ancestor species are ultimately reduced to zero.

Discussion: basic tree types in evolutionary biology

Evaluation of the ability of different trees to show, summarize and even confuse background speciation events allows conclusions to be made on 1) their general features and 2) their performance under the specific models used. Considering the portrayed temporal relationships among populations and species, extended to genera and higher taxa¹⁴, I suggest distinguishing among four basic tree types, as follows.

1. Diachronous trees

Budding, splitting and anagenesis are population-level processes that can be best modeled by Darwinian evolutionary trees in which nodes represent temporally separated populations and edges correspond to progenitor-derivative relations (Fig. 2, middle column, Fig. 3.b-d, Fig. 4,

¹⁴ This paper is not concerned with rank-free classifications.

second column, Fig. 5) or Ancestor-Descendant Relations (ADR trees, Dayrat 2005). These model trees are *diachronous* because they depict genealogical history over time correctly: the temporal relationships between the units of study are preserved by the sequence of nodes along any path from the root towards the leaves (i.e., terminal nodes or tips). The prototype of these trees is the sole figure in “The Origin of Species” by Darwin (1859, see also Fig. 22 in Ragan 2009 or Fig. 6 in Tassy 2011, partly reproduced in this paper, Fig. 3.e) – although it does not satisfy fully the criteria for being a mathematical tree (in fact, it is not a single tree but a forest, while most vertices are not shown). Actual evolutionary processes will never be known to such fine details; nevertheless, these trees can be used efficiently in theoretical discussions (Freudenstein 1998; Kornet and McAllister 2005; Podani 2010ab).

Mathematically, these graphs are spanning trees in which the nodes are biologically of similar type (e.g., all of them represent populations, generations or internodons), and the number of edges is one less than the number of nodes. It has been suggested (e.g., Dayrat 2005) that the terms “evolutionary” or “phylogenetic” should be reserved to these trees, a convention followed throughout this paper as well.

Diachrony cannot be shown by evolutionary trees at every taxonomic level. If we switch from populations to species, then the graph can display proper temporal order only if the possibility of speciation by budding is excluded. Thus, species trees may be correct diachronous representations of evolutionary history only if ancestors disappear when giving rise to descendants (anagenesis or splitting, Fig. 2.a, Fig. 4.b and c). Moreover, if we raise the taxonomic level from species to genera or higher (i.e., aggregate several species into a single node), then diachrony cannot be valid any longer for obvious reasons. Diachrony would require that whenever a progenitor species A disappears after the speciation event, then all other species in the same genus (or higher taxon) as A also go extinct in concert. Needless to say, the probability of such coincidences rapidly diminishes when taxonomic rank increases above the species level. Furthermore, paraphyly enters the scene, which brings us to the next section.

2. *Achronous trees*

In case of budding (i.e., when the ancestor species survives the speciation event), species trees may confuse temporal relationships: although the edges represent ancestor-descendant relations, extinct and extant species may alternate along any path in the tree (Fig. 2.b and Fig. 4.a and d). Without having information on extinction, such trees may give the impression that

one species was followed by the other in time. Temporal relations are even more confounded when species of the same genus or higher taxon are aggregated into a single node. It is possible that the order of taxa along a path in such a tree conflicts with the order of geological times in which some members of these taxa first appeared, hence the suggested name *achronous* (Greek, “timeless”). A potential source of misinterpretation of these trees is that they seem to suggest that the ancestor stopped evolving when giving rise to the descendant(s)¹⁵. The prototype of achronous trees is the one drawn by Lamarck in 1809 (reproduced as Fig. 5 in Ragan 2009, or Fig. 4 in Tassy 2011), the first “phylogenetic” tree ever published. Since that time, similar diagrams have dominated the biological literature, before and after Darwin (for example, those drawn by Strickland and Haeckel). An interesting historical aspect is that Wallace’s tree showing “affinities” within the bird group Fissirostres was also of similar nature (Fig. 19 in Ragan 2009). Such trees are still popular today to summarize major evolutionary advancements in function and form rather than descent (e.g., Cavalier-Smith 2010) and, hence, these are best termed as *grade* trees. Mathematically, these graphs are spanning trees like evolutionary trees: all vertices are (ideally) of the same type and edges may correctly link ancestor taxa with descendants at any taxonomic level. For orders, the most famous example is perhaps the “cactus diagram” of angiosperms suggested by Bessey (Fig. 3.2 in Judd et al. 2002) converted to a tree. Theoretically, a node corresponding to a highly ranked taxon is an aggregate of nodes in evolutionary trees or diachronous species trees, while in practice Besseyan diagrams may be derived from cladograms (for example, Zander 2008). Taxa in grade trees may be *monophyletic* (represented by nodes with a degree of 1) and *paraphyletic* (otherwise), while polyphyletic groups correspond to single nodes mostly in achronous tree diagrams that are only of historical importance (e.g., Haeckel’s many trees).

3. *Synchronous trees*

Based on the original proposal by Hennig (1966), cladograms are constructed to reveal the evolutionary relationships for extant taxa, hence the name (*synchrony* refers to “contemporaneous” organisms). These are represented by the leaves of the tree. Evolutionary relationships between them are expressed by means of interior nodes, which can be considered hypothetical ancestors, allowing the possibility that an ancestor is identical to an

¹⁵ As Judd et al. (2002, p. 44) noted, „such diagrams imply that groups that exist in the world today are the ancestors of other groups that also currently exist, which doesn’t make much sense in terms of evolutionary processes”.

extant taxon connected directly to it. A synchronous cladogram is thus a summary of a set of Sister-Group Relationships (SGR-tree, Dayrat 2005), each expressed by two edges that connect two terminal nodes (or sets of them, i.e., two clades) through an interior node. A sister group hypothesis means that the groups involved are closer to each other than to any other group. Mathematically, cladograms are Steiner trees in which the leaves and the interior nodes are of different type. This difference is emphasized unintentionally in the cladistic literature by not showing interior nodes explicitly. If the number of terminal nodes is n , then a fully dichotomous Steiner tree has $2n-1$ nodes and $2n-2$ edges.

The examples in this paper demonstrated that a cladogram of contemporaneous organisms may illustrate two phenomena simultaneously: 1) the sister group relationships and the tick marks together reflect *pattern* (character distributions) as a result of evolution at a given point of time, while 2) cladogram topology, as the backbone of the truncated evolutionary tree, plus edge lengths (if available) depict the *process* (evolutionary pathways) by which that pattern was generated. The ability to reflect background processes in this way is unequivocal for splitting and anagenesis, but not always so for budding. If the still extant progenitor species gives rise to two or more derivative species, then it manifests itself as a polytomy in the cladogram and one edge with zero length. This happens whenever the data are uninformative on branching sequences (Schmidt-Lebuhn 2012, see explanation to his Fig. 2). It has been shown that the longer-lived is the ancestor, the more likely that several species will derive from it by budding, and therefore the chance for obtaining polytomies is not negligible (Foote 1996). Consequently, trichotomy is not always a reflection of “unresolved” bifurcations (considered by Hennig as a mere technical issue, but see Rieppel 2011), but a true three-species relationship (see also Posada and Crandall’s [2001] similar arguments on gene trees). In practice, perfect coincidence of pattern and process is more often the exception than the rule: homoplasies in the cladogram can spoil interpretability of interior nodes as synapomorphies. Also, many cladogram constructing methods do not even bother with character distributions, because the process leading to the terminal objects is in focus (Ereshefsky 2001; Rieppel 2010; Wiley and Lieberman 2011).

That synchronous cladograms reflect budding (except for polytomies), splitting and anagenesis and their combinations in model situations correctly does not mean, of course, that cladogram topology is fully informative on background speciation events. In fact, there are an infinite number of possible evolutionary trees that produce the same cladogram (remember,

for example, that we do not know how many related species are extinct). However, it is easy to see that the backbone trees of the truncated forms of all these alternatives are identical to one another and isomorphic with the cladogram after applying edge contraction to their vertices which represent dead or extinct populations of the same species, if such vertices exist. This would not be possible at all if different speciation processes were represented incorrectly by synchronous cladograms. Isomorphism is the key feature ensuring that synchronous cladograms can be considered as attempts to “*reconstruct phylogeny*” (as authors of many contemporary molecular cladistic papers put it)¹⁶ while all of us are aware that complete reconstruction of the past is impossible.

When using a cladogram as a reference for classification, we should keep in mind that only the leaves of the tree represent actual, classifiable objects, while interior nodes do not. In other words, cladograms of contemporaneous organisms are useful to derive synchronous classifications only. Therefore, if grouping is based on cladograms, I advise 1) to distinguish such classifications from diachronous systems; 2) to distinguish monoclادistic groups from paracladistic ones: the first one is a complete sister group system, while the second is incomplete and, consequently, 3) to separate monophyly from monoclady and paraphyly from paraclady (see Podani 2009, 2010b, for more details).

Historically, prototypes of synchronous cladograms are those given in Hennig (1966). It is nevertheless interesting to note that one of Haeckel’s trees (“*Der Monophyletische Stammbaum der Organismen*”, Haeckel 1866, reproduced as Fig. 23 in Ragan 2009, Fig. 6 in Kutschera 2011) may also be viewed as a cladogram: taxa are arranged at the tips of the tree, all taxa are extant, none of them is derived from the other (contrary to Haeckel’s many other grade trees, see Dayrat 2003), extinct side branches are almost completely missing, and there is a superimposed high-level classification (3 major clades, and 19 smaller clades labeled).

4. *Asynchronous trees*

When extinct and extant organisms or, in general: taxa known from different geological ages, are evaluated simultaneously by cladistic analysis, we are faced with radically different possibilities for explanation and interpretation. Representing organisms of different times at

¹⁶ Dayrat (2005) pointed out that “most ‘phylogenetic trees’ or ‘phylogenies’ currently published simply are cladograms” which might confuse many scientists.

the same level violates synchrony, hence the suggested term *asynchronous*. The examples in this paper demonstrated that under these circumstances

- a cladogram cannot always reveal the historical process although topologically it is comparable with the evolutionary tree if all speciation events were budding,
- polytomies may result from *both* budding and splitting,
- zero length of terminal edges may reflect survival of ancestor species (budding), and extinction of ancestor species (splitting or anagenesis) as well, and
- contraction of zero length edges establishes close relationship to grade trees, i.e., transfer from asynchronous to achronous topologies.

Examples demonstrated that an asynchronous tree topology and edge lengths may depict both pattern and process simultaneously only if speciation is by budding. Otherwise, ancestors may appear in false sister group relationship with descendants, and the cladogram cannot be isomorphic with the backbone of the underlying evolutionary tree. Of course, this is a conclusion from a model whereas in practice one can never be sure about past speciation processes. Uncertainty exists, in general, even though in models ancestors are easy to distinguish from descendants (zero-length edges are incident to ancestors in asynchronous cladograms). This is not a problem for many systematists whose interest is focused on pattern (character distributions, synapomorphies), entirely disregarding the evolutionary process generating that pattern. The paradigmatic shift from process to pattern is behind the development of transformed cladistics (see, e.g., Scott-Ram 1990), which has a not too distant relationship to numerical taxonomy as well: classifiable objects are at the tips of the cladogram, as in dendrograms obtained by hierarchical clustering. Often, asynchronous cladograms are used as a basis for classification without reference to phylogeny, while groups derived from them are still called „*monophyletic*” as opposed to “non-*monophyletic*” (Williams and Ebach 2007)¹⁷. Nevertheless, asynchronous groups may be directly comparable with those delineated on diachronous and achronous trees, which is not so with synchronous ones. If asynchronous trees are not burdened with reversals and convergences, then synapomorphies (i.e., characters with apomorphic state appearing for at least two species) may be associated with interior nodes. As a prototype of asynchronous cladograms, I would nominate the one for fossil horses suggested by Camin and Sokal (1965, their Fig. 4) in which

¹⁷ To resolve this ambiguity, I have suggested the use of terms monothety and polythety (Podani 2010a).

the tips of the tree represent taxa described from different geological times (from the Oligocene to the Pliocene), both ancestors and descendants.

5. *Eclectic forms*

The four tree types do not always appear in pure form in the literature, because their characteristics may show up simultaneously in the same graph in a wide variety of ways. Especially common is the practice of combining cladogram properties with a grade tree¹⁸. In such “hybrid” trees, unlabeled interior nodes (cladistic bifurcations or polytomies) appear together with named interior nodes representing extinct or extant taxa, or both. Noted examples are some “phylogenetic” classification trees of angiosperms (e.g., Takhtajan and Cronquist, among others, see Figure 3.3 in Judd et al. 2002). Similar diagrams are quite often used to display relationships of genera within a family (e.g., Pedaliaceae, Ihlenfeldt 2010). Regarding the time aspect, these are *eclectic* because parts of the tree emphasize synchrony of sister groups (or appear to do so) whereas other parts refer to the derivation of one group from the other in a way that diachrony and achrony are not distinguished properly. For this reason, interpretation of eclectic tree diagrams is not straightforward in most cases.

Concluding remarks

Whereas much has been said in the contemporary literature on the philosophical aspects of evolutionary/ phylogenetic/ cladistic analysis, the graph theoretical side of the subject matter has not yet received sufficient attention – even though tree graphs have long been used paradigmatically as metaphors of order in the living (and extinct) world. This may have serious consequences that are harmful to systematics and, in general, to biology. The problem is rooted in that edges and nodes of the graphs are not always understood in accordance with the common language of science, i.e., mathematics. In lack of a unified terminology that is consistent with graph theory, mutual understanding among different schools of systematics is impossible. For example, persisting terminological confusion over the meaning of trees, or different parts of them, explains that participants in the controversy about paraphyly and monophyly still “talk past each other” (Schmidt-Lebuhn 2012).

I used simple models of three speciation processes to generate tree diagrams which portray within- and between species relationships differently. Examples demonstrated that

¹⁸ Note, however, that combining trees of the same type into a single one (e.g., consensus cladograms and supertrees) preserves the properties of the original trees.

interpretation of these trees is constrained by their ability to reflect speciation processes and ancestor-descendant relationships (Fig. 6). These phenomena can only be shown adequately by diachronous trees in which nodes represent individuals, populations or, at most, species. Such trees are, however, epistemologically unknowable albeit useful in theoretical discussions. Achronous trees expand the meaning of nodes to taxa higher than species, but the cost is high: while ancestor-descendant relationships may be maintained (when species A in taxon 1 is the ancestor of species B in taxon 2), temporal relationships between taxa 1-2 will not be maintained in the tree, unless both of them are monotypic, and therefore paraphyly becomes unavoidable. At the species level, the topology of diachronous and achronous trees is comparable for anagenesis and splitting, but not so for budding. Thus, although both of them are spanning trees (i.e., studied populations or taxa are connected directly), their interpretation differs radically.

Synchronous trees (conventional Hennigian cladograms) can be used to generate hypotheses on evolutionary processes. This may be achieved, for example, by finding synapomorphies for entities ranging from individuals to high taxa living at a given point of time, but other, probability-based strategies are also widely used especially at the molecular level. Cladogram topology, if all sister-group relationships are depicted correctly, agrees with the backbone topology of the truncated (true but unknown) evolutionary tree, with the exception of polytomies caused by >1 budding events from the same ancestor species. Thus, the modeled cases refute the common belief that cladograms can represent only divergence (splitting) and that multifurcations always reflect phylogenetically “unresolved” situations. If a cladogram is constructed for organisms of different times, then it may be primarily viewed as an asynchronous summary of synapomorphies. Nevertheless, asynchronous cladograms may also be identical in topology to the backbone phylogeny when no analyzed entity is ancestral to any other via speciation by splitting or anagenesis. One should keep it mind that all cladograms are Steiner trees: taxa are connected through interior vertices which should be interpreted differently from terminal vertices.

Although recently the most important demarcation line within the domain of cladistic approaches has been drawn between the so-called process cladistics and pattern cladistics (see e.g., Ereshefsky 2001; Rieppel 2010), the present study demonstrated that distinction between synchronous and asynchronous cladograms is perhaps more important in evolutionary context. Synchrony always allows (although does not guarantee, of course) reconstruction of

evolutionary pathways which may then serve as a basis for classification, and a synchronous summary may also reflect character distributions quite properly. That is, pattern and process do not separate as sharply as previously suggested. An asynchronous analysis may very well be a useful atemporal summary of the pattern of life, and process as well (for budding), but there is always a risk to view the topology of asynchronous cladograms as being a reconstruction of phylogeny. There is no ambiguity at all if we consider these cladograms as classification trees, as originally proposed by pattern cladists.

My answer to the questions raised by Hörandl and Stuessy (2010) may be summarized as follows. Conceptually, there is loss of information during transfer from the most detailed evolutionary trees to grade trees and both types of cladograms. This means that none of the latter three can recover underlying evolutionary processes fully – there are an infinite number of possible evolutionary scenarios that lead to a given grade tree or a cladogram. The present model situations demonstrate, however, that the risk of mistake is the smallest for synchronous cladograms (unbiased towards any type of speciation processes examined here), followed by asynchronous ones (biased towards budding), whereas grade trees (biased towards splitting and anagenesis) can be drastically misleading even at the species level, not to mention higher taxa. Nevertheless, each tree type has its own merits in revealing, explaining or illustrating evolutionary and classificatory pattern of nature, and is therefore useful under different circumstances. Mathematically they are closely related: graph theoretical operations may be used to convert one tree type into the other. Therefore, distinction among the four tree types is not necessarily sharp and, indeed, many published diagrams combine their features. The ground is now open for a more detailed comparison of tree types by using more realistic (e.g., stochastic) evolutionary models and tree reconstruction procedures that rely not only on parsimony of character distributions.

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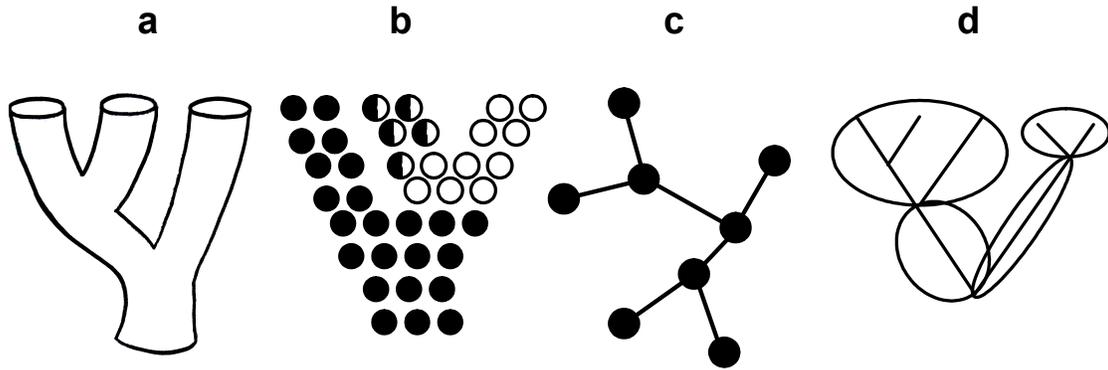


Figure 1. “Phylogenetic trees” (**a**: modified after Platnick 1979, **b**: based on Freudenstein 1998); a mathematical tree with nodes and edges (**c**); and a cladogram with a classification superimposed such that group memberships remain unclear (**d**, modified after Griffiths 1974 and de Queiroz and Gauthier 1990).

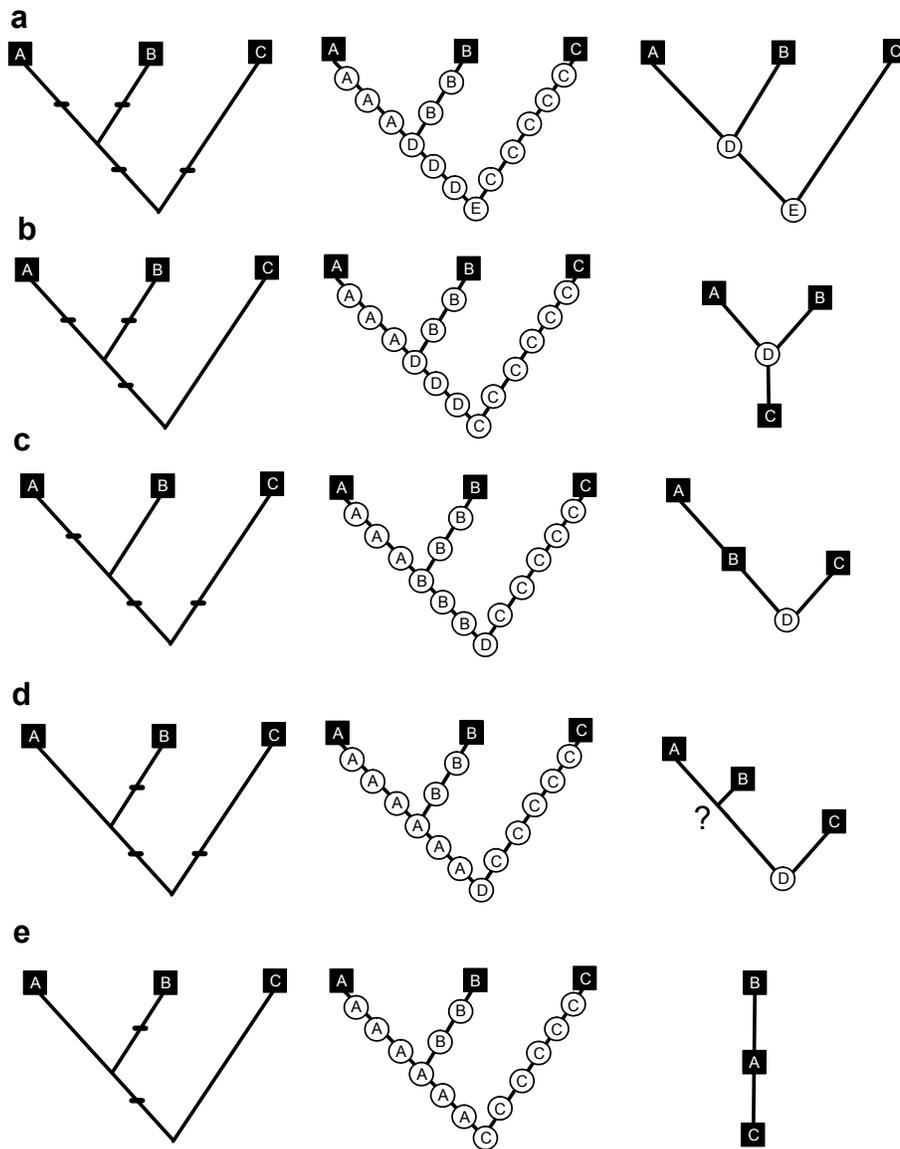


Figure 2. Conventional cladograms for three species (left column) and species trees (right column, after Hörandl and Stuessy 2010) derived from trees representing different speciation models with vertices as populations and edges representing progenitor-descendant relationships (middle column). **a:** splitting, **b:** ancestor species C survives its daughter species D which splits, **c:** A buds from B, **d:** B buds from A, **e:** two consecutive budding events. Squares: extant or living, circles: extinct or dead. Interior nodes in cladograms are NOT shown, which is a general convention in cladistics followed here for simplicity only. Tick marks indicate changes from the plesiomorphic to the apomorphic character state.

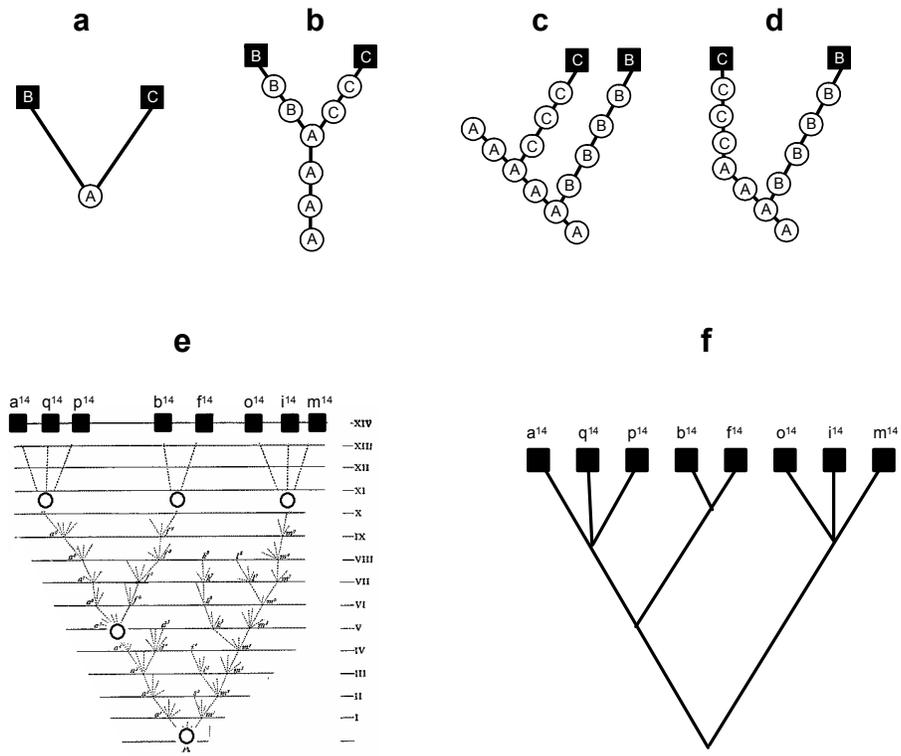


Figure 3. Three different speciation model trees with populations as vertices (**b-d**), which correspond to the same species tree (**a**). Tree **b** is a simplified form of the “species cleavage” model of Hennig (his Fig 4, 1966). Detail of Darwin’s scheme (Darwin 1859, some vertices added) representing a single evolutionary model tree (**e**) and the corresponding correct cladogram for extant species (**f**). Truncation means that in the evolutionary tree all subtrees terminated with extinction are pruned off and then the backbone topology is obtained by smoothing all vertices with a degree of 2 (vertices are only imaginary on Darwin’s original tree, because the interval between two consecutive time levels shown on the right corresponds to 1000 generations). As a result, the cladogram is isomorphic with the backbone of the truncated evolutionary tree. Interior nodes in the cladogram are NOT shown, which is a general convention in cladistics followed here for simplicity only. Squares: extant or living, circles: extinct or dead.

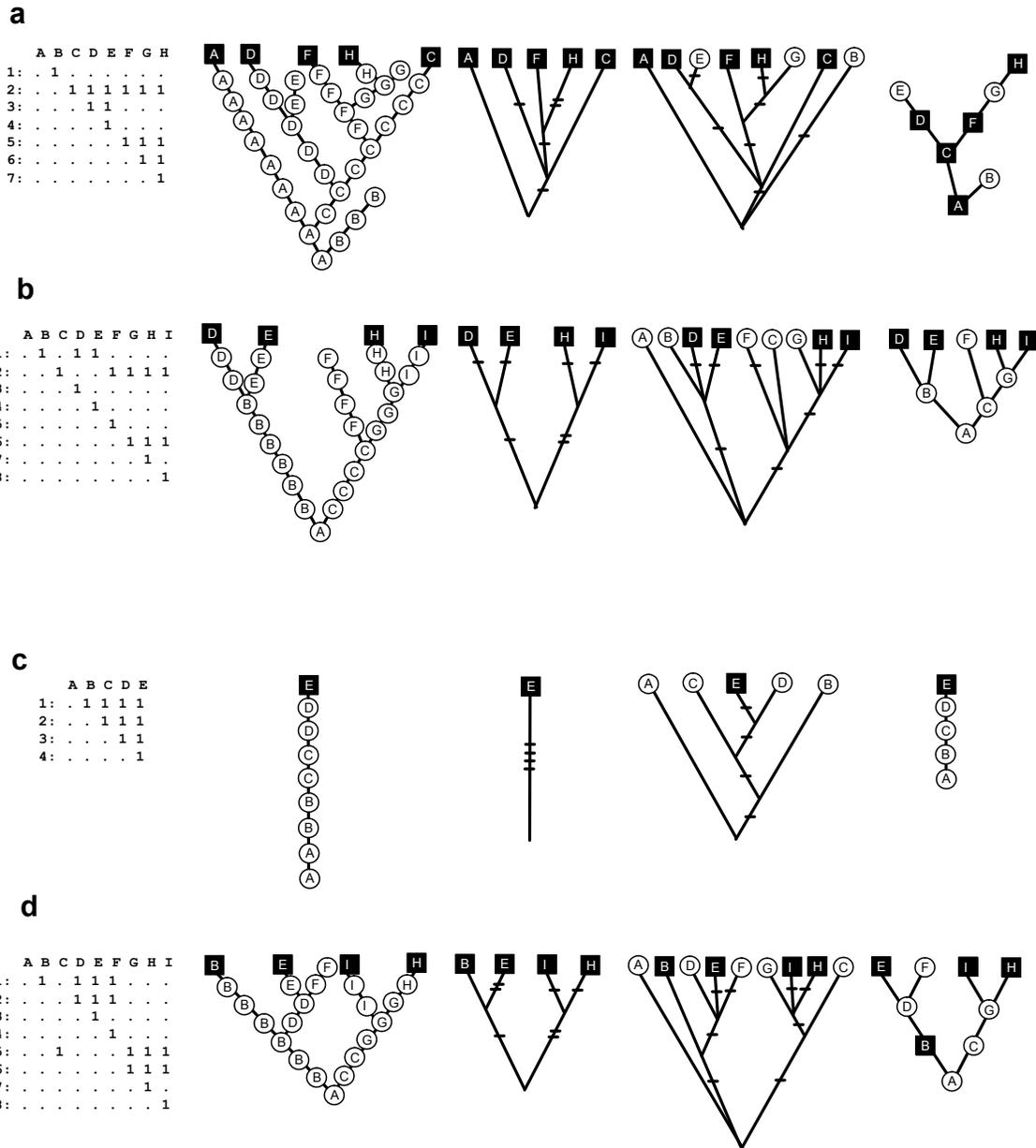


Figure 4. Four types of trees for four different speciation models. **a:** budding, **b:** splitting, **c:** anagenesis, **d:** combined. Left column: characters by taxa data matrices (with zeros replaced by dots for clarity), second column: evolutionary trees, third column: cladograms for extant species, fourth column: cladograms for all species, fifth column: species trees. Squares: extant or living, circles: extinct or dead. Interior nodes in cladograms are NOT shown, which is a general convention in cladistics followed here for simplicity only. Tick marks indicate changes from the plesiomorphic to the apomorphic character state (see data sets on the left, for synapomorphies and autapomorphies).

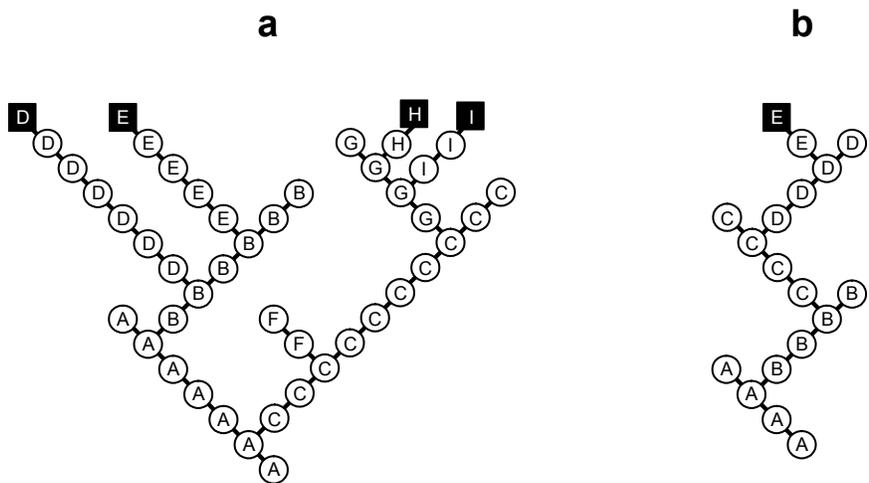


Figure 5. Evolutionary model trees that may be described by the same data matrices as those in Fig. 4.b-c, but all speciation events are budding (extinction of ancestors is never immediate). **a:** model tree fitted to the data of Fig. 4.b, **b:** model tree fitted to the data of Fig. 4.c.

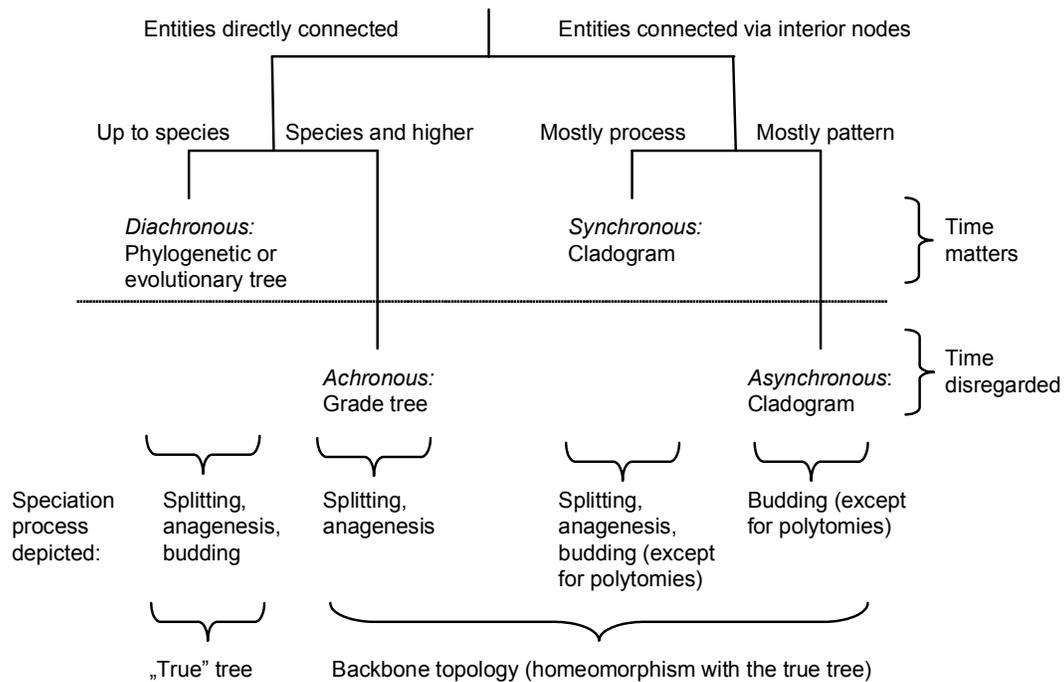


Figure 6. Tree of trees showing major features of tree diagrams and their ability to depict speciation processes as deduced from the simple models used in this study. Major dichotomy is between spanning trees in which entities (populations, taxa) are directly connected and Steiner trees (cladograms) whose interior and terminal vertices have different meaning. Further split within each group is found according to the level of study and the process-pattern contrast, respectively, and based on the time factor (see the horizontal separator). The curly brackets indicate that three tree types reveal at best the backbone topology of the true evolutionary tree, but success depends on the underlying speciation model.