#### TOMKÓ

# ON A SINGLE-CHANNEL LOSS SYSTEM CONSIDERING THE RELIABILITY OF THE CHANNEL

### by

## J. TOMKÓ

## Summary

A single-channel service system is considered under the following conditions:

a) The arrival process is of Poisson type with parameter  $\lambda$ ;

b) A call not finding the channel in a free state at the instant of its arrival will be lost; a call will be lost as well if before having finished its service the channel goes wrong.

Let  $\omega(t)$  denote the life time of the service channel related to the moment in that the channel is free. For the reliability of the service channel we sssume c)

$$\omega(t + \Delta t) - \omega(t) = \begin{cases} -\Delta t & \text{if in the interval } (t, t + \Delta t) \text{ the channel is free,} \\ -c \Delta t & \text{if in the interval } (t, t + \Delta t) \text{ the channel is occupied.} \end{cases}$$

Denote by  $\pi_1$  the probability of the service channel being occupied at any given instant, by  $\pi_2$  the probability of its being stopped for repair and by  $\pi_3$  the probability of finding it in a free state.

It is proved under certain further conditions that these probabilities can be given as follows:

$$\begin{split} \pi_1 &= \varrho \int\limits_0^\infty \left( \int\limits_0^{y/c} Z_c(y - cx) \left[ 1 - F(x) \right] dx \right) \left[ 1 - H(y) \right] dy \\ \pi_2 &= \varrho \int\limits_0^\infty \left[ 1 - G(u) \right] du \\ \pi_3 &= \varrho \cdot 1/\lambda \cdot \int\limits_0^\infty Z_c(y) \left[ 1 - H(y) \right] dy \end{split}$$

where

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$$= \frac{1}{\int_{0}^{\infty} [1 - G(u)] \, du + \frac{1}{c} \int_{0}^{\infty} \left[1 - \frac{c - 1}{\lambda} Z_{c}(u)\right] [1 - H(u)] \, du}$$

and

$$\overline{Z}_{c}(s) = \int_{0}^{\infty} e^{-su} Z_{c}(u) \, du = \frac{\lambda}{s + \lambda[1 - \overline{F}(s)]}, \ \overline{F}(s) = \int_{0}^{\infty} e^{-su} \, dF(u) \, .$$