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# Tolerances as images of congruences in varieties defined by linear identities

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ABSTRACT. An identity s=t is linear if each variable occurs at most once in each of the terms s and t. Let T be a tolerance relation of an algebra  $\mathcal A$  in a variety defined by a set of linear identities. We prove that there exist an algebra  $\mathcal B$  in the same variety and a congruence  $\theta$  of  $\mathcal B$  such that a homomorphism from  $\mathcal B$  onto  $\mathcal A$  maps  $\theta$  onto T.

An identity s=t is linear if each variable occurs at most once in each of the terms s and t, see, for example, M. N. Bleicher, H. Schneider and R. L. Wilson [1, Theorem 4.19], W. Taylor [8], I. Bošnjak and R. Madarász [2], A. Pilitowska [7], and their references. In the particular case where every variable occurs exactly twice, once in s and once in t, we speak of a balanced linear identity, see M. V. Lawson [6]. For example, the variety of semigroups and that of commutative semigroups are defined by balanced linear identities. Binary reflexive, symmetric, and compatible relations are called tolerances; see I. Chajda [3]. If  $\varphi \colon \mathcal{B} \to \mathcal{A}$  is a surjective homomorphism and  $\theta$  is a congruence of the algebra  $\mathcal{B}$ , then  $\varphi(\theta) = \{(\varphi(x), \varphi(y)) : (x, y) \in \theta\}$  is a tolerance of  $\mathcal{A}$ . Each tolerance of  $\mathcal{A}$  is obtained this way; this follows from our result below (applied for the variety defined by the empty set of linear identities). Sometimes, like in I. Chajda, G. Czédli, and R. Halaš [4] or G. Czédli and G. Grätzer [5], we can choose an appropriate  $\mathcal{B}$  from a given variety. We have the following additional result of this kind.

**Theorem.** Assume that  $\mathcal{V}$  is a variety defined by a set of linear identities, that  $\mathcal{A} = (A, F) \in \mathcal{V}$ , and that T is a tolerance of  $\mathcal{A}$ . Then there exist an algebra  $\mathcal{B} \in \mathcal{V}$ , a congruence  $\theta$  of  $\mathcal{B}$ , and a surjective homomorphism  $\varphi \colon \mathcal{B} \to \mathcal{A}$  such that  $T = \varphi(\theta)$ .

Proof. We generalize the idea of G. Czédli and G. Grätzer [5].

If  $\mathcal{D}$  is an arbitrary algebra (not necessarily in  $\mathcal{V}$ ), then the *complex algebra*  $\mathcal{C}$  of  $\mathcal{D}$ , in other words the *algebra of complexes of*  $\mathcal{D}$ , has the underlying set  $\{X \subseteq D : X \neq \varnothing\}$ , and for each basic operation f of  $\mathcal{D}$ , the corresponding operation of  $\mathcal{C}$  is defined by

$$f(X_1, \dots, X_n) = \{ f(x_1, \dots, x_n) : x_1 \in X_1, \dots, x_n \in X_n \}.$$

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If s is a linear term, which means that each variable occurs in s at most once, then it can be shown that

$$s(X_1, \ldots, X_n) = \{s(x_1, \ldots, x_n) : x_1 \in X_1, \ldots, x_n \in X_n\}$$

holds for arbitrary  $X_i \in C$  (but this does not hold for arbitrary terms in general). This implies, as proved in [1] and [8], that if a variety is defined by linear identities, then it contains the complex algebra of each of its members.

Next, let E denote the set  $\{X \subseteq A : X^2 \subseteq T \text{ and } X \neq \varnothing\}$ . Since it is clearly a subalgebra of the complex algebra of  $\mathcal{A}$ , the paragraph above implies that  $\mathcal{E} = (E, F)$  belongs to  $\mathcal{V}$ . Let  $B = \{(x, Y) \in A \times E : x \in Y\}$ . Then  $\mathcal{B} = (B, F)$  also belongs to  $\mathcal{V}$  since it is a subalgebra of  $\mathcal{A} \times \mathcal{E}$ . Define  $\mathbf{\theta} = \{((x_1, Y_1), (x_2, Y_2)) \in B^2 : Y_1 = Y_2\}$ . As the kernel of the second projection from  $\mathcal{B}$  to  $\mathcal{E}$ , it is a congruence of  $\mathcal{B}$ . The first projection  $\varphi \colon \mathcal{B} \to \mathcal{A}$ ,  $(x, Y) \mapsto x$ , is a surjective homomorphism since, for every  $x \in A$ ,  $x = \varphi(x, \{x\})$ .

Clearly, if  $((x_1, Y_1), (x_2, Y_2)) \in \boldsymbol{\theta}$ , then  $\{x_1, x_2\} \subseteq Y_1 = Y_2 \in E$  implies that  $(\varphi(x_1, Y_1), \varphi(x_2, Y_2)) = (x_1, x_2) \in T$ . Hence  $\varphi(\boldsymbol{\theta}) \subseteq T$ . Conversely, let  $(x_1, x_2) \in T$ . Then, with  $Y = \{x_1, x_2\}$ , we have that  $(x_1, Y), (x_2, Y) \in B$ ,  $((x_1, Y), (x_2, Y)) \in \boldsymbol{\theta}$ , and  $x_i = \varphi(x_i, Y)$ . This implies that  $(x_1, x_2) \in \varphi(\boldsymbol{\theta})$ , and we conclude that  $T \subseteq \varphi(\boldsymbol{\theta})$ .

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