

DIFFERENTIAL INCLUSIONS INVOLVING OSCILLATORY TERMS

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ABSTRACT. Motivated by mechanical problems where external forces are non-smooth, we consider the differential inclusion problem

$$\begin{cases} -\Delta u(x) \in \partial F(u(x)) + \lambda \partial G(u(x)) & \text{in } \Omega; \\ u \geq 0, & \text{in } \Omega; \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (\mathcal{D}_\lambda)$$

where $\Omega \subset \mathbb{R}^n$ is a bounded open domain, and ∂F and ∂G stand for the generalized gradients of the locally Lipschitz functions F and G . In this paper we provide a quite complete picture on the number of solutions of (\mathcal{D}_λ) whenever ∂F oscillates near the origin/infinity and ∂G is a generic perturbation of order $p > 0$ at the origin/infinity, respectively. Our results extend in several aspects those of Kristály and Moroşanu [*J. Math. Pures Appl.*, 2010].

1. INTRODUCTION

We consider the model Dirichlet problem

$$\begin{cases} -\Delta u(x) = f(u(x)) & \text{in } \Omega; \\ u \geq 0, & \text{in } \Omega; \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (P_0)$$

where Δ is the usual Laplace operator, $\Omega \subset \mathbb{R}^n$ is a bounded open domain ($n \geq 2$), and $f : \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function verifying certain growth conditions at the origin and infinity. Usually, such a problem is studied on the Sobolev space $H_0^1(\Omega)$ and weak solutions of (P_0) become classical/strong solutions whenever f has further regularity. There are several approaches to treat problem (P_0) , mainly depending on the behavior of the function f . When f is superlinear and subcritical at infinity (and superlinear at the origin), the seminal paper of Ambrosetti and Rabinowitz [2] guarantees the existence of at least a nontrivial solution of (P_0) by using variational methods. An important extension of (P_0) is its *perturbation*, i.e.,

$$\begin{cases} -\Delta u(x) = f(u(x)) + \lambda g(u(x)) & \text{in } \Omega; \\ u \geq 0, & \text{in } \Omega; \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (P_\lambda)$$

where $g : \mathbb{R} \rightarrow \mathbb{R}$ is another continuous function which is going to compete with the original function f . When both functions f and g are of *polynomial type* of sub- and super-unit degree, – the right hand side being called as a concave-convex nonlinearity – the existence of at least one or two nontrivial solutions of (P_λ) is guaranteed, depending on the range of $\lambda > 0$, see e.g. Ambrosetti, Brezis and Cerami [1], Autuori and Pucci [4], de Figueiredo, Gossez and Ubilla [8]. In these papers variational arguments, sub- and super-solution methods as well as fixed point arguments are employed.

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Dedicated to Professor Gheorghe Moroşanu on the occasion of his 70th birthday.

Another important class of problems of the type (P_λ) is studied whenever f has a certain *oscillation* (near the origin or at infinity) and g is a *perturbation*. Although oscillatory functions seemingly call forth the existence of infinitely many solutions, it turns out that 'too classical' oscillatory functions do not have such a feature. Indeed, when $f(s) = c \sin s$ and $g = 0$, with $c > 0$ small enough, a simple use of the Poincaré inequality implies that problem (P_λ) has only the zero solution. However, when f *strongly* oscillates, problem (P_0) has indeed infinitely many different solutions; see e.g. Omari and Zanolin [19], Saint Raymond [21]. Furthermore, if $g(s) = s^p$ ($s > 0$), a novel competition phenomena has been described for (P_λ) by Kristály and Moroşanu [12]. We notice that several extensions of [12] can be found in the literature, see e.g. Ambrosio, D'Onofrio and Molica Bisci [3] and Molica Bisci and Pizzimenti [16] for nonlocal fractional Laplacians; Molica Bisci, Rădulescu and Servadei [17] for general operators in divergence form; Mălin and Rădulescu [15] for difference equations. We emphasize that in the aforementioned papers the perturbations are either zero or have a (smooth) polynomial form.

In mechanical applications, however, the perturbation may occur in a *discontinuous* manner as a non-regular external force, see e.g. the gluing force in von Kármán laminated plates, cf. Bocea, Panagiotopoulos and Rădulescu [5], Motreanu and Panagiotopoulos [18] and Panagiotopoulos [20]. In order to give a reasonable reformulation of problem (P_λ) in such a non-regular setting, the idea is to 'fill the gaps' of the discontinuities, considering instead of the discontinuous nonlinearity a *set-valued map* appearing as the generalized gradient of a locally Lipschitz function. In this way, we deal with an *elliptic differential inclusion* problem rather than an elliptic differential equation, see e.g. Chang [6], Gazzolla and Rădulescu [9] and Kristály [10]; this problem can be formulated generically as

$$\begin{cases} -\Delta u(x) \in \partial F(u(x)) + \lambda \partial G(u(x)) & \text{in } \Omega; \\ u \geq 0, & \text{in } \Omega; \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (\mathcal{D}_\lambda)$$

where F and G are both nonsmooth, locally Lipschitz functions having various growths, while ∂F and ∂G stand for the generalized gradients of F and G , respectively.

The main purpose of the present paper is to extend the main results of Kristály and Moroşanu [12] in two directions:

- (a) to allow the presence of nonsmooth nonlinear terms – reformulated into the inclusion (\mathcal{D}_λ) – which are more suitable from mechanical point of view (mostly due to the perturbation term G , although we allow non-smoothness for the oscillatory term F as well);
- (b) to consider a generic p -order perturbation ∂G at the origin/infinity, not necessarily of polynomial growth as in [12], $p > 0$.

In the present paper we study the inclusion (\mathcal{D}_λ) in two different settings, i.e., we analyze the number of distinct solutions of (\mathcal{D}_λ) whenever ∂F oscillates near the origin/infinity and ∂G is of order $p > 0$ near the origin/infinity. Roughly speaking, when ∂F *oscillates near the origin* and ∂G *is of order $p > 0$ at the origin*, we prove that the number of distinct, nontrivial solutions of (\mathcal{D}_λ) is

- infinitely many whenever $p > 1$ ($\lambda \geq 0$ is arbitrary) or $p = 1$ and λ is small enough (see Theorem 2.1);
- at least (a prescribed number) $k \in \mathbb{N}$ whenever $0 < p < 1$ and λ is small enough (see Theorem 2.2).

As we can observe, in the first case, the term $\partial G(s) \sim s^p$ as $s \rightarrow 0^+$ with $p > 1$ has no effect on the number of solutions (i.e., the oscillatory term is the leading one), while in the second case, the situation changes dramatically, i.e., ∂G has a 'truth' competition with respect to the oscillatory term ∂F .

We can state a very similar result as above whenever ∂F oscillates at infinity and ∂G is of order $p > 0$ at infinity by proving that the number of distinct, nontrivial solutions of the differential inclusion (\mathcal{D}_λ) is

- infinitely many whenever $p < 1$ ($\lambda \geq 0$ is arbitrary) or $p = 1$ and λ is small enough (see Theorem 2.3);
- at least (a prescribed number) $k \in \mathbb{N}$ whenever $p > 1$ and λ is small enough (see Theorem 2.4).

Contrary to the competition at the origin, in the first case the term $\partial G(s) \sim s^p$ as $s \rightarrow \infty$ with $p < 1$ has no effect on the number of solutions (i.e., the oscillatory term is the leading one), while in the second case, the perturbation term ∂G competes with the oscillator function ∂F .

We admit that the line of the proofs is conceptually similar to that of Kristály and Moroşanu [12]; however, the presence of the nonsmooth terms ∂F and ∂G requires a deep argumentation by fully exploring the nonsmooth calculus of locally Lipschitz functions in the sense of Clarke [7]. In addition, the presence of the generic p -order perturbation ∂G needs a special attention with respect to [12]; in particular, the p -order growth of ∂G is new even in smooth settings.

The organization of the present paper is the following. In Section 2 we state our main assumptions and results, providing also some examples of functions fulfilling the assumptions. Section 3 contains a generic localization theorem for differential inclusions, while Sections 4 and 5 are devoted to the proof of our main results. In Section 6 we formulate some concluding remarks, while in the Appendix (Section 7) we collect those notions and results on locally Lipschitz functions that are used throughout our arguments.

2. MAIN THEOREMS

Let $F, G : \mathbb{R}_+ \rightarrow \mathbb{R}$ be locally Lipschitz functions and as usual, let us denote by ∂F and ∂G their generalized gradients in the sense of Clarke (see the Appendix). Hereafter, $\mathbb{R}_+ = [0, \infty)$. Let $p > 0$, $\lambda \geq 0$ and $\Omega \subset \mathbb{R}^n$ be a bounded open domain, and consider the elliptic differential inclusion problem

$$\begin{cases} -\Delta u(x) \in \partial F(u(x)) + \lambda \partial G(u(x)) & \text{in } \Omega; \\ u \geq 0 & \text{in } \Omega; \\ u = 0, & \text{on } \partial\Omega. \end{cases} \quad (\mathcal{D}_\lambda)$$

We distinguish the cases when ∂F oscillates near the *origin* or at *infinity*.

2.1. Oscillation near the origin. We assume:

- (F_0^0) $F(0) = 0$;
- (F_1^0) $-\infty < \liminf_{s \rightarrow 0^+} \frac{F(s)}{s^2}$; $\limsup_{s \rightarrow 0^+} \frac{F(s)}{s^2} = +\infty$;
- (F_2^0) $l_0 := \liminf_{s \rightarrow 0^+} \frac{\max\{\xi : \xi \in \partial F(s)\}}{s} < 0$.
- (G_0^0) $G(0) = 0$;
- (G_1^0) There exist $p > 0$ and $\underline{c}, \bar{c} \in \mathbb{R}$ such that

$$\underline{c} = \liminf_{s \rightarrow 0^+} \frac{\min\{\xi : \xi \in \partial G(s)\}}{s^p} \leq \limsup_{s \rightarrow 0^+} \frac{\max\{\xi : \xi \in \partial G(s)\}}{s^p} = \bar{c}.$$

Remark 2.1. Hypotheses (F_1^0) and (F_2^0) imply a strong oscillatory behavior of ∂F near the origin. Moreover, it turns out that $0 \in \partial F(0)$; indeed, if we assume the contrary, by the upper semicontinuity of ∂F we also have that $0 \notin \partial F(s)$ for every small $s > 0$. Thus, by (F_2^0) we have that $\partial F(s) \subset (-\infty, 0]$ for these values of $s > 0$. By using (F_0^0) and Lebourg's mean value theorem (see Proposition 7.3 in the Appendix), it follows that $F(s) = F(s) - F(0) = \xi s \leq 0$ for some $\xi \in \partial F(\theta s) \subset (-\infty, 0]$ with $\theta \in (0, 1)$. The latter inequality contradicts the second assumption from (F_1^0) . Similarly, one obtains that $0 \in \partial G(0)$ by exploring (G_0^0) and (G_1^0) , respectively.

In conclusion, since $0 \in \partial F(0)$ and $0 \in \partial G(0)$, it turns out that $0 \in H_0^1(\Omega)$ is a solution of the differential inclusion (\mathcal{D}_λ) . Clearly, we are interested in nonzero solutions of (\mathcal{D}_λ) .

Example 2.1. Let us consider $F_0(s) = \int_0^s f_0(t) dt$, $s \geq 0$, where $f_0(t) = \sqrt{t}(\frac{1}{2} + \sin t^{-1})$, $t > 0$ and $f_0(0) = 0$, or some of its jumping variants. One can prove that $\partial F_0 = f_0$ verifies the assumptions $(F_0^0) - (F_2^0)$. For a fixed $p > 0$, let $G_0(s) = \ln(1 + s^{p+2}) \max\{0, \cos s^{-1}\}$, $s > 0$ and $G_0(0) = 0$. It is clear that G_0 is not of class C^1 and verifies (G_1^0) with $\underline{c} = -1$ and $\bar{c} = 1$, respectively; see Figure 1 representing both f_0 and G_0 (for $p = 2$).

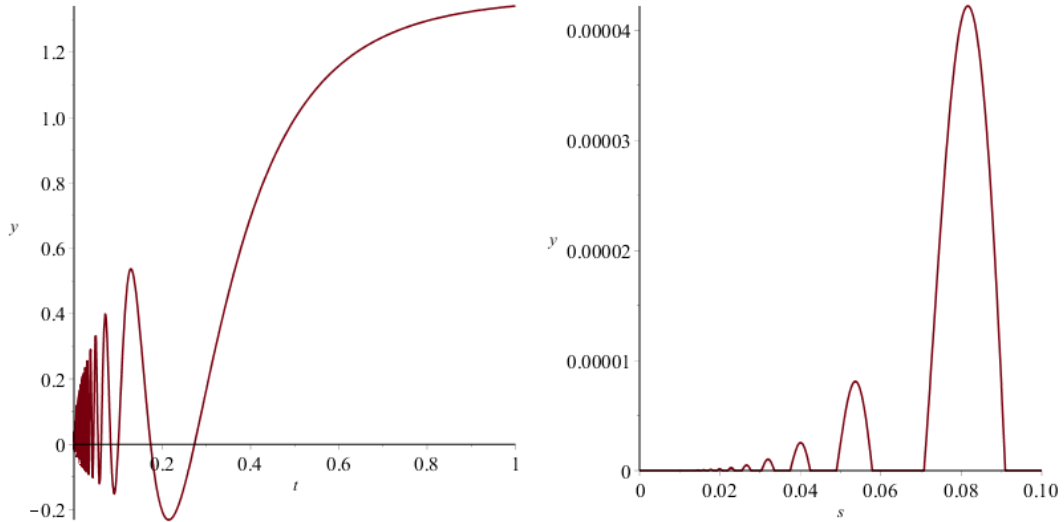


FIGURE 1. Graphs of f_0 and G_0 around the origin, respectively.

In the sequel, we provide a quite complete picture about the competition concerning the terms $s \mapsto \partial F(s)$ and $s \mapsto \partial G(s)$, respectively. First, we are going to show that when $p \geq 1$ then the 'leading' term is the oscillatory function ∂F ; roughly speaking, one can say that the effect of $s \mapsto \partial G(s)$ is negligible in this competition. More precisely, we prove the following result.

Theorem 2.1. (Case $p \geq 1$) Assume that $p \geq 1$ and the locally Lipschitz functions $F, G : \mathbb{R}_+ \rightarrow \mathbb{R}$ satisfy $(F_0^0) - (F_2^0)$ and $(G_0^0) - (G_1^0)$. If

- (i) either $p = 1$ and $\lambda \bar{c} < -l_0$ (with $\lambda \geq 0$),
- (ii) or $p > 1$ and $\lambda \geq 0$ is arbitrary,

then the differential inclusion problem (\mathcal{D}_λ) admits a sequence $\{u_i\}_i \subset H_0^1(\Omega)$ of distinct weak solutions such that

$$\lim_{i \rightarrow \infty} \|u_i\|_{H_0^1} = \lim_{i \rightarrow \infty} \|u_i\|_{L^\infty} = 0. \quad (2.1)$$

In the case when $p < 1$, the perturbation term ∂G may compete with the oscillatory function ∂F ; namely, we have:

Theorem 2.2. (Case $0 < p < 1$) Assume $0 < p < 1$ and that the locally Lipschitz functions $F, G : \mathbb{R}_+ \rightarrow \mathbb{R}$ satisfy $(F_0^0) - (F_2^0)$ and $(G_0^0) - (G_1^0)$. Then, for every $k \in \mathbb{N}$, there exists $\lambda_k > 0$ such that the differential inclusion (\mathcal{D}_λ) has at least k distinct weak solutions $\{u_{1,\lambda}, \dots, u_{k,\lambda}\} \subset H_0^1(\Omega)$ whenever $\lambda \in [0, \lambda_k]$. Moreover,

$$\|u_{i,\lambda}\|_{H_0^1} < i^{-1} \quad \text{and} \quad \|u_{i,\lambda}\|_{L^\infty} < i^{-1} \quad \text{for any } i = \overline{1, k}; \quad \lambda \in [0, \lambda_k]. \quad (2.2)$$

2.2. Oscillation at infinity. Let assume:

- (F_0^∞) $F(0) = 0$;
- (F_1^∞) $-\infty < \liminf_{s \rightarrow \infty} \frac{F(s)}{s^2}; \limsup_{s \rightarrow \infty} \frac{F(s)}{s^2} = +\infty$;
- (F_2^∞) $l_\infty := \liminf_{s \rightarrow \infty} \frac{\max\{\xi : \xi \in \partial F(s)\}}{s} < 0$.
- (G_0^∞) $G(0) = 0$;
- (G_1^∞) There exist $p > 0$ and $\underline{c}, \bar{c} \in \mathbb{R}$ such that

$$\underline{c} = \liminf_{s \rightarrow \infty} \frac{\min\{\xi : \xi \in \partial G(s)\}}{s^p} \leq \limsup_{s \rightarrow \infty} \frac{\max\{\xi : \xi \in \partial G(s)\}}{s^p} = \bar{c}.$$

Remark 2.2. Hypotheses (F_1^∞) and (F_2^∞) imply a strong oscillatory behavior of the set-valued map ∂F at infinity.

Example 2.2. We consider $F_\infty(s) = \int_0^s f_\infty(t) dt$, $s \geq 0$, where $f_\infty(t) = \sqrt{t}(\frac{1}{2} + \sin t)$, $t \geq 0$, or some of its jumping variants; one has that F_∞ verifies the assumptions $(F_0^\infty) - (F_2^\infty)$. For a fixed $p > 0$, let $G_\infty(s) = s^p \max\{0, \sin s\}$, $s \geq 0$; it is clear that G_∞ is a typically locally Lipschitz function on $[0, \infty)$ (not being of class C^1) and verifies (G_1^∞) with $\underline{c} = -1$ and $\bar{c} = 1$; see Figure 2 representing both f_∞ and G_∞ (for $p = 2$), respectively.

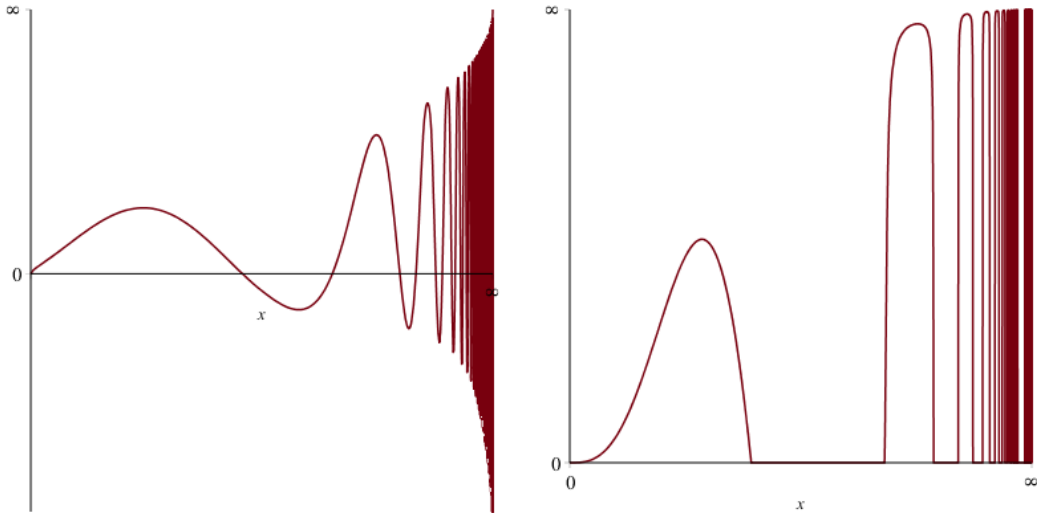


FIGURE 2. Graphs of f_∞ and G_∞ at infinity, respectively.

In the sequel, we investigate the competition at infinity concerning the terms $s \mapsto \partial F(s)$ and $s \mapsto \partial G(s)$, respectively. First, we show that when $p \leq 1$ then the 'leading' term is the oscillatory function F , i.e., the effect of $s \mapsto \partial G(s)$ is negligible. More precisely, we prove the following result:

Theorem 2.3. (Case $p \leq 1$) *Assume that $p \leq 1$ and the locally Lipschitz functions $F, G : \mathbb{R}_+ \rightarrow \mathbb{R}$ satisfy $(F_0^\infty) - (F_2^\infty)$ and $(G_0^\infty) - (G_1^\infty)$. If*

- (i) *either $p = 1$ and $\lambda \bar{c} \leq -l_0$ (with $\lambda \geq 0$),*
- (ii) *or $p < 1$ and $\lambda \geq 0$ is arbitrary,*

then the differential inclusion (\mathcal{D}_λ) admits a sequence $\{u_i\}_i \subset H_0^1(\Omega)$ of distinct weak solutions such that

$$\lim_{i \rightarrow \infty} \|u_i^\infty\|_{L^\infty} = \infty. \quad (2.3)$$

Remark 2.3. Let 2^* be the usual critical Sobolev exponent. In addition to (2.3), we also have $\lim_{i \rightarrow \infty} \|u_i^\infty\|_{H_0^1} = \infty$ whenever

$$\sup_{s \in [0, \infty)} \frac{\max\{|\xi| : \xi \in \partial F(s)\}}{1 + s^{2^*-1}} < \infty. \quad (2.4)$$

In the case when $p > 1$, it turns out that the perturbation term ∂G may compete with the oscillatory function ∂F ; more precisely, we have:

Theorem 2.4. (Case $p > 1$) *Assume that $p > 1$ and the locally Lipschitz functions $F, G : \mathbb{R}_+ \rightarrow \mathbb{R}$ satisfy $(F_0^\infty) - (F_2^\infty)$ and $(G_0^\infty) - (G_1^\infty)$. Then, for every $k \in \mathbb{N}$, there exists $\lambda_k^\infty > 0$ such that the differential inclusion (\mathcal{D}_λ) has at least k distinct weak solutions $\{u_{1,\lambda}, \dots, u_{k,\lambda}\} \subset H_0^1(\Omega)$ whenever $\lambda \in [0, \lambda_k^\infty]$. Moreover,*

$$\|u_{i,\lambda}\|_{L^\infty} > i - 1 \quad \text{for any } i = \overline{1, k}; \quad \lambda \in [0, \lambda_k^\infty]. \quad (2.5)$$

Remark 2.4. If (2.4) holds and $p \leq 2^* - 1$ in Theorem 2.4, then we have in addition that

$$\|u_{i,\lambda}^\infty\|_{H_0^1} > i - 1 \quad \text{for any } i = \overline{1, k}; \quad \lambda \in [0, \lambda_k^\infty].$$

3. LOCALIZATION: A GENERIC RESULT

We consider the following differential inclusion problem

$$\begin{cases} -\Delta u(x) + ku(x) \in \partial A(u(x)), & u(x) \geq 0 & x \in \Omega, \\ u(x) = 0 & & x \in \partial\Omega, \end{cases} \quad (\mathcal{D}_A^k)$$

where $k > 0$ and

(H_A¹): $A : [0, \infty) \rightarrow \mathbb{R}$ is a locally Lipschitz function with $A(0) = 0$, and there is $M_A > 0$ such that

$$\max\{|\partial A(s)|\} := \max\{|\xi| : \xi \in \partial A(s)\} \leq M_A$$

for every $s \geq 0$;

(H_A²): there are $0 < \delta < \eta$ such that $\max\{\xi : \xi \in \partial A(s)\} \leq 0$ for every $s \in [\delta, \eta]$.

For simplicity, we extend the function A by $A(s) = 0$ for $s \leq 0$; the extended function is locally Lipschitz on the whole \mathbb{R} . The natural energy functional $\mathcal{T} : H_0^1(\Omega) \rightarrow \mathbb{R}$ associated with the differential inclusion problem (\mathcal{D}_A^k) is defined by

$$\mathcal{T}(u) = \frac{1}{2} \|u\|_{H_0^1}^2 + \frac{k}{2} \int_{\Omega} u^2 dx - \int_{\Omega} A(u(x)) dx.$$

The energy functional \mathcal{T} is well defined and locally Lipschitz on $H_0^1(\Omega)$, while its critical points in the sense of Chang (see Definition 7.3 in the Appendix) are precisely the weak solutions of the differential inclusion problem

$$\begin{cases} -\Delta u(x) + ku(x) \in \partial A(u(x)), & x \in \Omega, \\ u(x) = 0 & x \in \partial\Omega; \end{cases} \quad (\mathbf{D}_A^{k,0})$$

note that at this stage we have no information on the sign of u .

Indeed, if $0 \in \partial\mathcal{T}(u)$, then for every $v \in H_0^1(\Omega)$ we have

$$\int_{\Omega} \nabla u(x) \nabla v(x) dx - k \int_{\Omega} u(x)v(x) dx - \int_{\Omega} \xi_x(x)v(x) dx = 0,$$

where $\xi_x \in \partial A(u(x))$ a.e. $x \in \Omega$, see e.g. Motreanu and Panagiotopoulos [18]. By using the divergence theorem for the first term at the left hand side (and exploring the Dirichlet boundary condition), we obtain that

$$\int_{\Omega} \nabla u(x) \nabla v(x) dx = - \int_{\Omega} \operatorname{div}(\nabla u(x))v(x) dx = - \int_{\Omega} \Delta u(x)v(x) dx.$$

Accordingly, we have that

$$- \int_{\Omega} \Delta u(x)v(x) dx + k \int_{\Omega} u(x)v(x) dx = \int_{\Omega} \xi_x v(x) dx$$

for every test function $v \in H_0^1(\Omega)$ which means that $-\Delta u(x) + ku(x) \in \partial A(u(x))$ in the weak sense in Ω , as claimed before.

Let us consider the number $\eta \in \mathbb{R}$ from (\mathbf{H}_A^2) and the set

$$W^\eta = \{u \in H_0^1(\Omega) : \|u\|_{L^\infty} \leq \eta\}.$$

Our localization result reads as follows (see [12, Theorem 2.1] for its smooth form):

Theorem 3.1. *Let $k > 0$ and assume that hypotheses (\mathbf{H}_A^1) and (\mathbf{H}_A^2) hold. Then*

- (i) *the energy functional \mathcal{T} is bounded from below on W^η and its infimum is attained at some $\tilde{u} \in W^\eta$;*
- (ii) *$\tilde{u}(x) \in [0, \delta]$ for a.e. $x \in \Omega$;*
- (iii) *\tilde{u} is a weak solution of the differential inclusion (\mathbf{D}_A^k) .*

Proof. The proof is similar to that of Kristály and Moroşanu [12]; for completeness, we provide its main steps.

(i) Due to (\mathbf{H}_A^1) , it is clear that the energy functional \mathcal{T} is bounded from below on $H_0^1(\Omega)$. Moreover, due to the compactness of the embedding $H_0^1(\Omega) \subset L^q(\Omega)$, $q \in [2, 2^*)$, it turns out that \mathcal{T} is sequentially weak lower semi-continuous on $H_0^1(\Omega)$. In addition, the set W^η is weakly closed, being convex and closed in $H_0^1(\Omega)$. Thus, there is $\tilde{u} \in W^\eta$ which is a minimum point of \mathcal{T} on the set W^η , cf. Zeidler [24].

(ii) We introduce the set $L = \{x \in \Omega : \tilde{u}(x) \notin [0, \delta]\}$ and suppose indirectly that $m(L) > 0$. Define the function $\gamma : \mathbb{R} \rightarrow \mathbb{R}$ by $\gamma(s) = \min(s_+, \delta)$, where $s_+ = \max(s, 0)$. Now, set $w = \gamma \circ \tilde{u}$. It is clear that γ is a Lipschitz function and $\gamma(0) = 0$. Accordingly, based on the superposition theorem of Marcus and Mizel [14], one has that $w \in H_0^1(\Omega)$. Moreover, $0 \leq w(x) \leq \delta$ for a.e. Ω . Consequently, $w \in W^\eta$.

Let us introduce the sets

$$L_1 = \{x \in L : \tilde{u}(x) < 0\} \quad \text{and} \quad L_2 = \{x \in L : \tilde{u}(x) > \delta\}.$$

In particular, $L = L_1 \cup L_2$, and by definition, it follows that $w(x) = \tilde{u}(x)$ for all $x \in \Omega \setminus L$, $w(x) = 0$ for all $x \in L_1$, and $w(x) = \delta$ for all $x \in L_2$. In addition, one has

$$\begin{aligned} \mathcal{T}(w) - \mathcal{T}(\tilde{u}) &= \frac{1}{2} \left[\|w\|_{H_0^1}^2 - \|\tilde{u}\|_{H_0^1}^2 \right] + \frac{k}{2} \int_{\Omega} [w^2 - \tilde{u}^2] - \int_{\Omega} [A(w(x)) - A(\tilde{u}(x))] \\ &= -\frac{1}{2} \int_L |\nabla \tilde{u}|^2 + \frac{k}{2} \int_L [w^2 - \tilde{u}^2] - \int_L [A(w(x)) - A(\tilde{u}(x))]. \end{aligned}$$

On account of $k > 0$, we have

$$k \int_L [w^2 - \tilde{u}^2] = -k \int_{L_1} \tilde{u}^2 + k \int_{L_2} [\delta^2 - \tilde{u}^2] \leq 0.$$

Since $A(s) = 0$ for all $s \leq 0$, we have

$$\int_{L_1} [A(w(x)) - A(\tilde{u}(x))] = 0.$$

By means of the Lebourg's mean value theorem, for a.e. $x \in L_2$, there exists $\theta(x) \in [\delta, \tilde{u}(x)] \subseteq [\delta, \eta]$ such that

$$A(w(x)) - A(\tilde{u}(x)) = A(\delta) - A(\tilde{u}(x)) = a(\theta(x))(\delta - \tilde{u}(x)),$$

where $a(\theta(x)) \in \partial A(\theta(x))$. Due to (H_A^2) , it turns out that

$$\int_{L_2} [A(w(x)) - A(\tilde{u}(x))] \geq 0.$$

Therefore, we obtain that $\mathcal{T}(w) - \mathcal{T}(\tilde{u}) \leq 0$. On the other hand, since $w \in W^\eta$, then $\mathcal{T}(w) \geq \mathcal{T}(\tilde{u}) = \inf_{W^\eta} \mathcal{T}$, thus every term in the difference $\mathcal{T}(w) - \mathcal{T}(\tilde{u})$ should be zero; in particular,

$$\int_{L_1} \tilde{u}^2 = \int_{L_2} [\tilde{u}^2 - \delta^2] = 0.$$

The latter relation implies in particular that $m(L) = 0$, which is a contradiction, completing the proof of (ii).

(iii) Since $\tilde{u}(x) \in [0, \delta]$ for a.e. $x \in \Omega$, an arbitrarily small perturbation $\tilde{u} + \epsilon v$ of \tilde{u} with $0 < \epsilon \ll 1$ and $v \in C_0^\infty(\Omega)$ still implies that $\mathcal{T}(\tilde{u} + \epsilon v) \geq \mathcal{T}(\tilde{u})$; accordingly, \tilde{u} is a minimum point for \mathcal{T} in the strong topology of $H_0^1(\Omega)$, thus $0 \in \partial \mathcal{T}(\tilde{u})$, cf. Remark 7.1 in the Appendix. Consequently, it follows that \tilde{u} is a weak solution of the differential inclusion (D_A^k) . \square

In the sequel, we need a truncation function of $H_0^1(\Omega)$, see also [12]. To construct this function, let $B(x_0, r) \subset \Omega$ be the n -dimensional ball with radius $r > 0$ and center $x_0 \in \Omega$. For $s > 0$, define

$$w_s(x) = \begin{cases} 0, & \text{if } x \in \Omega \setminus B(x_0, r); \\ s, & \text{if } x \in B(x_0, r/2); \\ \frac{2s}{r}(r - |x - x_0|), & \text{if } x \in B(x_0, r) \setminus B(x_0, r/2). \end{cases} \quad (3.1)$$

Note that $w_s \in H_0^1(\Omega)$, $\|w_s\|_{L^\infty} = s$ and

$$\|w_s\|_{H_0^1}^2 = \int_{\Omega} |\nabla w_s|^2 = 4r^{n-2}(1 - 2^{-n})\omega_n s^2 \equiv C(r, n)s^2 > 0; \quad (3.2)$$

hereafter ω_n stands for the volume of $B(0, 1) \subset \mathbb{R}^n$.

4. PROOF OF THEOREMS 2.1 AND 2.2

Before giving the proof of Theorems 2.1 and 2.2, in the first part of this section we study the differential inclusion problem

$$\begin{cases} -\Delta u(x) + ku(x) \in \partial A(u(x)), & u(x) \geq 0 & x \in \Omega, \\ u(x) = 0 & & x \in \partial\Omega, \end{cases} \quad (\text{D}_A^k)$$

where $k > 0$ and the locally Lipschitz function $A : \mathbb{R}_+ \rightarrow \mathbb{R}$ verifies

$$(\text{H}_0^0): A(0) = 0;$$

$$(\text{H}_1^0): -\infty < \liminf_{s \rightarrow 0^+} \frac{A(s)}{s^2} \text{ and } \limsup_{s \rightarrow 0^+} \frac{A(s)}{s^2} = +\infty;$$

$$(\text{H}_2^0): \text{there are two sequences } \{\delta_i\}, \{\eta_i\} \text{ with } 0 < \eta_{i+1} < \delta_i < \eta_i, \lim_{i \rightarrow \infty} \eta_i = 0, \text{ and}$$

$$\max\{\partial A(s)\} := \max\{\xi : \xi \in \partial A(s)\} \leq 0$$

for every $s \in [\delta_i, \eta_i]$, $i \in \mathbb{N}$.

Theorem 4.1. *Let $k > 0$ and assume hypotheses (H_0^0) , (H_1^0) and (H_2^0) hold. Then there exists a sequence $\{u_i^0\}_i \subset H_0^1(\Omega)$ of distinct weak solutions of the differential inclusion problem (D_A^k) such that*

$$\lim_{i \rightarrow \infty} \|u_i^0\|_{H_0^1} = \lim_{i \rightarrow \infty} \|u_i^0\|_{L^\infty} = 0. \quad (4.1)$$

Proof. We may assume that $\{\delta_i\}_i, \{\eta_i\}_i \subset (0, 1)$. For any fixed number $i \in \mathbb{N}$, we define the locally Lipschitz function $A_i : \mathbb{R} \rightarrow \mathbb{R}$ by

$$A_i(s) = A(\tau_{\eta_i}(s)), \quad (4.2)$$

where $A(s) = 0$ for $s \leq 0$ and $\tau_\eta : \mathbb{R} \rightarrow \mathbb{R}$ denotes the truncation function $\tau_\eta(s) = \min(\eta, s)$, $\eta > 0$. For further use, we introduce the energy functional $\mathcal{T}_i : H_0^1(\Omega) \rightarrow \mathbb{R}$ associated with problem $(\text{D}_{A_i}^k)$.

We notice that for $s \geq 0$, the chain rule (see Proposition 7.4 in the Appendix) gives

$$\partial A_i(s) = \begin{cases} \partial A(s) & \text{if } s < \eta_i, \\ \overline{\text{co}}\{0, \partial A(\eta_i)\} & \text{if } s = \eta_i, \\ \{0\} & \text{if } s > \eta_i. \end{cases}$$

It turns out that on the compact set $[0, \eta_i]$, the upper semicontinuous set-valued map $s \mapsto \partial A_i(s)$ attains its supremum (see Proposition 7.1 in the Appendix); therefore, there exists $M_{A_i} > 0$ such that

$$\max|\partial A_i(s)| := \max\{|\xi| : \xi \in \partial A_i(s)\} \leq M_{A_i}$$

for every $s \geq 0$, i.e., $(\text{H}_{A_i}^1)$ holds. The same is true for $(\text{H}_{A_i}^2)$ by using (H_2^0) on $[\delta_i, \eta_i]$, $i \in \mathbb{N}$.

Accordingly, the assumptions of Theorem 3.1 are verified for every $i \in \mathbb{N}$ with $[\delta_i, \eta_i]$, thus there exists $u_i^0 \in W^{\eta_i}$ such that

$$u_i^0 \text{ is the minimum point of the functional } \mathcal{T}_i \text{ on } W^{\eta_i}, \quad (4.3)$$

$$u_i^0(x) \in [0, \delta_i] \text{ for a.e. } x \in \Omega, \quad (4.4)$$

$$u_i^0 \text{ is a solution of } (\text{D}_{A_i}^k). \quad (4.5)$$

On account of relations (4.2), (4.4) and (4.5), u_i^0 is a weak solution also for the differential inclusion problem (D_A^k) .

We are going to prove that there are infinitely many distinct elements in the sequence $\{u_i^0\}_i$. To conclude it, we first prove that

$$\mathcal{T}_i(u_i^0) < 0 \text{ for all } i \in \mathbb{N}; \text{ and} \quad (4.6)$$

$$\lim_{i \rightarrow \infty} \mathcal{T}_i(u_i^0) = 0. \quad (4.7)$$

The left part of (H_1^0) implies the existence of some $l_0 > 0$ and $\zeta \in (0, \eta_1)$ such that

$$A(s) \geq -l_0 s^2 \text{ for all } s \in (0, \zeta). \quad (4.8)$$

One can choose $L_0 > 0$ such that

$$\frac{1}{2}C(r, n) + \left(\frac{k}{2} + l_0\right) m(\Omega) < L_0(r/2)^n \omega_n, \quad (4.9)$$

where $r > 0$ and $C(r, n) > 0$ come from (3.2). Based on the right part of (H_1^0) , one can find a sequence $\{\tilde{s}_i\}_i \subset (0, \zeta)$ such that $\tilde{s}_i \leq \delta_i$ and

$$A(\tilde{s}_i) > L_0 \tilde{s}_i^2 \text{ for all } i \in \mathbb{N}. \quad (4.10)$$

Let $i \in \mathbb{N}$ be a fixed number and let $w_{\tilde{s}_i} \in H_0^1(\Omega)$ be the function from (3.1) corresponding to the value $\tilde{s}_i > 0$. Then $w_{\tilde{s}_i} \in W^{n_i}$, and due to (4.8), (4.10) and (3.2) one has

$$\begin{aligned} \mathcal{T}_i(w_{\tilde{s}_i}) &= \frac{1}{2} \|w_{\tilde{s}_i}\|_{H_0^1}^2 + \frac{k}{2} \int_{\Omega} w_{\tilde{s}_i}^2 - \int_{\Omega} A_i(w_{\tilde{s}_i}(x)) dx \\ &= \frac{1}{2} C(r, n) \tilde{s}_i^2 + \frac{k}{2} \int_{\Omega} w_{\tilde{s}_i}^2 - \int_{B(x_0, r/2)} A(\tilde{s}_i) dx - \int_{B(x_0, r) \setminus B(x_0, r/2)} A(w_{\tilde{s}_i}(x)) dx \\ &\leq \left[\frac{1}{2} C(r, n) + \frac{k}{2} m(\Omega) - L_0(r/2)^n \omega_n + l_0 m(\Omega) \right] \tilde{s}_i^2. \end{aligned}$$

Accordingly, with (4.3) and (4.9), we conclude that

$$\mathcal{T}_i(u_i^0) = \min_{W^{n_i}} \mathcal{T}_i \leq \mathcal{T}_i(w_{\tilde{s}_i}) < 0 \quad (4.11)$$

which completes the proof of (4.6).

Now, we prove (4.7). For every $i \in \mathbb{N}$, by using the Lebourg's mean value theorem, relations (4.2) and (4.4) and (H_0^0) , we have

$$\mathcal{T}_i(u_i^0) \geq - \int_{\Omega} A_i(u_i^0(x)) dx = - \int_{\Omega} A_1(u_i^0(x)) dx \geq -M_{A_1} m(\Omega) \delta_i.$$

Since $\lim_{i \rightarrow \infty} \delta_i = 0$, the latter estimate and (4.11) provides relation (4.7).

Based on (4.2) and (4.4), we have that $\mathcal{T}_i(u_i^0) = \mathcal{T}_1(u_i^0)$ for all $i \in \mathbb{N}$. This relation with (4.6) and (4.7) means that the sequence $\{u_i^0\}_i$ contains infinitely many distinct elements.

We now prove (4.1). One can prove the former limit by (4.4), i.e. $\|u_i^0\|_{L^\infty} \leq \delta_i$ for all $i \in \mathbb{N}$, combined with $\lim_{i \rightarrow \infty} \delta_i = 0$. For the latter limit, we use $k > 0$, (4.11), (4.2) and (4.4) to get for all $i \in \mathbb{N}$ that

$$\frac{1}{2} \|u_i^0\|_{H_0^1}^2 \leq \frac{1}{2} \|u_i^0\|_{H_0^1}^2 + \frac{k}{2} \int_{\Omega} (u_i^0)^2 < \int_{\Omega} A_i(u_i^0(x)) = \int_{\Omega} A_1(u_i^0(x)) \leq M_{A_1} m(\Omega) \delta_i,$$

which completes the proof. \square

Proof of Theorem 2.1. We split the proof into two parts.

(i) *Case $p = 1$.* Let $\lambda \geq 0$ with $\lambda\bar{c} < -l_0$ and fix $\tilde{\lambda}_0 \in \mathbb{R}$ such that $\lambda\bar{c} < \tilde{\lambda}_0 < -l_0$. With these choices we define

$$k := \tilde{\lambda}_0 - \lambda\bar{c} > 0 \quad \text{and} \quad A(s) := F(s) + \frac{\tilde{\lambda}_0}{2}s^2 + \lambda \left(G(s) - \frac{\bar{c}}{2}s^2 \right) \quad \text{for every } s \in [0, \infty). \quad (4.12)$$

It is clear that $A(0) = 0$, i.e., (H_0^0) is verified. Since $p = 1$, by (G_1^0) one has

$$\underline{c} = \liminf_{s \rightarrow 0^+} \frac{\min\{\partial G(s)\}}{s} \leq \limsup_{s \rightarrow 0^+} \frac{\max\{\partial G(s)\}}{s} = \bar{c}.$$

In particular, for sufficiently small $\epsilon > 0$ there exists $\gamma = \gamma(\epsilon) > 0$ such that

$$\max\{\partial G(s)\} - \bar{c}s < \epsilon s, \quad \forall s \in [0, \gamma],$$

and

$$\min\{\partial G(s)\} - \underline{c}s > -\epsilon s, \quad \forall s \in [0, \gamma].$$

For $s \in [0, \gamma]$, Lebourg's mean value theorem and $G(0) = 0$ implies that there exists $\xi_s \in \partial G(\theta_s s)$ for some $\theta_s \in [0, 1]$ such that $G(s) - G(0) = \xi_s s$. Accordingly, for every $s \in [0, \gamma]$ we have that

$$(\underline{c} - \epsilon)s^2 \leq G(s) \leq (\bar{c} + \epsilon)s^2. \quad (4.13)$$

By (4.13) and (F_1^0) we have that

$$\liminf_{s \rightarrow 0^+} \frac{A(s)}{s^2} \geq \liminf_{s \rightarrow 0^+} \frac{F(s)}{s^2} + \frac{\tilde{\lambda}_0 - \lambda\bar{c}}{2} + \lambda \liminf_{s \rightarrow 0^+} \frac{G(s)}{s^2} \geq \liminf_{s \rightarrow 0^+} \frac{F(s)}{s^2} + \frac{\tilde{\lambda}_0 - \lambda\bar{c}}{2} + \lambda\underline{c} > -\infty$$

and

$$\limsup_{s \rightarrow 0^+} \frac{A(s)}{s^2} \geq \limsup_{s \rightarrow 0^+} \frac{F(s)}{s^2} + \frac{\tilde{\lambda}_0 - \lambda\bar{c}}{2} + \lambda \liminf_{s \rightarrow 0^+} \frac{G(s)}{s^2} = +\infty,$$

i.e., (H_1^0) is verified.

Since

$$\partial A(s) \subseteq \partial F(s) + \tilde{\lambda}_0 s + \lambda(\partial G(s) - \bar{c}s), \quad (4.14)$$

and $\lambda \geq 0$, we have that

$$\max\{\partial A(s)\} \leq \max\{\partial F(s) + \tilde{\lambda}_0 s\} + \lambda \max\{\partial G(s) - \bar{c}s\}. \quad (4.15)$$

Since

$$\limsup_{s \rightarrow 0^+} \frac{\max\{\partial G(s)\}}{s} = \bar{c},$$

cf. (G_1^0) , and

$$\liminf_{s \rightarrow 0^+} \frac{\max\{\partial F(s)\}}{s} = l_0 < 0,$$

cf. (F_2^0) , it turns out by (4.15) that

$$\liminf_{s \rightarrow 0^+} \frac{\max\{\partial A(s)\}}{s} \leq \liminf_{s \rightarrow 0^+} \frac{\max\{\partial F(s)\}}{s} + \tilde{\lambda}_0 - \lambda\bar{c} + \lambda \limsup_{s \rightarrow 0^+} \frac{\max\{\partial G(s)\}}{s} \leq l_0 + \tilde{\lambda}_0 < 0.$$

Therefore, one has a sequence $\{s_i\}_i \subset (0, 1)$ converging to 0 such that $\frac{\max\{\partial A(s_i)\}}{s_i} < 0$ i.e., $\max\{\partial A(s_i)\} < 0$ for all $i \in \mathbb{N}$. By using the upper semicontinuity of $s \mapsto \partial A(s)$, we may choose two numbers $\delta_i, \eta_i \in (0, 1)$ with $\delta_i < s_i < \eta_i$ such that $\partial A(s) \subset \partial A(s_i) + [-\epsilon_i, \epsilon_i]$ for every $s \in [\delta_i, \eta_i]$, where $\epsilon_i := -\max\{\partial A(s_i)\}/2 > 0$. In particular, $\max\{\partial A(s)\} \leq 0$ for all $s \in [\delta_i, \eta_i]$. Thus, one may fix two sequences $\{\delta_i\}_i, \{\eta_i\}_i \subset (0, 1)$ such that $0 < \eta_{i+1} < \delta_i < s_i < \eta_i$, $\lim_{i \rightarrow \infty} \eta_i = 0$, and $\max\{\partial A(s)\} \leq 0$ for all $s \in [\delta_i, \eta_i]$ and $i \in \mathbb{N}$. Accordingly, (H_2^0) is verified as

well. Let us apply Theorem 4.1 with the choice (4.12), i.e., there exists a sequence $\{u_i\}_i \subset H_0^1(\Omega)$ of different elements such that

$$\begin{cases} -\Delta u_i(x) + (\tilde{\lambda}_0 - \lambda \bar{c})u_i(x) \in \partial F(u_i(x)) + \tilde{\lambda}_0 u_i(x) + \lambda(\partial G(u_i(x)) - \bar{c}u_i(x)) & x \in \Omega, \\ u_i(x) \geq 0 & x \in \Omega, \\ u_i(x) = 0 & x \in \partial\Omega, \end{cases}$$

where we used the inclusion (4.14). In particular, u_i solves problem (\mathcal{D}_λ) , $i \in \mathbb{N}$, which completes the proof of (i).

(ii) *Case* $p > 1$. Let $\lambda \geq 0$ be arbitrary fixed and choose a number $\lambda_0 \in (0, -l_0)$. Let

$$k := \lambda_0 > 0 \quad \text{and} \quad A(s) := F(s) + \lambda G(s) + \lambda_0 \frac{s^2}{2} \quad \text{for every } s \in [0, \infty). \quad (4.16)$$

Since $F(0) = G(0) = 0$, hypothesis (H_0^0) clearly holds. By (G_1^0) one has

$$\underline{c} = \liminf_{s \rightarrow 0^+} \frac{\min\{\partial G(s)\}}{s^p} \leq \limsup_{s \rightarrow 0^+} \frac{\max\{\partial G(s)\}}{s^p} = \bar{c}.$$

In particular, since $p > 1$, then

$$\lim_{s \rightarrow 0^+} \frac{\min\{\partial G(s)\}}{s} = \lim_{s \rightarrow 0^+} \frac{\max\{\partial G(s)\}}{s} = 0 \quad (4.17)$$

and for sufficiently small $\epsilon > 0$ there exists $\gamma = \gamma(\epsilon) > 0$ such that

$$\max\{\partial G(s)\} - \bar{c}s^p < \epsilon s^p, \quad \forall s \in [0, \gamma]$$

and

$$\min\{\partial G(s)\} - \underline{c}s^p > -\epsilon s^p, \quad \forall s \in [0, \gamma].$$

For a fixed $s \in [0, \gamma]$, by Lebourg's mean value theorem and $G(0) = 0$ we conclude again that $G(s) - G(0) = \xi_s s$. Accordingly, for sufficiently small $\epsilon > 0$ there exists $\gamma = \gamma(\epsilon) > 0$ such that $(\underline{c} - \epsilon)s^{p+1} \leq G(s) \leq (\bar{c} + \epsilon)s^{p+1}$ for every $s \in [0, \gamma]$. Thus, since $p > 1$,

$$\lim_{s \rightarrow 0^+} \frac{G(s)}{s^2} = \lim_{s \rightarrow 0^+} \frac{G(s)}{s^{p+1}} s^{p-1} = 0.$$

Therefore, by using (4.16) and (F_1^0) , we conclude that

$$\liminf_{s \rightarrow 0^+} \frac{A(s)}{s^2} = \liminf_{s \rightarrow 0^+} \frac{F(s)}{s^2} + \lambda \lim_{s \rightarrow 0^+} \frac{G(s)}{s^2} + \frac{\lambda_0}{2} > -\infty,$$

and

$$\limsup_{s \rightarrow 0^+} \frac{A(s)}{s^2} = \infty,$$

i.e., (H_0^1) holds. Since

$$\partial A(s) \subseteq \partial F(s) + \lambda \partial G(s) + \lambda_0 s,$$

and $\lambda \geq 0$, we have that

$$\max\{\partial A(s)\} \leq \max\{\partial F(s)\} + \max\{\lambda \partial G(s) + \lambda_0 s\}.$$

Since

$$\limsup_{s \rightarrow 0^+} \frac{\max\{\partial G(s)\}}{s^p} = \bar{c},$$

cf. (G_1^0) , and

$$\liminf_{s \rightarrow 0^+} \frac{\max\{\partial F(s)\}}{s} = l_0,$$

cf. (F₂⁰), by relation (4.17) it turns out that

$$\liminf_{s \rightarrow 0^+} \frac{\max\{\partial A(s)\}}{s} = \liminf_{s \rightarrow 0^+} \frac{\max\{\partial F(s)\}}{s} + \lambda \lim_{s \rightarrow 0^+} \frac{\max\{\partial G(s)\}}{s} + \lambda_0 = l_0 + \lambda_0 < 0,$$

and the upper semicontinuity of ∂A implies the existence of two sequences $\{\delta_i\}_i$ and $\{\eta_i\}_i \subset (0, 1)$ such that $0 < \eta_{i+1} < \delta_i < s_i < \eta_i$, $\lim_{i \rightarrow \infty} \eta_i = 0$, and $\max\{\partial A(s)\} \leq 0$ for all $s \in [\delta_i, \eta_i]$ and $i \in \mathbb{N}$. Therefore, hypothesis (H₂⁰) holds. Now, we can apply Theorem 4.1, i.e., there is a sequence $\{u_i\}_i \subset H_0^1(\Omega)$ of different elements such that

$$\begin{cases} -\Delta u_i(x) + \lambda_0 u_i(x) \in \partial A(u_i(x)) \subseteq \partial F(u_i(x)) + \lambda \partial G(u_i(x)) + \lambda_0 u_i(x) & x \in \Omega, \\ u_i(x) \geq 0 & x \in \Omega, \\ u_i(x) = 0 & x \in \partial\Omega, \end{cases}$$

which means that u_i solves problem (\mathcal{D}_λ) , $i \in \mathbb{N}$. This completes the proof of Theorem 2.1. \square

Proof of Theorem 2.2. The proof is done in two steps:

(i) Let $\lambda_0 \in (0, -l_0)$, $\lambda \geq 0$ and define

$$k := \lambda_0 > 0 \quad \text{and} \quad A^\lambda(s) := F(s) + \lambda G(s) + \lambda_0 \frac{s^2}{2} \quad \text{for every } s \in [0, \infty). \quad (4.18)$$

One can observe that $\partial A^\lambda(s) \subseteq \partial F(s) + \lambda_0 s + \lambda \partial G(s)$ for every $s \geq 0$. On account of (F₂⁰), there is a sequence $\{s_i\}_i \subset (0, 1)$ converging to 0 such that

$$\max\{\partial A^{\lambda=0}(s_i)\} \leq \max\{\partial F(s_i)\} + \lambda_0 s_i < 0.$$

Thus, due to the upper semicontinuity of $(s, \lambda) \mapsto \partial A^\lambda(s)$, we can choose three sequences $\{\delta_i\}_i, \{\eta_i\}_i, \{\lambda_i\}_i \subset (0, 1)$ such that $0 < \eta_{i+1} < \delta_i < s_i < \eta_i$, $\lim_{i \rightarrow \infty} \eta_i = 0$, and

$$\max\{\partial A^\lambda(s)\} \leq 0 \quad \text{for all } \lambda \in [0, \lambda_i], s \in [\delta_i, \eta_i], i \in \mathbb{N}.$$

Without any loss of generality, we may choose

$$\delta_i \leq \min\{i^{-1}, 2^{-1}i^{-2}[1 + m(\Omega)(\max_{s \in [0,1]} |\partial F(s)| + \max_{s \in [0,1]} |\partial G(s)|)]^{-1}\}. \quad (4.19)$$

For every $i \in \mathbb{N}$ and $\lambda \in [0, \lambda_i]$, let $A_i^\lambda : [0, \infty) \rightarrow \mathbb{R}$ be defined as

$$A_i^\lambda(s) = A^\lambda(\tau_{\eta_i}(s)), \quad (4.20)$$

and the energy functional $\mathcal{T}_{i,\lambda} : H_0^1(\Omega) \rightarrow \mathbb{R}$ associated with the differential inclusion problem $(D_{A_i^\lambda}^k)$ is given by

$$\mathcal{T}_{i,\lambda}(u) = \frac{1}{2} \|u\|_{H_0^1}^2 + \frac{k}{2} \int_{\Omega} u^2 dx - \int_{\Omega} A_i^\lambda(u(x)) dx.$$

One can easily check that for every $i \in \mathbb{N}$ and $\lambda \in [0, \lambda_i]$, the function A_i^λ verifies the hypotheses of Theorem 3.1. Accordingly, for every $i \in \mathbb{N}$ and $\lambda \in [0, \lambda_i]$:

$$\mathcal{T}_{i,\lambda} \text{ attains its infimum on } W^{\eta_i} \text{ at some } u_{i,\lambda}^0 \in W^{\eta_i} \quad (4.21)$$

$$u_{i,\lambda}^0(x) \in [0, \delta_i] \text{ for a.e. } x \in \Omega; \quad (4.22)$$

$$u_{i,\lambda}^0 \text{ is a weak solution of } (D_{A_i^\lambda}^k). \quad (4.23)$$

By the choice of the function A^λ and $k > 0$, $u_{i,\lambda}^0$ is also a solution to the differential inclusion problem $(D_{A^\lambda}^k)$, so (\mathcal{D}_λ) .

(ii) It is clear that for $\lambda = 0$, the set-valued map $\partial A_i^\lambda = \partial A_i^0$ verifies the hypotheses of Theorem 4.1. In particular, $\mathcal{T}_i := \mathcal{T}_{i,0}$ is the energy functional associated with problem $(D_{A_i^0}^k)$. Consequently, the elements $u_i^0 := u_{i,0}^0$ verify not only (4.21)-(4.23) but also

$$\mathcal{T}_i(u_i^0) = \min_{W^{\eta_i}} \mathcal{T}_i \leq \mathcal{T}_i(w_{\bar{s}_i}) < 0 \text{ for all } i \in \mathbb{N}. \quad (4.24)$$

Similarly to Kristály and Moroşanu [12], let $\{\theta_i\}_i$ be a sequence with negative terms such that $\lim_{i \rightarrow \infty} \theta_i = 0$. Due to (4.24) we may assume that

$$\theta_i < \mathcal{T}_i(u_i^0) \leq \mathcal{T}_i(w_{\bar{s}_i}) < \theta_{i+1}. \quad (4.25)$$

Let us choose

$$\lambda_i' = \frac{\theta_{i+1} - \mathcal{T}_i(w_{\bar{s}_i})}{m(\Omega) \max_{s \in [0,1]} |G(s)| + 1} \text{ and } \lambda_i'' = \frac{\mathcal{T}_i(u_i^0) - \theta_i}{m(\Omega) \max_{s \in [0,1]} |G(s)| + 1}, \quad i \in \mathbb{N}, \quad (4.26)$$

and for a fixed $k \in \mathbb{N}$, set

$$\lambda_k^0 = \min(1, \lambda_1, \dots, \lambda_k, \lambda_1', \dots, \lambda_k', \lambda_1'', \dots, \lambda_k'') > 0. \quad (4.27)$$

Having in our mind these choices, for every $i \in \{1, \dots, k\}$ and $\lambda \in [0, \lambda_k^0]$ one has

$$\begin{aligned} \mathcal{T}_{i,\lambda}(u_{i,\lambda}^0) &\leq \mathcal{T}_{i,\lambda}(w_{\bar{s}_i}) = \frac{1}{2} \|w_{\bar{s}_i}\|_{H_0^1}^2 - \int_{\Omega} F(w_{\bar{s}_i}(x)) dx - \lambda \int_{\Omega} G(w_{\bar{s}_i}(x)) dx \\ &= \mathcal{T}_i(w_{\bar{s}_i}) - \lambda \int_{\Omega} G(w_{\bar{s}_i}(x)) dx \\ &< \theta_{i+1}, \end{aligned} \quad (4.28)$$

and due to $u_{i,\lambda}^0 \in W^{\eta_i}$ and to the fact that u_i^0 is the minimum point of \mathcal{T}_i on the set W^{η_i} , by (4.25) we also have

$$\mathcal{T}_{i,\lambda}(u_{i,\lambda}^0) = \mathcal{T}_i(u_{i,\lambda}^0) - \lambda \int_{\Omega} G(u_{i,\lambda}^0(x)) dx \geq \mathcal{T}_i(u_i^0) - \lambda \int_{\Omega} G(u_{i,\lambda}^0(x)) dx > \theta_i. \quad (4.29)$$

Therefore, by (4.28) and (4.29), for every $i \in \{1, \dots, k\}$ and $\lambda \in [0, \lambda_k^0]$, one has

$$\theta_i < \mathcal{T}_{i,\lambda}(u_{i,\lambda}^0) < \theta_{i+1},$$

thus

$$\mathcal{T}_{1,\lambda}(u_{1,\lambda}^0) < \dots < \mathcal{T}_{k,\lambda}(u_{k,\lambda}^0) < 0.$$

We notice that $u_i^0 \in W^{\eta_i}$ for every $i \in \{1, \dots, k\}$, so $\mathcal{T}_{i,\lambda}(u_{i,\lambda}^0) = \mathcal{T}_{1,\lambda}(u_{i,\lambda}^0)$ because of (4.20). Therefore, we conclude that for every $\lambda \in [0, \lambda_k^0]$,

$$\mathcal{T}_{1,\lambda}(u_{1,\lambda}^0) < \dots < \mathcal{T}_{1,\lambda}(u_{k,\lambda}^0) < 0 = \mathcal{T}_{1,\lambda}(0).$$

Based on these inequalities, it turns out that the elements $u_{1,\lambda}^0, \dots, u_{k,\lambda}^0$ are distinct and non-trivial whenever $\lambda \in [0, \lambda_k^0]$.

Now, we are going to prove the estimate (2.2). We have for every $i \in \{1, \dots, k\}$ and $\lambda \in [0, \lambda_k^0]$:

$$\mathcal{T}_{1,\lambda}(u_{i,\lambda}^0) = \mathcal{T}_{i,\lambda}(u_{i,\lambda}^0) < \theta_{i+1} < 0.$$

By Lebourg's mean value theorem and (4.19), we have for every $i \in \{1, \dots, k\}$ and $\lambda \in [0, \lambda_k^0]$ that

$$\begin{aligned} \frac{1}{2} \|u_{i,\lambda}^0\|_{H_0^1}^2 &< \int_{\Omega} F(u_{i,\lambda}^0(x)) dx + \lambda \int_{\Omega} G(u_{i,\lambda}^0(x)) dx \\ &\leq m(\Omega) \delta_i \left[\max_{s \in [0,1]} |\partial F(s)| + \max_{s \in [0,1]} |\partial G(s)| \right] \\ &\leq \frac{1}{2i^2}. \end{aligned}$$

This completes the proof of Theorem 2.2. \square

5. PROOF OF THEOREMS 2.3 AND 2.4

We consider again the differential inclusion problem

$$\begin{cases} -\Delta u(x) + ku(x) \in \partial A(u(x)), & u(x) \geq 0 & x \in \Omega, \\ u(x) = 0 & & x \in \partial\Omega, \end{cases} \quad (\mathbf{D}_A^k),$$

where $k > 0$ and the locally Lipschitz function $A : \mathbb{R}_+ \rightarrow \mathbb{R}$ verifies

$$(H_0^\infty): A(0) = 0;$$

$$(H_1^\infty): -\infty < \liminf_{s \rightarrow \infty} \frac{A(s)}{s^2} \text{ and } \limsup_{s \rightarrow \infty} \frac{A(s)}{s^2} = +\infty;$$

$$(H_2^\infty): \text{there are two sequences } \{\delta_i\}, \{\eta_i\} \text{ with } 0 < \delta_i < \eta_i < \delta_{i+1}, \lim_{i \rightarrow \infty} \delta_i = \infty, \text{ and}$$

$$\max\{\partial A(s)\} := \max\{\xi : \xi \in \partial A(s)\} \leq 0$$

for every $s \in [\delta_i, \eta_i]$, $i \in \mathbb{N}$.

The counterpart of Theorem 4.1 reads as follows.

Theorem 5.1. *Let $k > 0$ and assume the hypotheses (H_0^∞) , (H_1^∞) and (H_2^∞) hold. Then the differential inclusion problem (\mathbf{D}_A^k) admits a sequence $\{u_i^\infty\}_i \subset H_0^1(\Omega)$ of distinct weak solutions such that*

$$\lim_{i \rightarrow \infty} \|u_i^\infty\|_{L^\infty} = \infty. \quad (5.1)$$

Proof. The proof is similar to the one performed in Theorem 4.1; we shall show the differences only. We associate the energy functional $\mathcal{T}_i : H_0^1(\Omega) \rightarrow \mathbb{R}$ with problem $(\mathbf{D}_{A_i}^k)$, where $A_i : \mathbb{R} \rightarrow \mathbb{R}$ is given by

$$A_i(s) = A(\tau_{\eta_i}(s)), \quad (5.2)$$

with $A(s) = 0$ for $s \leq 0$. One can show that there exists $M_{A_i} > 0$ such that

$$\max |\partial A_i(s)| := \max\{|\xi| : \xi \in \partial A_i(s)\} \leq M_{A_i}$$

for all $s \geq 0$, i.e., hypothesis $(H_{A_i}^1)$ holds. Moreover, $(H_{A_i}^2)$ follows by (H_2^∞) . Thus Theorem 4.1 can be applied for all $i \in \mathbb{N}$, i.e., we have an element $u_i^\infty \in W^{\eta_i}$ such that

$$u_i^\infty \text{ is the minimum point of the functional } \mathcal{T}_i \text{ on } W^{\eta_i}, \quad (5.3)$$

$$u_i^\infty(x) \in [0, \delta_i] \text{ for a.e. } x \in \Omega, \quad (5.4)$$

$$u_i^\infty \text{ is a weak solution of } (\mathbf{D}_{A_i}^k). \quad (5.5)$$

By (5.2), u_i^∞ turns to be a weak solution also for differential inclusion problem (\mathbf{D}_A^k) .

We shall prove that there are infinitely many distinct elements in the sequence $\{u_i^\infty\}_i$ by showing that

$$\lim_{i \rightarrow \infty} \mathcal{T}_i(u_i^\infty) = -\infty. \quad (5.6)$$

By the left part of (H_1^∞) we can find $l_\infty^A > 0$ and $\zeta > 0$ such that

$$A(s) \geq -l_\infty^A \text{ for all } s > \zeta. \quad (5.7)$$

Let us choose $L_\infty^A > 0$ large enough such that

$$\frac{1}{2}C(r, n) + \left(\frac{k}{2} + l_\infty^A\right) m(\Omega) < L_\infty^A (r/2)^n \omega_n. \quad (5.8)$$

On account of the right part of (H_1^∞) , one can fix a sequence $\{\tilde{s}_i\}_i \subset (0, \infty)$ such that $\lim_{i \rightarrow \infty} \tilde{s}_i = \infty$ and

$$A(\tilde{s}_i) > L_\infty^A \tilde{s}_i^2 \text{ for every } i \in \mathbb{N}. \quad (5.9)$$

We know from (H_2^∞) that $\lim_{i \rightarrow \infty} \delta_i = \infty$, therefore one has a subsequence $\{\delta_{m_i}\}_i$ of $\{\delta_i\}_i$ such that $\tilde{s}_i \leq \delta_{m_i}$ for all $i \in \mathbb{N}$. Let $i \in \mathbb{N}$, and recall $w_{s_i} \in H_0^1(\Omega)$ from (3.1) with $s_i := \tilde{s}_i > 0$. Then $w_{\tilde{s}_i} \in W^{\eta_{m_i}}$ and according to (3.2), (5.7) and (5.9) we have

$$\begin{aligned} \mathcal{T}_{m_i}(w_{\tilde{s}_i}) &= \frac{1}{2} \|w_{\tilde{s}_i}\|_{H_0^1}^2 + \frac{k}{2} \int_{\Omega} w_{\tilde{s}_i}^2 - \int_{\Omega} A_{m_i}(w_{\tilde{s}_i}(x)) dx \\ &= \frac{1}{2} C(r, n) \tilde{s}_i^2 + \frac{k}{2} \int_{\Omega} w_{\tilde{s}_i}^2 - \int_{B(x_0, r/2)} A(\tilde{s}_i) dx \\ &\quad - \int_{(B(x_0, r) \setminus B(x_0, r/2)) \cap \{w_{\tilde{s}_i} > \zeta\}} A(w_{\tilde{s}_i}(x)) dx \\ &\quad - \int_{(B(x_0, r) \setminus B(x_0, r/2)) \cap \{w_{\tilde{s}_i} \leq \zeta\}} A(w_{\tilde{s}_i}(x)) dx \\ &\leq \left[\frac{1}{2} C(r, n) + \frac{k}{2} m(\Omega) - L_\infty^A (r/2)^n \omega_n + l_\infty^A m(\Omega) \right] \tilde{s}_i^2 + \tilde{M}_A m(\Omega) \zeta, \end{aligned}$$

where $\tilde{M}_A = \max\{|A(s)| : s \in [0, \zeta]\}$ does not depend on $i \in \mathbb{N}$. This estimate combined by (5.8) and $\lim_{i \rightarrow \infty} \tilde{s}_i = \infty$ yields that

$$\lim_{i \rightarrow \infty} \mathcal{T}_{m_i}(w_{\tilde{s}_i}) = -\infty. \quad (5.10)$$

By equation (5.3), one has

$$\mathcal{T}_{m_i}(u_{m_i}^\infty) = \min_{W^{\eta_{m_i}}} \mathcal{T}_{m_i} \leq \mathcal{T}_{m_i}(w_{\tilde{s}_i}). \quad (5.11)$$

It follows by (5.10) that $\lim_{i \rightarrow \infty} \mathcal{T}_{m_i}(u_{m_i}^\infty) = -\infty$.

We notice that the sequence $\{\mathcal{T}_i(u_i^\infty)\}_i$ is non-increasing. Indeed, let $i < k$; due to (5.2) one has that

$$\mathcal{T}_i(u_i^\infty) = \min_{W^{\eta_i}} \mathcal{T}_i = \min_{W^{\eta_i}} \mathcal{T}_k \geq \min_{W^{\eta_k}} \mathcal{T}_k = \mathcal{T}_k(u_k^\infty), \quad (5.12)$$

which completes the proof of (5.6).

The proof of (5.1) goes in a similar way as in [12]. \square

Proof of Theorem 2.3. We split the proof into two parts.

(i) *Case $p = 1$.* Let $\lambda \geq 0$ with $\lambda \bar{c} < -l_\infty$ and fix $\tilde{\lambda}_\infty \in \mathbb{R}$ such that $\lambda \bar{c} < \tilde{\lambda}_\infty < -l_\infty$. With these choices, we define

$$k := \tilde{\lambda}_\infty - \lambda \bar{c} > 0 \text{ and } A(s) := F(s) + \frac{\tilde{\lambda}_\infty}{2} s^2 + \lambda \left(G(s) - \frac{\bar{c}}{2} s^2 \right) \text{ for every } s \in [0, \infty). \quad (5.13)$$

It is clear that $A(0) = 0$, i.e., (H_0^∞) is verified. A similar argument for the p -order perturbation ∂G as before shows that

$$\liminf_{s \rightarrow \infty} \frac{A(s)}{s^2} \geq \liminf_{s \rightarrow \infty} \frac{F(s)}{s^2} + \frac{\tilde{\lambda}_\infty - \lambda \bar{c}}{2} + \lambda \liminf_{s \rightarrow \infty} \frac{G(s)}{s^2} \geq \liminf_{s \rightarrow \infty} \frac{F(s)}{s^2} + \frac{\tilde{\lambda}_\infty - \lambda \bar{c}}{2} + \lambda \underline{c} > -\infty,$$

and

$$\limsup_{s \rightarrow \infty} \frac{A(s)}{s^2} \geq \limsup_{s \rightarrow \infty} \frac{F(s)}{s^2} + \frac{\tilde{\lambda}_\infty - \lambda \bar{c}}{2} + \lambda \liminf_{s \rightarrow \infty} \frac{G(s)}{s^2} = +\infty,$$

i.e., (H_1^∞) is verified.

Since

$$\partial A(s) \subseteq \partial F(s) + \tilde{\lambda}_\infty s + \lambda(\partial G(s) - \bar{c}s), \quad s \geq 0, \quad (5.14)$$

it turns out that

$$\liminf_{s \rightarrow \infty} \frac{\max\{\partial A(s)\}}{s} \leq \liminf_{s \rightarrow \infty} \frac{\max\{\partial F(s)\}}{s} + \tilde{\lambda}_\infty - \lambda \bar{c} + \lambda \limsup_{s \rightarrow \infty} \frac{\max\{\partial G(s)\}}{s} = l_\infty + \tilde{\lambda}_\infty < 0.$$

By using the upper semicontinuity of $s \mapsto \partial A(s)$, one may fix two sequences $\{\delta_i\}_i, \{\eta_i\}_i \subset (0, \infty)$ such that $0 < \delta_i < s_i < \eta_i < \delta_{i+1}$, $\lim_{i \rightarrow \infty} \delta_i = \infty$, and $\max\{\partial A(s)\} \leq 0$ for all $s \in [\delta_i, \eta_i]$ and $i \in \mathbb{N}$. Thus, (H_2^∞) is verified as well. By applying the inclusion (5.14) and Theorem 4.1 with the choice (5.13), there exists a sequence $\{u_i\}_i \subset H_0^1(\Omega)$ of different elements such that

$$\begin{cases} -\Delta u_i(x) + (\tilde{\lambda}_\infty - \lambda \bar{c})u_i(x) \in \partial F(u_i(x)) + \tilde{\lambda}_\infty u_i(x) + \lambda(\partial G(u_i(x)) - \bar{c}u_i(x)) & x \in \Omega, \\ u_i(x) \geq 0 & x \in \Omega, \\ u_i(x) = 0 & x \in \partial\Omega, \end{cases}$$

i.e., u_i solves problem (\mathcal{D}_λ) , $i \in \mathbb{N}$.

(ii) *Case* $p < 1$. Let $\lambda \geq 0$ be arbitrary fixed and choose a number $\lambda_\infty \in (0, -l_\infty)$. Let

$$k := \lambda_\infty > 0 \quad \text{and} \quad A(s) := F(s) + \lambda G(s) + \lambda_\infty \frac{s^2}{2} \quad \text{for every } s \in [0, \infty). \quad (5.15)$$

Since $F(0) = G(0) = 0$, hypothesis (H_0^∞) clearly holds. Moreover, by (G_1^∞) , for sufficiently small $\epsilon > 0$ there exists $s_0 > 0$, such that $(\underline{c} - \epsilon)s^{p+1} \leq G(s) \leq (\bar{c} + \epsilon)s^{p+1}$ for every $s > s_0$. Thus, since $p < 1$,

$$\lim_{s \rightarrow \infty} \frac{G(s)}{s^2} = \lim_{s \rightarrow \infty} \frac{G(s)}{s^{p+1}} s^{p-1} = 0.$$

Accordingly, by using (5.15) we obtain that hypothesis (H_1^∞) holds. A similar argument as above implies that

$$\liminf_{s \rightarrow \infty} \frac{\max\{\partial A(s)\}}{s} \leq l_0 + \lambda_\infty < 0,$$

and the upper semicontinuity of ∂A implies the existence of two sequences $\{\delta_i\}_i$ and $\{\eta_i\}_i \subset (0, 1)$ such that $0 < \delta_i < s_i < \eta_i < \delta_{i+1}$, $\lim_{i \rightarrow \infty} \delta_i = \infty$, and $\max\{\partial A(s)\} \leq 0$ for all $s \in [\delta_i, \eta_i]$ and $i \in \mathbb{N}$. Therefore, hypothesis (H_2^∞) holds. Now, we can apply Theorem 4.1, i.e., there is a sequence $\{u_i\}_i \subset H_0^1(\Omega)$ of different elements such that

$$\begin{cases} -\Delta u_i(x) + \lambda_\infty u_i(x) \in \partial A(u_i(x)) \subseteq \partial F(u_i(x)) + \lambda \partial G(u_i(x)) + \lambda_\infty u_i(x) & x \in \Omega, \\ u_i(x) \geq 0 & x \in \Omega, \\ u_i(x) = 0 & x \in \partial\Omega, \end{cases}$$

which means that u_i solves problem (\mathcal{D}_λ) , $i \in \mathbb{N}$, which completes the proof. \square

Proof of Theorem 2.4. The proof is done in two steps:

(i) Let $\lambda_\infty \in (0, -l_\infty)$, $\lambda \geq 0$ and define

$$k := \lambda_\infty > 0 \quad \text{and} \quad A^\lambda(s) := F(s) + \lambda G(s) + \lambda_\infty \frac{s^2}{2} \quad \text{for every } s \in [0, \infty). \quad (5.16)$$

One has clearly that $\partial A^\lambda(s) \subseteq \partial F(s) + \lambda_\infty s + \lambda \partial G(s)$ for every $s \in \mathbb{R}$. On account of (F_2^∞) , there is a sequence $\{s_i\}_i \subset (0, \infty)$ converging to ∞ such that

$$\max\{\partial A^{\lambda=0}(s_i)\} \leq \max\{\partial F(s_i)\} + \lambda_\infty s_i < 0.$$

By the upper semicontinuity of $(s, \lambda) \mapsto \partial A^\lambda(s)$, we can choose the sequences $\{\delta_i\}_i, \{\eta_i\}_i, \{\lambda_i\}_i \subset (0, \infty)$ such that $0 < \delta_i < s_i < \eta_i < \delta_{i+1}$, $\lim_{i \rightarrow \infty} \delta_i = \infty$, and

$$\max\{\partial A^\lambda(s)\} \leq 0$$

for all $\lambda \in [0, \lambda_i]$, $s \in [\delta_i, \eta_i]$ and $i \in \mathbb{N}$.

For every $i \in \mathbb{N}$ and $\lambda \in [0, \lambda_i]$, let $A_i^\lambda : [0, \infty) \rightarrow \mathbb{R}$ be defined by

$$A_i^\lambda(s) = A^\lambda(\tau_{\eta_i}(s)), \quad (5.17)$$

and accordingly, the energy functional $\mathcal{T}_{i,\lambda} : H_0^1(\Omega) \rightarrow \mathbb{R}$ associated with the differential inclusion problem $(D_{A_i^\lambda}^k)$ is

$$\mathcal{T}_{i,\lambda}(u) = \frac{1}{2} \|u\|_{H_0^1}^2 + \frac{k}{2} \int_\Omega u^2 dx - \int_\Omega A_i^\lambda(u(x)) dx.$$

Then for every $i \in \mathbb{N}$ and $\lambda \in [0, \lambda_i]$, the function A_i^λ clearly verifies the hypotheses of Theorem 3.1. Accordingly, for every $i \in \mathbb{N}$ and $\lambda \in [0, \lambda_i]$ there exists

$$\mathcal{T}_{i,\lambda} \text{ attains its infimum at some } \tilde{u}_{i,\lambda}^\infty \in W^{\eta_i} \quad (5.18)$$

$$\tilde{u}_{i,\lambda}^\infty \in [0, \delta_i] \text{ for a.e. } x \in \Omega; \quad (5.19)$$

$$\tilde{u}_{i,\lambda}^\infty(x) \text{ is a weak solution of } (D_{A_i^\lambda}^k). \quad (5.20)$$

Due to (5.17), $\tilde{u}_{i,\lambda}^\infty$ is not only a solution to $(D_{A_i^\lambda}^k)$ but also to the differential inclusion problem $(D_{A^\lambda}^k)$, so (\mathcal{D}_λ) .

(ii) For $\lambda = 0$, the function $\partial A_i^\lambda = \partial A_i^0$ verifies the hypotheses of Theorem 4.1. Moreover, $\mathcal{T}_i := \mathcal{T}_{i,0}$ is the energy functional associated with problem $(D_{A_i^0}^k)$. Consequently, the elements $u_i^\infty := u_{i,0}^\infty$ verify not only (5.18)-(5.20) but also

$$\mathcal{T}_{m_i}(u_{m_i}^\infty) = \min_{W^{m_i}}(\mathcal{T}_{m_i}) \leq \mathcal{T}_{m_i}(w_{\bar{s}_i}) \text{ for all } i \in \mathbb{N}, \quad (5.21)$$

where the subsequence $\{u_{m_i}^\infty\}_i$ of $\{u_i^\infty\}_i$ and $w_{\bar{s}_i} \in W^{\eta_i}$ appear in the proof of Theorem 5.1.

Similarly to Kristály and Moroşanu [12], let $\{\theta_i\}_i$ be a sequence with negative terms such that $\lim_{i \rightarrow \infty} \theta_i = -\infty$. On account of (5.21) we may assume that

$$\theta_{i+1} < \mathcal{T}_{m_i}(u_{m_i}^\infty) \leq \mathcal{T}_{m_i}(w_{\bar{s}_i}) < \theta_i. \quad (5.22)$$

Let

$$\lambda_i' = \frac{\theta_i - \mathcal{T}_{m_i}(w_{\bar{s}_i})}{m(\Omega) \max_{s \in [0,1]} |G(s)| + 1} \quad \text{and} \quad \lambda_i'' = \frac{\mathcal{T}_{m_i}(u_{m_i}^\infty) - \theta_{i+1}}{m(\Omega) \max_{s \in [0,1]} |G(s)| + 1}, \quad i \in \mathbb{N}, \quad (5.23)$$

and for a fixed $k \in \mathbb{N}$, we set

$$\lambda_k^\infty = \min(1, \lambda_1, \dots, \lambda_k, \lambda_1', \dots, \lambda_k', \lambda_1'', \dots, \lambda_k'') > 0. \quad (5.24)$$

Then, for every $i \in \{1, \dots, k\}$ and $\lambda \in [0, \lambda_k^\infty]$, due to (5.22) we have that

$$\begin{aligned} \mathcal{T}_{m_i, \lambda}(\tilde{u}_{m_i, \lambda}^\infty) &\leq \mathcal{T}_{m_i, \lambda}(w_{\tilde{s}_i}) = \frac{1}{2} \|w_{\tilde{s}_i}\|_{H_0^1}^2 - \int_{\Omega} F(w_{\tilde{s}_i}(x)) dx - \lambda \int_{\Omega} G(w_{\tilde{s}_i}(x)) dx \\ &= \mathcal{T}_{m_i}(w_{\tilde{s}_i}) - \lambda \int_{\Omega} G(w_{\tilde{s}_i}(x)) dx \\ &< \theta_i. \end{aligned} \quad (5.25)$$

Similarly, since $\tilde{u}_{m_i, \lambda}^\infty \in W^{\eta_{m_i}}$ and $u_{m_i}^\infty$ is the minimum point of \mathcal{T}_i on the set $W^{\eta_{m_i}}$, on account of (5.22) we have

$$\mathcal{T}_{m_i, \lambda}(\tilde{u}_{m_i, \lambda}^\infty) = \mathcal{T}_{m_i}(\tilde{u}_{m_i, \lambda}^\infty) - \lambda \int_{\Omega} G(\tilde{u}_{m_i, \lambda}^\infty) dx \geq \mathcal{T}_{m_i}(u_{m_i}^\infty) - \lambda \int_{\Omega} G(\tilde{u}_{m_i, \lambda}^\infty) dx > \theta_{i+1}. \quad (5.26)$$

Therefore, for every $i \in \{1, \dots, k\}$ and $\lambda \in [0, \lambda_k^\infty]$,

$$\theta_{i+1} < \mathcal{T}_{m_i, \lambda}(\tilde{u}_{m_i, \lambda}^\infty) < \theta_i < 0, \quad (5.27)$$

thus

$$\mathcal{T}_{m_k, \lambda}(\tilde{u}_{m_k, \lambda}^\infty) < \dots < \mathcal{T}_{m_1, \lambda}(\tilde{u}_{m_1, \lambda}^\infty) < 0. \quad (5.28)$$

Because of (5.17), we notice that $\tilde{u}_{m_i, \lambda}^\infty \in W^{\eta_{m_k}}$ for every $i \in \{1, \dots, k\}$, thus $\mathcal{T}_{m_i, \lambda}(\tilde{u}_{m_i, \lambda}^\infty) = \mathcal{T}_{m_k, \lambda}(\tilde{u}_{i, \lambda}^\infty)$. Therefore, for every $\lambda \in [0, \lambda_k^\infty]$,

$$\mathcal{T}_{m_k, \lambda}(\tilde{u}_{m_k, \lambda}^\infty) < \dots < \mathcal{T}_{m_k, \lambda}(\tilde{u}_{m_1, \lambda}^\infty) < 0 = \mathcal{T}_{m_k, \lambda}(0),$$

i.e, the elements $\tilde{u}_{m_1, \lambda}^\infty, \dots, \tilde{u}_{m_k, \lambda}^\infty$ are distinct and non-trivial whenever $\lambda \in [0, \lambda_k^\infty]$. The estimate (2.5) follows in a similar manner as in [12]. \square

6. CONCLUDING REMARKS

1. Suitable modification of our arguments provide multiplicity results for the differential inclusion problem

$$\begin{cases} -\Delta u(x) + u(x) \in \partial F(u(x)) + \lambda \partial G(u(x)) & \text{in } \mathbb{R}^n; \\ u \geq 0, & \text{in } \mathbb{R}^n, \end{cases} \quad (\tilde{\mathcal{D}}_\lambda)$$

where ∂F and ∂G behave in a similar manner as before. The main difficulty in the investigation of $(\tilde{\mathcal{D}}_\lambda)$ is the lack of compact embedding of the Sobolev space $H^1(\mathbb{R}^n)$ into the Lebesgue spaces $L^q(\mathbb{R}^n)$, $n \geq 2$, $q \in [2, 2^*)$. However, by using Strauss-type estimates and Lions-type embedding results for radially symmetric functions of $H^1(\mathbb{R}^n)$ (see e.g. Willem [23]), the principle of symmetric criticality for non-smooth functionals (see Kobayashi and Ôtani [13] and Squassina [22]) provides the expected results. A related result in the smooth setting can be found in Kristály [11].

2. Assume that ∂F oscillates at a point $l \in [0, +\infty]$ and ∂G has a p -order growth at l . We are wondering if our results, valid for $l = 0$ and $l = +\infty$, can be extended to any $l \in (0, \infty)$, even in the smooth framework.

7. APPENDIX: LOCALLY LIPSCHITZ FUNCTIONS

In this part we collect those notions and properties of locally Lipschitz functions which are used in the proofs; for details, see Clarke [7] and Chang [6]. Let $(X, \|\cdot\|)$ be a real Banach space and $U \subset X$ be an open set; we denote by $\langle \cdot, \cdot \rangle$ the duality mapping between X^* and X .

Definition 7.1. (see [7]) *A function $f : X \rightarrow \mathbb{R}$ is locally Lipschitz if, for every $x \in X$, there exist a neighborhood U of x and a constant $L > 0$ such that*

$$|f(x_1) - f(x_2)| \leq L\|x_1 - x_2\| \quad \text{for all } x_1, x_2 \in U.$$

Definition 7.2. (see [7]) *Let f be a locally Lipschitz function near the point x and let v be any arbitrary vector in X . The generalized directional derivative in the sense of Clarke of f at the point $x \in X$ in the direction $v \in X$ is*

$$f^\circ(x; v) = \limsup_{z \rightarrow x, \tau \rightarrow 0^+} \frac{f(z + \tau v) - f(z)}{\tau}.$$

The generalized gradient of f at $x \in X$ is the set

$$\partial f(x) = \{x^* \in X^* : \langle x^*, v \rangle \leq f^\circ(x; v) \text{ for all } v \in X\}.$$

For all $x \in X$, the functional $f^\circ(x, \cdot)$ is finite and positively homogeneous. Moreover, we have the following properties.

Proposition 7.1. (see [7]) *Let X be a real Banach space, $U \subset X$ an open subset and $f, g : U \rightarrow \mathbb{R}$ be locally Lipschitz functions. The following properties hold:*

- (a) *For every $x \in U$, $\partial f(x)$ is a nonempty, convex and weakly^{*}-compact subset of X^* which is bounded by the Lipschitz constant $L > 0$ of f near x ;*
- (b) *$f^\circ(x; v) = \max\{\langle \xi, v \rangle : \xi \in \partial f(x)\}$ for all $v \in X$;*
- (c) *$(f + g)^\circ(x; v) \leq f^\circ(x; v) + g^\circ(x; v)$ for all $x \in U, v \in X$;*
- (d) *$\partial(f + g)(u) \subset \partial f(u) + \partial g(u)$ for all $u \in U$;*
- (e) *$(-f)^\circ(x; v) = f^\circ(x; -v)$ for all $x \in U$;*
- (f) *The function $(x, v) \mapsto f^\circ(x; v)$ is upper semicontinuous;*
- (g) *The set-valued map $\partial f : U \rightarrow 2^{X^*}$ is weakly^{*}-closed, that is, if $\{x_i\} \subset U$ and $\{w_i\} \subset X^*$ are sequences such that $x_i \rightarrow x$ strongly in X and $w_i \in \partial f(x_i)$ with $w_i \rightarrow z$ weakly^{*} in X^* , then $z \in \partial f(x)$. In particular, if X is finite dimensional, then ∂f is upper semicontinuous, i.e., for every $\epsilon > 0$ there exists $\gamma > 0$ such that $\partial f(x') \subseteq \partial f(x) + B_{X^*}(0, \epsilon)$, $\forall x' \in B_X(x, \gamma)$;*

Proposition 7.2. (see [6]) *The number $\lambda_f(u) = \inf_{w \in \partial f(u)} \|w\|_{X^*}$ is well defined and*

$$\liminf_{u \rightarrow u_0} \lambda_f(u) \geq \lambda_f(u_0).$$

Definition 7.3. (see [6]) *Let $f : X \rightarrow \mathbb{R}$ be a locally Lipschitz function. We say that $u \in X$ is a critical point (in the sense of Chang) of f , if $\lambda_f(u) = 0$, i.e., $0 \in \partial f(u)$.*

Remark 7.1. (see [7]) (a) $u \in X$ is a critical point of f if $f^\circ(u; v) \geq 0$ for all $v \in X$.

(b) If $x \in U$ is a local minimum or maximum of the locally Lipschitz function $f : X \rightarrow \mathbb{R}$ on an open set of a Banach space, then x is a critical point of f .

Proposition 7.3. (see [7]) (Lebourg’s mean value theorem) *Let X be a Banach space, $x, y \in X$ and $f : X \rightarrow \mathbb{R}$ be Lipschitz on an open set containing the line segment $[x, y]$. Then there is a point $a \in (x, y)$ such that*

$$f(y) - f(x) \in \langle \partial f(a), y - x \rangle.$$

Proposition 7.4. (see [7]) (Chain Rule) *Let X be Banach space, let us consider the composite function $f = g \circ h$ where $h : X \rightarrow \mathbb{R}^n$ and $g : \mathbb{R}^n \rightarrow \mathbb{R}$ are given functions. Let denote h_i , $i \in \{1, \dots, n\}$ be the component functions of h . We assume h_i is locally Lipschitz near x and g is too near $h(x)$. Then f is locally Lipschitz near x as well. Let us denote by α_i the elements of ∂g , and let $\alpha = (\alpha_1, \dots, \alpha_n)$; then*

$$\partial f(x) \subset \overline{\text{co}}\left\{\sum \alpha_i \xi_i : \xi_i \in \partial h_i(x), \alpha \in \partial g(h(x))\right\},$$

where $\overline{\text{co}}$ denotes the weak-closed convex hull.

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